



KNOWLEDGE GRAPHS

Lecture 6: SPARQL Semantics

Markus Krötzsch Knowledge-Based Systems

TU Dresden, 5 Dec 2024

More recent versions of this slide deck might be available.

For the most current version of this course, see

https://iccl.inf.tu-dresden.de/web/Knowledge_Graphs/6

Review

SPARQL is a feature-rich query language:

- Basic graph patterns (conjunctions of triple patterns)
- Property path patterns
- Filters
- Union, Optional, Minus
- Subqueries, Values, Bind
- Solution set modifiers
- Aggregates

Review: Answers to BGPs

What is the result of a SPARQL query?

Definition 6.1: A solution mapping is a partial function μ from variable names to RDF terms. A solution sequence is a list of solution mappings.

Note: When no specific order is required, the solutions computed for a SPARQL query can be represented by a multiset (= "a set with repeated elements" = "an unordered list").

Definition 6.2: Given an RDF graph G and a BGP P, a solution mapping μ is a solution to P over G if it is defined exactly on the variable names in P and there is a mapping σ from blank nodes in P to RDF terms such that $\mu(\sigma(P)) \subseteq G$.

The cardinality of μ in the multiset of solutions is the number of distinct such mappings σ . The multiset of these solutions is denoted $BGP_G(P)$, where we omit G if clear from the context.

Note: Here, we write $\mu(\sigma(P))$ to denote the graph given by the triples in P after first replacing bnodes according to σ , and then replacing variables according to μ .

 $\mathsf{BGP}\,P_1=\mathsf{?film}\,\mathsf{eg}:\mathsf{actorRole}\,\mathsf{?ar}$. ?ar $\mathsf{eg}:\mathsf{actor}\,\mathsf{?person}$. has solution multiset:

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

For example, for μ : film \mapsto eg:Arrival, ar \mapsto eg:aux1, person \mapsto eg:Adams, there is exactly one mapping $\sigma:\emptyset\to \mathsf{RDF}$ Terms (defined on the bnodes in P_1) such that $\mu(\sigma(P_1))\subseteq G$.

 $P_1 = ?$ film eg:actorRole ?ar . ?ar eg:actor ?person .

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

 $P_1 = ?$ film eg:actorRole ?ar . ?ar eg:actor ?person .

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

```
P_2 = ?film eg:actorRole [ eg:actor ?person ]
```

$P_1 = ?$ film eg:actorRole ?ar . ?ar eg:actor ?person .

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

P_2 = ?film eg:actorRole [eg:actor ?person]

| film | person | cardinality |
|------------|------------|-------------|
| eg:Arrival | eg:Adams | 1 |
| eg:Arrival | eg:Renner | 1 |
| eg:Gravity | eg:Bullock | 1 |

 $P_1 = ?$ film eg:actorRole ?ar . ?ar eg:actor ?person .

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

 $P_2 = ?$ film eg:actorRole [eg:actor ?person]

| film | person | cardinality |
|------------|------------|-------------|
| eg:Arrival | eg:Adams | 1 |
| eg:Arrival | eg:Renner | 1 |
| eg:Gravity | eg:Bullock | 1 |

```
P_3 = ?film eg:actorRole [ eg:actor [] ]
```

 $P_1 = ?$ film eg:actorRole ?ar . ?ar eg:actor ?person .

| film | ar | person | cardinality |
|------------|---------|------------|-------------|
| eg:Arrival | eg:aux1 | eg:Adams | 1 |
| eg:Arrival | eg:aux2 | eg:Renner | 1 |
| eg:Gravity | _:1 | eg:Bullock | 1 |

 $P_2 = ?$ film eg:actorRole [eg:actor ?person]

| film | person | cardinality |
|------------|------------|-------------|
| eg:Arrival | eg:Adams | 1 |
| eg:Arrival | eg:Renner | 1 |
| eg:Gravity | eg:Bullock | 1 |

 $P_3 = ?film eg:actorRole [eg:actor []]$

| film | cardinality | |
|------------|-------------|--|
| eg:Arrival | 2 | |
| eg:Gravity | 1 | |

Review: Projection and Duplicates

Projection can increase the multiplicity of solutions

Definition 6.3: The projection of a solutions mapping μ to a set of variables V is the restriction of the partial function μ to variables in V. The projection of a solution sequence is the set of all projections of its solution mappings, ordered by the first occurrence of each projected solution mapping.

