

CHASE TERMINATION BEYOND POLYNOMIAL TIME

43rd Symposium on Principles of Database Systems (PODS'24)

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Introduction

Tuple-generating dependencies (tgds): rules with existential quantifiers

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Chase: 'apply rules until nothing new follows'
→ but might run forever

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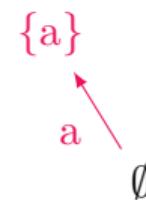
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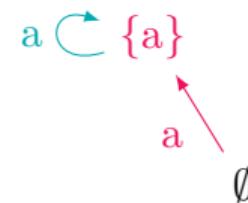
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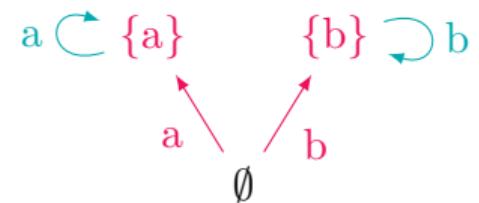
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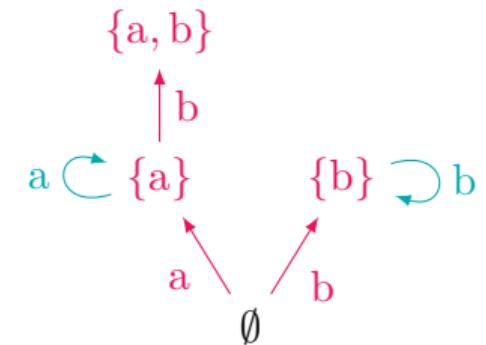
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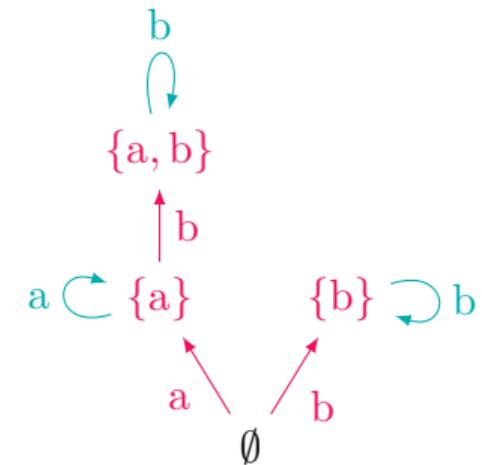
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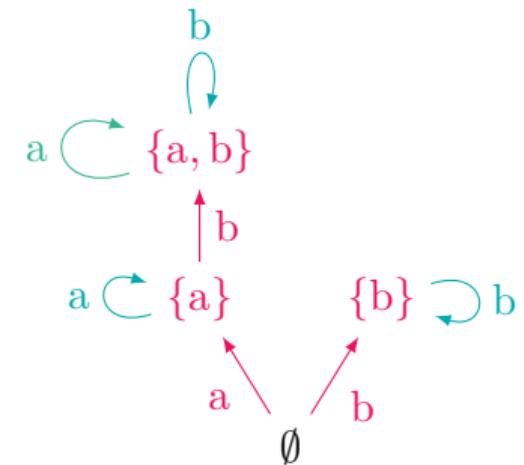
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Analysing termination