The cardinality of a solution mapping μ in a solution Ω is the sum of the cardinalities of all mappings $\nu \in \Omega$ that project to the same mapping μ .

 \leadsto using blank nodes in patterns has the same effect as using variables that are projected away

(but bnode values cannot be used to compute aggregates or computed functions)

To answer BGPs, real graph database retrieve solutions for triple patterns and combine them with joins.

To answer BGPs, real graph database retrieve solutions for triple patterns and combine them with joins.

Definition 6.4: Two solution mappings μ_1 and μ_2 are compatible if $\mu_1(x) = \mu_2(x)$ for all variable names $x \in \text{dom}(\mu_1) \cap \text{dom}(\mu_2)$, where dom is the domain on which a (partial) function is defined. In this case, $\mu_1 \uplus \mu_2$ is the mapping defined as

$$\mu_1 \uplus \mu_2(x) = \begin{cases} \mu_1(x) & \text{if } x \in \text{dom}(\mu_1) \\ \mu_2(x) & \text{if } x \in \text{dom}(\mu_2) \\ \text{undefined} & \text{otherwise} \end{cases}$$

To answer BGPs, real graph database retrieve solutions for triple patterns and combine them with joins.

Definition 6.4: Two solution mappings μ_1 and μ_2 are compatible if $\mu_1(x) = \mu_2(x)$ for all variable names $x \in \text{dom}(\mu_1) \cap \text{dom}(\mu_2)$, where dom is the domain on which a (partial) function is defined. In this case, $\mu_1 \uplus \mu_2$ is the mapping defined as

$$\mu_1 \uplus \mu_2(x) = \left\{ \begin{array}{ll} \mu_1(x) & \text{if } x \in \text{dom}(\mu_1) \\ \\ \mu_2(x) & \text{if } x \in \text{dom}(\mu_2) \\ \\ \text{undefined} & \text{otherwise} \end{array} \right.$$

Definition 6.5: The join of two multisets Ω_1 and Ω_2 of solution mappings is the multiset $Join(\Omega_1, \Omega_2) = \{\mu_1 \uplus \mu_2 \mid \mu_1 \in \Omega_1, \mu_2 \in \Omega_2, \text{ and } \mu_1 \text{ and } \mu_2 \text{ are compatible}\}.$

The multiplicity $\operatorname{card}_{\Omega}(\mu)$ of each solution $\mu \in \Omega = \operatorname{Join}(\Omega_1, \Omega_2)$ is given as $\operatorname{card}_{\Omega}(\mu) = \sum_{\mu_1 \in \Omega_1, \mu_2 \in \Omega_2, \mu_1 \uplus \mu_2 = \mu} \operatorname{card}_{\Omega_1}(\mu_1) \times \operatorname{card}_{\Omega_2}(\mu_2)$.

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$\mathsf{BGP}_G(P) = \mathsf{Join}(\mathsf{BGP}_G(P_1), \mathsf{BGP}_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$BGP_G(P) = Join(BGP_G(P_1), BGP_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Proof: Since P contains no bnodes, solutions are defined without considering mappings " σ " and the multiplicity of any solution will therefore be 1.

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$\mathsf{BGP}_G(P) = \mathsf{Join}(\mathsf{BGP}_G(P_1), \mathsf{BGP}_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Proof: Since P contains no bnodes, solutions are defined without considering mappings " σ " and the multiplicity of any solution will therefore be 1.

"⊆" Consider $\mu \in BGP_G(P)$.