Chase: relational structure of nulls,
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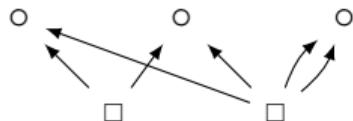
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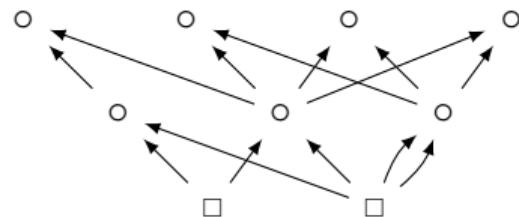
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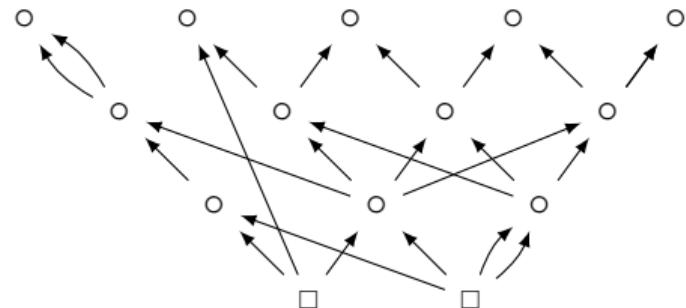
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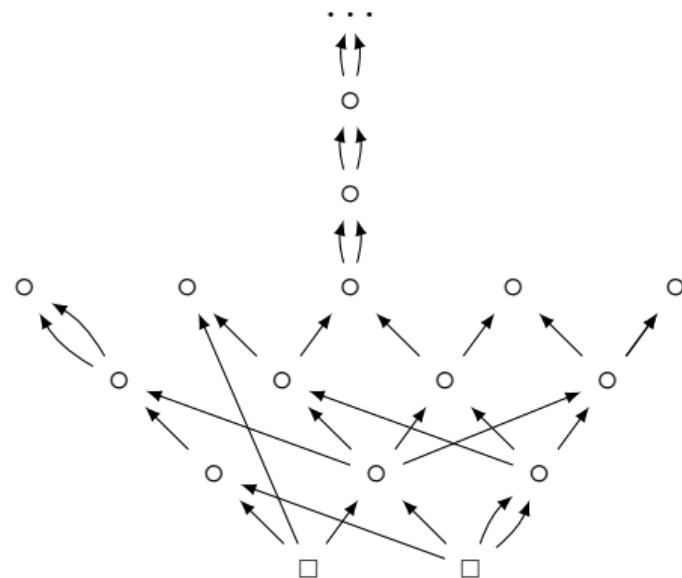
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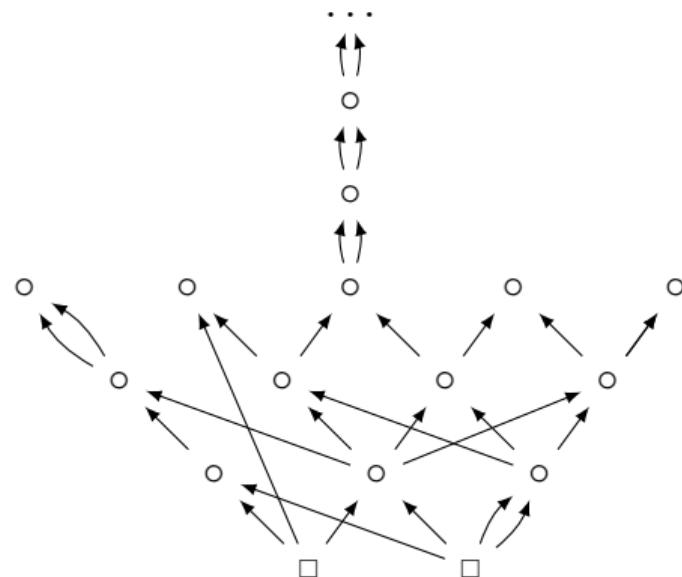
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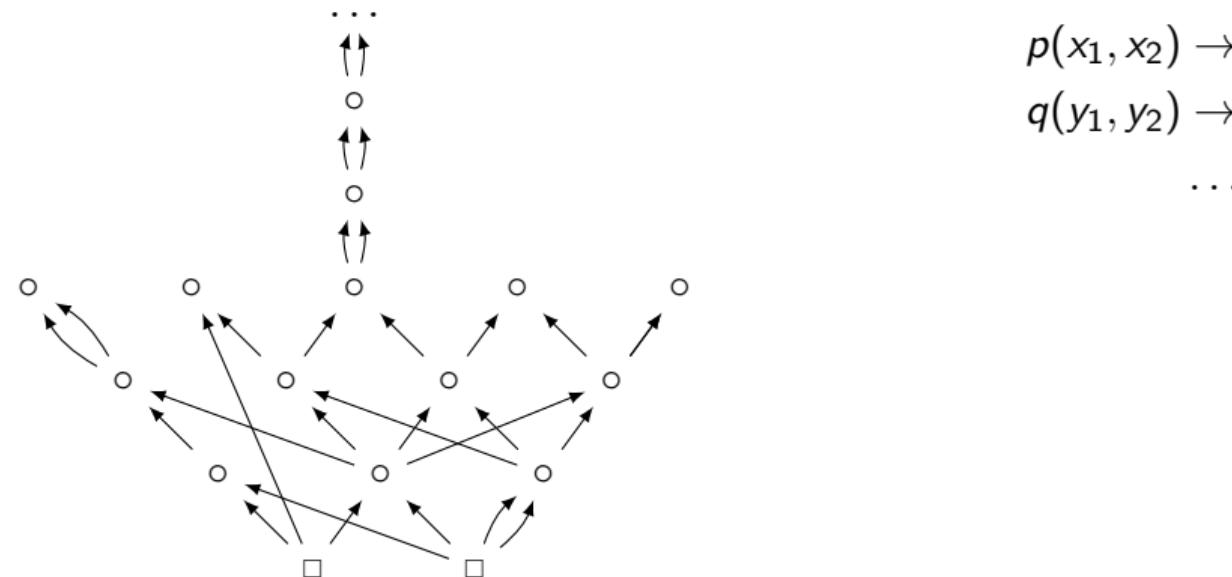
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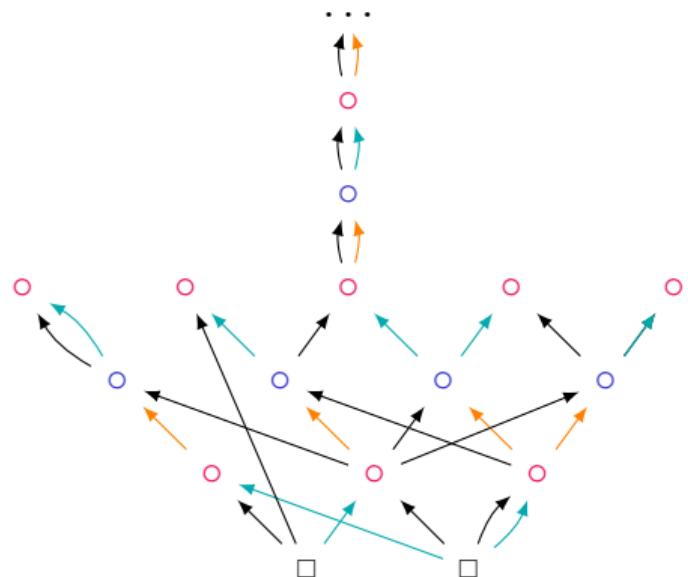
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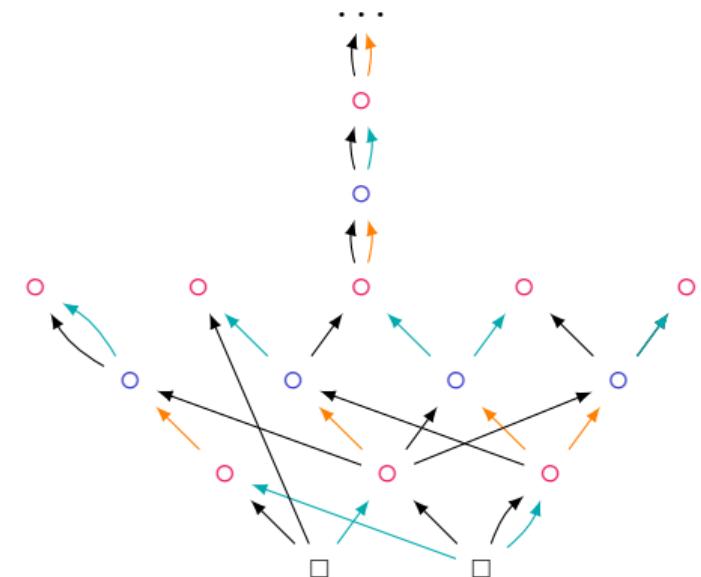
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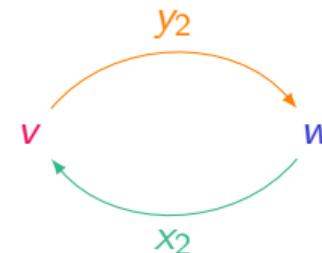