- Let μ_i be the restriction of μ to variables in P_i (i = 1, 2)
- Then $\mu_i \in \mathsf{BGP}_G(P_i)$ and μ_1 and μ_2 are compatible
- Therefore $\mu_1 \uplus \mu_2 = \mu \in \mathsf{Join}(\mathsf{BGP}_G(P_1), \mathsf{BGP}_G(P_2))$

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$BGP_G(P) = Join(BGP_G(P_1), BGP_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Proof: Since P contains no bnodes, solutions are defined without considering mappings " σ " and the multiplicity of any solution will therefore be 1.

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$\mathsf{BGP}_G(P) = \mathsf{Join}(\mathsf{BGP}_G(P_1), \mathsf{BGP}_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Proof: Since P contains no bnodes, solutions are defined without considering mappings " σ " and the multiplicity of any solution will therefore be 1.

" \supseteq " Consider $\mu \in Join(BGP_G(P_1), BGP_G(P_2))$.

- Then there are compatible $\mu_i \in \mathsf{BGP}_G(P_i)$ with $\mu_1 \uplus \mu_2 = \mu$
- By construction, $\mu_1(P_1) = \mu(P_1) \subseteq G$ and $\mu_2(P_2) = \mu(P_2) \subseteq G$
- Hence $\mu_1(P_1) \cup \mu_2(P_2) = \mu(P_1) \cup \mu(P_2) = \mu(P_1 \cup P_2) \subseteq G$, as claimed

Theorem 6.6: Let G be an RDF graph, and let $P = P_1 \cup P_2$ be a bnode-free BGP that is a disjoint union of two BGPs P_1 and P_2 . Then

$$BGP_G(P) = Join(BGP_G(P_1), BGP_G(P_2)).$$

So $BGP_G(P)$ is the join of the solution multisets of all individual triple patterns in P.

Proof: Since P contains no bnodes, solutions are defined without considering mappings " σ " and the multiplicity of any solution will therefore be 1.

"⊇" Consider $\mu \in Join(BGP_G(P_1), BGP_G(P_2))$.

- Then there are compatible $\mu_i \in \mathsf{BGP}_G(P_i)$ with $\mu_1 \uplus \mu_2 = \mu$
- By construction, $\mu_1(P_1) = \mu(P_1) \subseteq G$ and $\mu_2(P_2) = \mu(P_2) \subseteq G$
- Hence $\mu_1(P_1) \cup \mu_2(P_2) = \mu(P_1) \cup \mu(P_2) = \mu(P_1 \cup P_2) \subseteq G$, as claimed

Finding BGP solutions ... in practice

Theorem 6.6 does not work if the patterns contains blank nodes! (see exercise)

In practice, we can treat bnodes like variables that are projected away later on (leading to increased multiplicities).

Finding BGP solutions ... in practice

Theorem 6.6 does not work if the patterns contains blank nodes! (see exercise)

In practice, we can treat bnodes like variables that are projected away later on (leading to increased multiplicities).

Real graph databases compute joins in highly optimised ways:

- Efficient data structures for finding compatible solutions to triple patterns (e.g., hash maps, tries, ordered lists, ...)
- Query planners for optimising order of joins (goal: small intermediate results)
- Streaming joins: returning first results before join is complete
- Sometimes: multi-way joins (joining more than two triple patterns at once)

... but they still compute BGP solutions by joining partial solutions and hoping for an overall match

In the worst case, any known algorithm needs exponential time.

Semantics of SPARQL queries

SPARQL query features are defined by corresponding query algebra operations that produce results (i.e., multisets of solution mappings).

We already encountered some such operations:

- BGP_G produced results for BGPs and property path patterns
- Join computed the natural join of two results

Semantics of SPARQL queries

SPARQL query features are defined by corresponding query algebra operations that produce results (i.e., multisets of solution mappings).

We already encountered some such operations:

- BGP_G produced results for BGPs and property path patterns
- Join computed the natural join of two results

We omitted the according operation for **FILTER** so far. It is simple; we just need to take into account that the meaning of some filter expressions (e.g., **NOT EXISTS**) depends on the given RDF graph:

Definition 6.7: Given a filter expression φ , a multiset M of solution mappings, and an RDF graph G, we define the multiset

Filter
$$_G(\varphi, M) = \{ \mu \mid \mu \in M \text{ and } \varphi \text{ evaluates to true for } \mu \text{ (over } G) \}$$

with the cardinality of a solution mapping μ defined as $\operatorname{card}_{\mathsf{Filter}_G(\varphi,M)}(\mu) = \operatorname{card}_M(\mu)$.

Semantics of **UNION**

The semantics of **UNION** is defined by the operation $Union(M_1, M_2)$, which computes the union of two multisets M_1 and M_2 of solution mappings:

Definition 6.8: Given multisets M_1 and M_2 of solution mappings, we define the multiset

Union
$$(M_1, M_2) = \{ \mu \mid \mu \in M_1 \text{ or } \mu \in M_2 \}$$

with the cardinality of a solution mapping μ defined as

$$\operatorname{card}_{\operatorname{Union}(M_1,M_2)}(\mu) = \operatorname{card}_{M_1}(\mu) + \operatorname{card}_{M_2}(\mu).$$

Semantics of MINUS

The semantics of **MINUS** is defined by the operation $Minus(M_1, M_2)$, which computes the set difference of two results M_1 and M_2 :

Definition 6.9: Given multisets M_1 and M_2 of solution mappings, we define the multiset

Minus
$$(M_1,M_2)=\{\mu\mid \mu\in M_1 \text{ and for all }\mu'\in M_2:\mu \text{ and }\mu' \text{ are not compatible}$$
 or have disjoint domains: $\operatorname{dom}(\mu)\cap\operatorname{dom}(\mu')=\emptyset\}$

with the cardinality of a mapping μ defined as $card_{Minus(M_1,M_2)}(\mu) = card_{M_1}(\mu)$.

Recall: mappings μ_1 and μ_2 are compatible if $\mu_1(x) = \mu_2(x)$ for all variable names $x \in \text{dom}(\mu_1) \cap \text{dom}(\mu_2)$

Note: Minus(M_1, M_2) does not depend on cardinalities of mappings in M_2 .

Semantics of OPTIONAL

The semantics of **OPTIONAL** is defined by the operation LeftJoin $_G(M_1, M_2, \varphi)$, which augments solutions in M_1 with compatible solutions in M_2 if this combination satisfies the filter condition φ (w.r.t. graph G):

Definition 6.10: Given multisets M_1 and M_2 of solution mappings, a filter expression φ , and an RDF graph G, we define the multiset

$$\mathsf{LeftJoin}_G(M_1,M_2,\varphi) = \mathsf{Filter}_G(\varphi,\mathsf{Join}(M_1,M_2)) \cup \\ \{\mu_1 \in M_1 \mid \text{ for all } \mu_2 \in M_2 : \mu_1 \text{ incompatible } \mu_2 \text{ or } \\ \varphi \text{ evaluates to false on } \mu_1 \uplus \mu_2 \text{ (over G)} \}$$

with the cardinality of each mapping μ being its cardinality in $\operatorname{Filter}_G(\varphi,\operatorname{Join}(M_1,M_2))$ (in case $\mu\in\operatorname{Filter}_G(\varphi,\operatorname{Join}(M_1,M_2))$) or in M_1 (in case $\mu\notin\operatorname{Filter}_G(\varphi,\operatorname{Join}(M_1,M_2))$). Note that only one of the two cases can occur.