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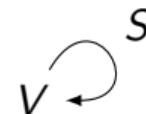
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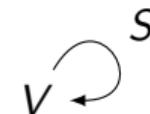
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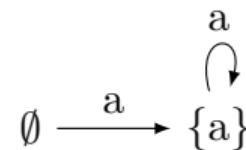
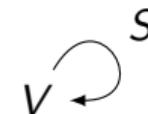
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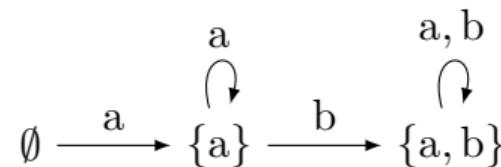
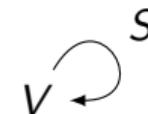
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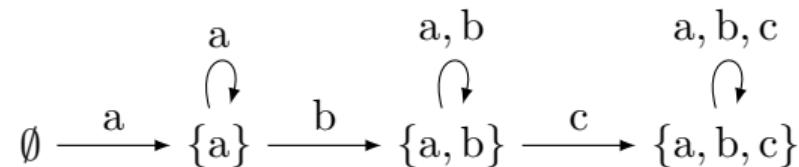
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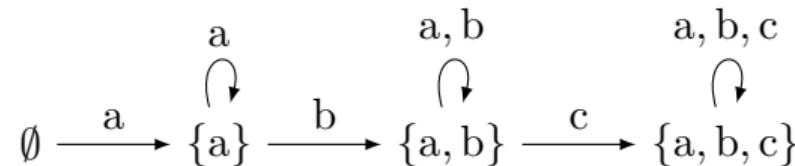
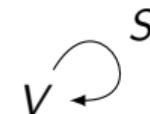
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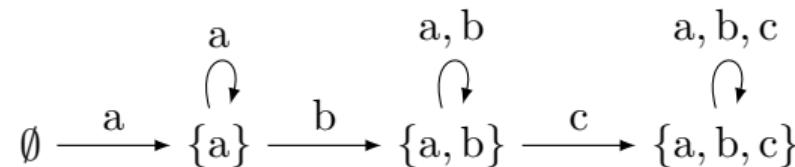
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Tgd (2) 'blocks' application along a path for latest element

Tgd (3) 'blocks' application along a path for previously added elements

Generalising this idea

$$\text{elem}(e) \wedge \text{set}(S) \rightarrow \exists V. \text{add}(e, S, V)$$

We identify three kinds of variables for the tgds we ‘block’:

- the existential variable that creates a new null
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→ **Datalog-entailment checks**, based on tgds and dependency graph

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Not all tgds need to be blocked:

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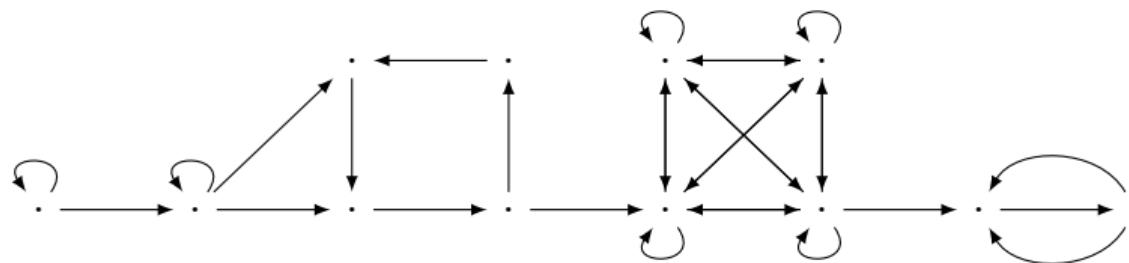
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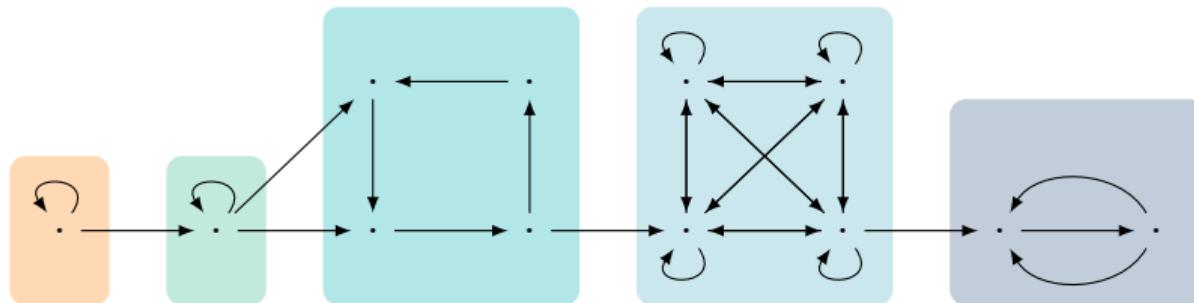