Recall: mappings μ_1 and μ_2 are compatible if $\mu_1(x) = \mu_2(x)$ for all variable names

 $x \in dom(\mu_1) \cap dom(\mu_2)$ Markus Krötzsch, 5 Dec 2024

Optional and filters (1)

We defined LeftJoin to include filter conditions. Note the difference:

```
Example 6.11:
SELECT ?person ?spouse
WHERE {
 ?person eg:birthdate ?bd .
 OPTIONAL {
   ?person eg:spouse ?spouse .
   ?spouse eg:birthdate ?bd2 .
   FILTER (year(?bd)=year(?bd2))
```

```
Example 6.12:
SELECT ?person ?spouse
WHERE {
 { ?person eg:birthdate ?bd .
  OPTIONAL {
    ?person eg:spouse ?spouse .
    ?spouse eg:birthdate ?bd2 .
 FILTER (year(?bd)=year(?bd2))
```

Optional and filters (1)

We defined LeftJoin to include filter conditions. Note the difference:

```
Example 6.11:
SELECT ?person ?spouse
WHERE {
 ?person eg:birthdate ?bd .
 OPTIONAL {
   ?person eg:spouse ?spouse .
   ?spouse eg:birthdate ?bd2 .
   FILTER (year(?bd)=year(?bd2))
```

```
Example 6.12:
SELECT ?person ?spouse
WHERE {
 { ?person eg:birthdate ?bd .
  OPTIONAL {
    ?person eg:spouse ?spouse .
    ?spouse eg:birthdate ?bd2.
 FILTER (year(?bd)=year(?bd2))
```

"People with birthdate, and, optionally, their spouses born in the same year."

"Pairs of people with birthdate and spouses that were born in the same year."

Optional and filters (2)

We defined LeftJoin to include filter conditions. Note the difference:

```
Example 6.13:

SELECT ?X ?Y

WHERE {

    VALUES (?X) { (1) (2) } .

    OPTIONAL {

        VALUES (?Y) ("OK") .

        FILTER (?X >= 2)

    }
}
```

```
Example 6.14:

SELECT ?X ?Y

WHERE {

    VALUES (?X) { (1) (2) } .

    OPTIONAL {

        VALUES (?Y) ("OK") .

    }

    FILTER (?X >= 2)
}
```

Optional and filters (2)

We defined LeftJoin to include filter conditions. Note the difference:

```
Example 6.13:
SELECT ?X ?Y
WHERE {
 VALUES (?X) { (1) (2) } .
 OPTIONAL {
   VALUES (?Y) ("OK") .
   FILTER (?X >= 2)
```

```
Example 6.14:

SELECT ?X ?Y

WHERE {

    VALUES (?X) { (1) (2) } .

    OPTIONAL {

        VALUES (?Y) ("OK") .

    }

    FILTER (?X >= 2)
}
```

```
Results: \{?X \mapsto 1\}, \{?X \mapsto 2, ?Y \mapsto "0K"\}
```

Results: $\{?X \mapsto 2, ?Y \mapsto "OK"\}$

Some SPARQL engines do not implement this correctly.

Adding VALUES (?X) (UNDEF) to the optional part should fix their behaviour (exercise: why is this equivalent?).

Semantics of subqueries

The semantics of subqueries does not require any special operator: the result multiset of the subquery is simply used like the result of any other (sub) group graph pattern.

Notes:

- The order of results from subqueries is not conveyed to the enclosing query (subqueries return multisets, not sequences).
- The use of **ORDER BY** is still meaningful to select top-*k* results by some ordering.
- Only selected variable names are part of the subquery result; other variables might be hidden from the enclosing query

Semantics of **VALUES** (review)

VALUES behaves just like a subquery with the specified result.

- As with subqueries, order does not matter.
- The special value UNDEF is used to signify that a variable should be unbound for a solution mapping
- Otherwise, only IRIs or literals can be used in **VALUES** especially no functions

Semantics of **BIND**

The semantics of **BIND** is defined by the operation $\operatorname{Extend}(M, v, \varphi)$, which computes the extension of solution mappings in M by assigning the output of expression φ to variable name v.