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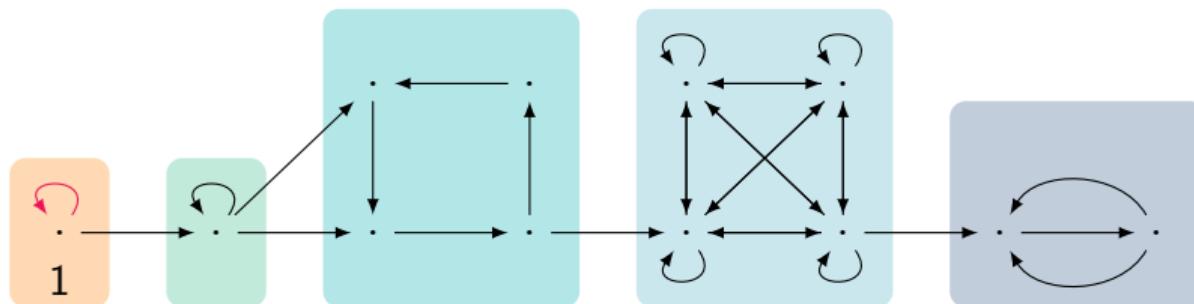


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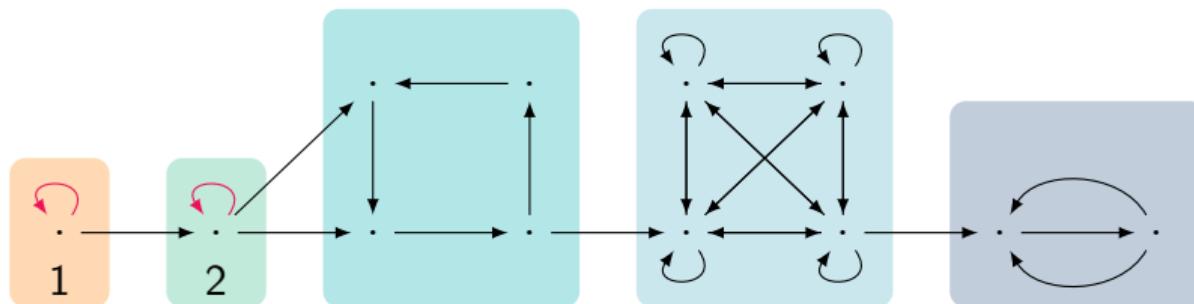


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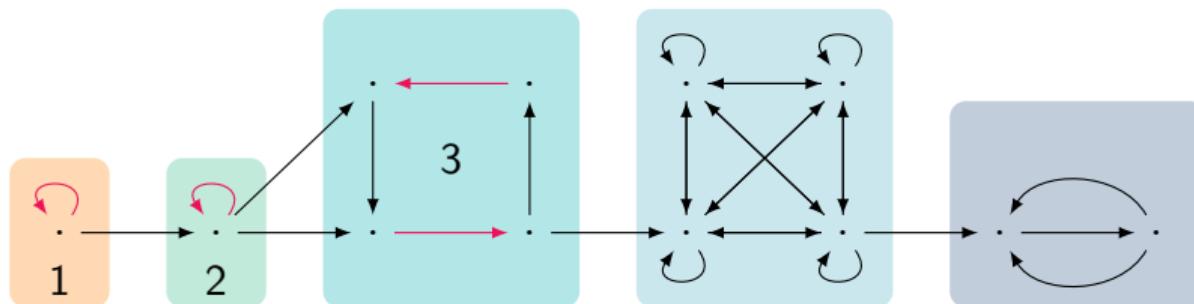


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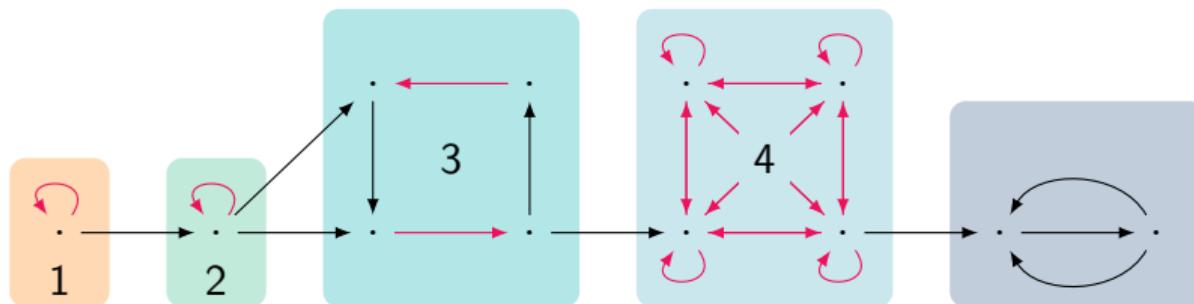


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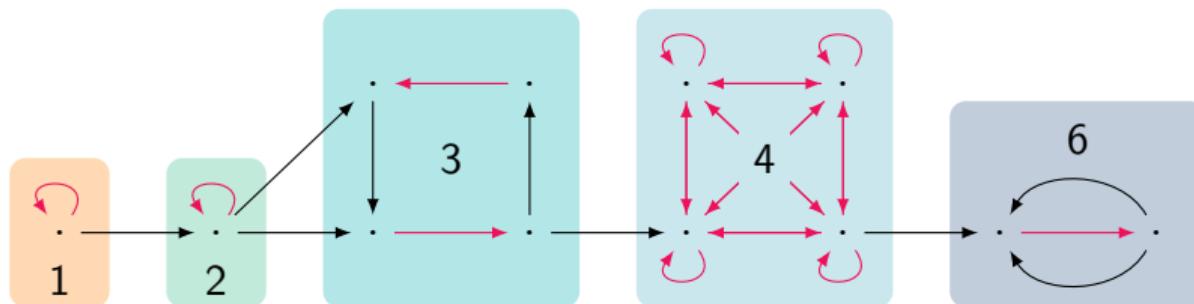


Breaking the cycles

Not all tgds need to be blocked:

- select 'blocking' tgds to break cycles
- identify predecessor and context variables
- verify saturation criteria

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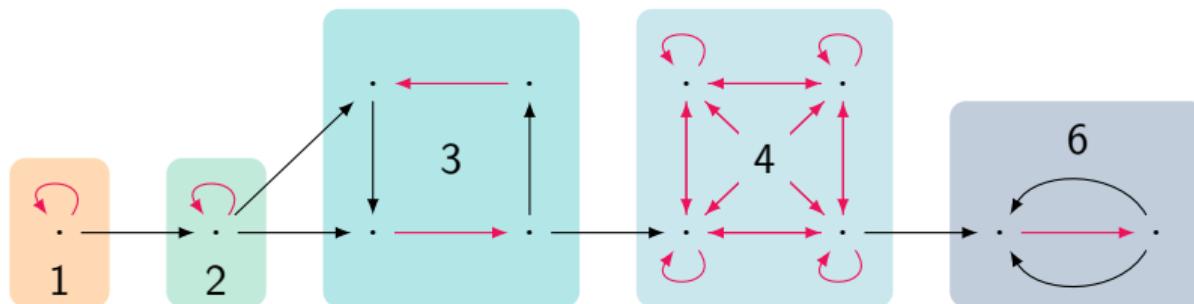