Definition 6.15: Consider a variable name v and an expression φ . Given a solution mapping μ such that $v \notin \text{dom}(\mu)$, we define an extended mapping

$$\mathsf{Extend}(\mu, \nu, \varphi) = \left\{ \begin{array}{ll} \mu \cup \{\nu \mapsto \mathsf{eval}(\mu(\varphi))\} & \mathsf{if} \ \mathsf{eval}(\mu(\varphi)) \ \mathsf{is} \ \mathsf{not} \ \text{``error''} \\ \mu & \mathsf{if} \ \mathsf{eval}(\mu(\varphi)) \ \mathsf{is} \ \text{``error''} \end{array} \right.$$

Given a multiset M of solution mappings, we define $\operatorname{Extend}(M, v, \varphi) = \{\operatorname{Extend}(\mu, v, \varphi) \mid \mu \in M\}$, where the cardinalities of extended mappings are the same as in M.

Notation: eval($\mu(\varphi)$) denotes the evaluation of the expression obtained from φ by replacing variables by their values in μ .

Summary: SPARQL algebra

We have already encountered a number of operators for extending results:

- Join(M_1, M_2): join compatible mappings from M_1 and M_2
- Filter $_G(\varphi, M)$: remove from multiset M all mappings for which φ does not evaluate to EBV "true"
- Union (M_1, M_2) : compute the union of mappings from multisets M_1 and M_2
- Minus(M₁, M₂): remove from multiset M₁ all mappings compatible with a non-empty mapping in M₂
- LeftJoin $_G(M_1, M_2, \varphi)$: extend mappings from M_1 by compatible mappings from M_2 when filter condition is satisfied; keep remaining mappings from M_1 unchanged
- Extend (M, v, φ) : extend all mappings from M by assigning v the value of φ .

SPARQL also defines operators for solution set modifiers, which work on lists of mappings ("ordered multisets"):

- OrderBy(*L*, condition): sort list by a condition
- Slice(*L*, start, length): apply limit and offset modifiers

Further operators exist, e.g., Distinct(L).

From query to algebra expression by example

It is often not hard to give a correct algebra expression for a group graph pattern:

```
Example 6.16: The pattern
{ ?person eg:birthdate ?bd .
   OPTIONAL {
     { ?person eg:spouse ?s } UNION { ?person eg:civilPartner ?s }
     { ?s eg:birthdate ?bd2 . }
     FILTER (year(?bd)=year(?bd2))
can be solved, e.g., by an algebra expression:
LeftJoin(BGP(?person eg:birthdate ?bd),
        Join(Union(BGP(?person eg:spouse ?s), BGP(?person eg:civilPartner ?s)),
             BGP(?s eg:birthdate ?bd2)),
        year(?bd)=year(?bd2)
```

A partial algorithm

Transformation for queries with only BGPs, filters, unions, and optional:

- (1) Replace all basic graph patterns P with BGP(P)
- (2) Replace all patterns of the form P UNION Q by Union(P, Q)
- (3) Now select an innermost sequence *S* of expressions (all sub-patterns processed already)
 - Remove all FILTER expressions, and store them combined into a conjunction ψ
 - Initialise a result R to be the empty SPARQL expression Z
 - Process the remaining list of subexpressions SE iteratively
 - If SE is of the form OPTIONAL Filter(φ,A) then set $R:= \mathsf{LeftJoin}(R,A,\varphi)$
 - Else, if SE is of the form OPTIONAL A then set
 R := LeftJoin(R, A, true)
 - Else set R := Join(R, SE)
 - Finally, replace S by the expression Filter(ψ , R)

Missing parts

Specifying the translation of SPARQL queries to SPARQL algebra in a fully formal way requires some further details:

- All operators must be taken into account
- Rules are needed to clarify the scope of operators when omitting some { and }

→ we are not interested in all the details in this course

Summary

SPARQL query results are multi-sets of answers (and lists if order was defined)

The semantics of SPARQL is defined using a variety of algebraic operators

SPARQL queries can be converted into nested expressions of operators that compute the result.

What's next?

- SPARQL complexity
- Expressive limits of SPARQL
- Other graph models and their query languages