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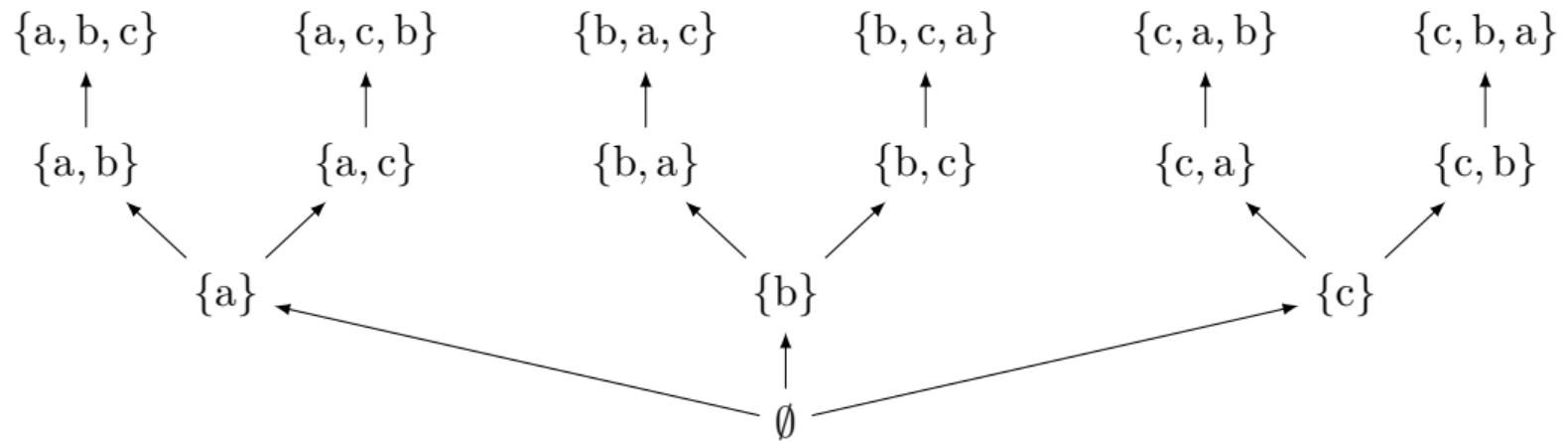
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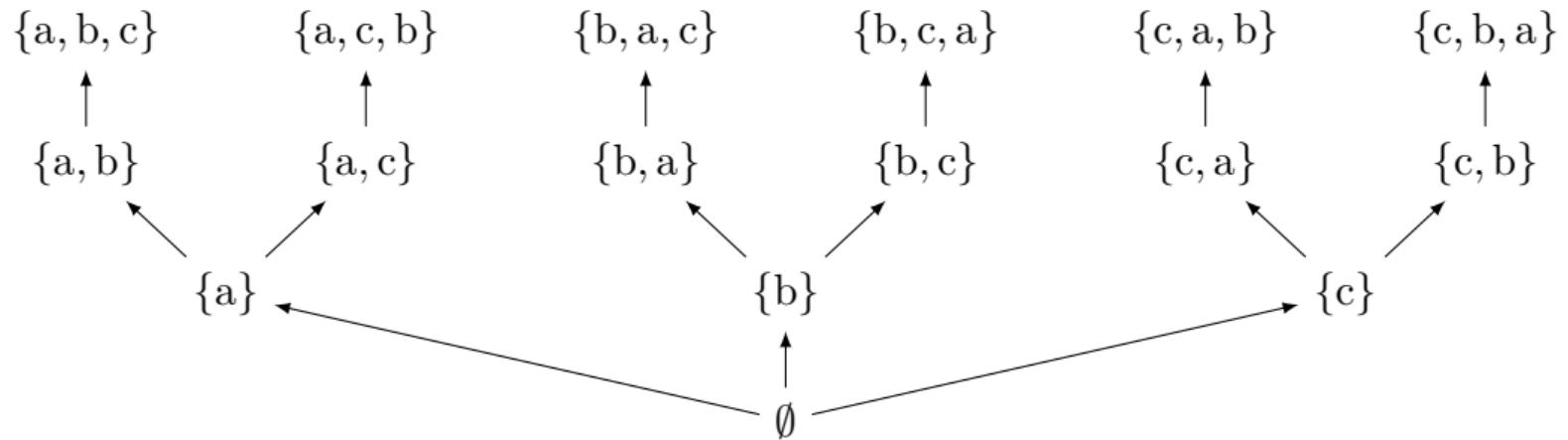


The saturation criteria define decidable classes of tgds with k -EXPTIME-complete data complexity for every k .

Teaser

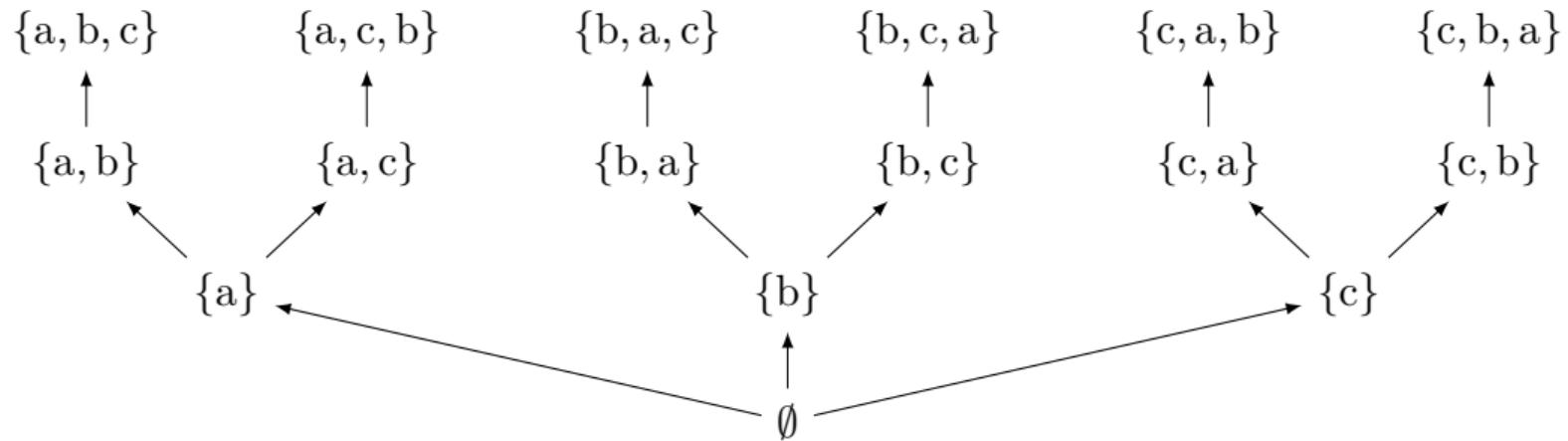


Teaser



There are exponentially many nulls, but they form a tree:
→ query answering might be possible in PSPACE.

Teaser

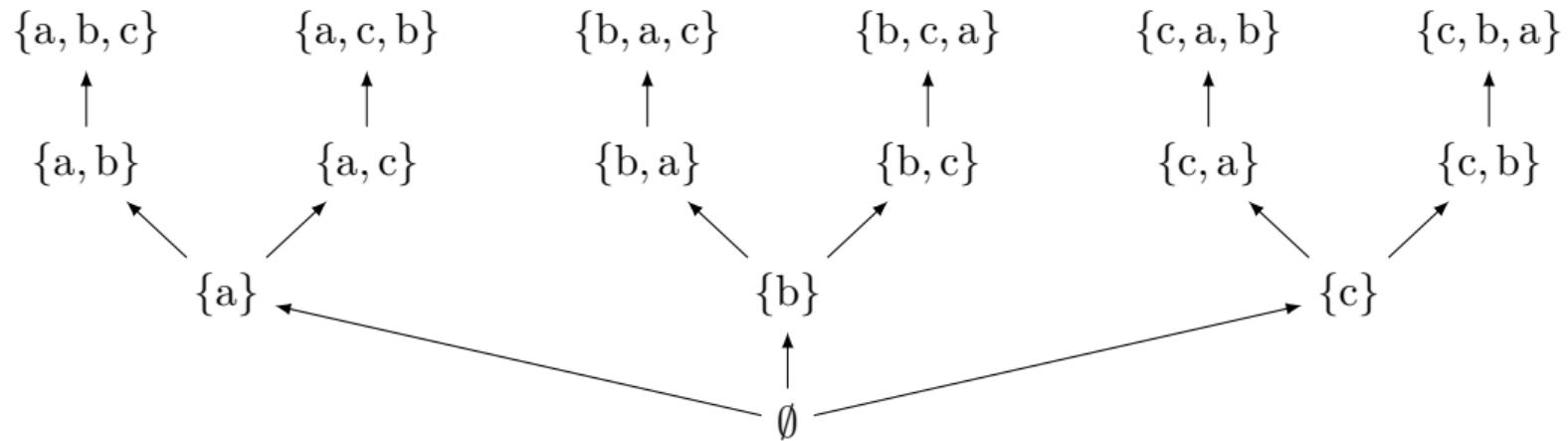


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We define a **syntactic condition** and a **chase** that realises this complexity.

Teaser



There are exponentially many nulls, but they form a tree:

→ query answering might be possible in PSPACE.

We define a **syntactic condition** and a **chase** that realises this complexity
and obtain decidable classes of tgds with PSPACE- and k -EXPSPACE-complete data complexity for all k .

Summary

Main results:

- decidable classes of tgds with PSPACE, k -EXPSPACE, k -EXPTIME data complexity for all k
- new methods for analysing the structure of the standard chase
- new chase procedures that are optimal for space-bound complexity classes

Open questions:

- refinement of criteria for further complexity classes
- capturing of queries in the covered complexity classes