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Existential Rules – Lecture 3

Adapted from slides by Andreas Pieris and Michaël Thomazo
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Syntax of Existential Rules

An **existential rule** is an expression

$$\forall \mathbf{X} \forall \mathbf{Y} (\underbrace{\varphi(\mathbf{X}, \mathbf{Y})}_{\text{body}} \rightarrow \exists \mathbf{Z} \underbrace{\psi(\mathbf{X}, \mathbf{Z})}_{\text{head}})$$

- \mathbf{X}, \mathbf{Y} and \mathbf{Z} are tuples of variables of \mathbf{V}
- $\varphi(\mathbf{X}, \mathbf{Y})$ and $\psi(\mathbf{X}, \mathbf{Z})$ are (constant-free) conjunctions of atoms

...a.k.a. tuple-generating dependencies, and Datalog[±] rules



Semantics of Existential Rules

- An instance J is a **model** of the rule

$$\sigma = \forall \mathbf{X} \forall \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}) \rightarrow \exists \mathbf{Z} \psi(\mathbf{X}, \mathbf{Z}))$$

written as $J \models \sigma$, if the following holds:

whenever there exists a homomorphism h such that $h(\varphi(\mathbf{X}, \mathbf{Y})) \subseteq J$,

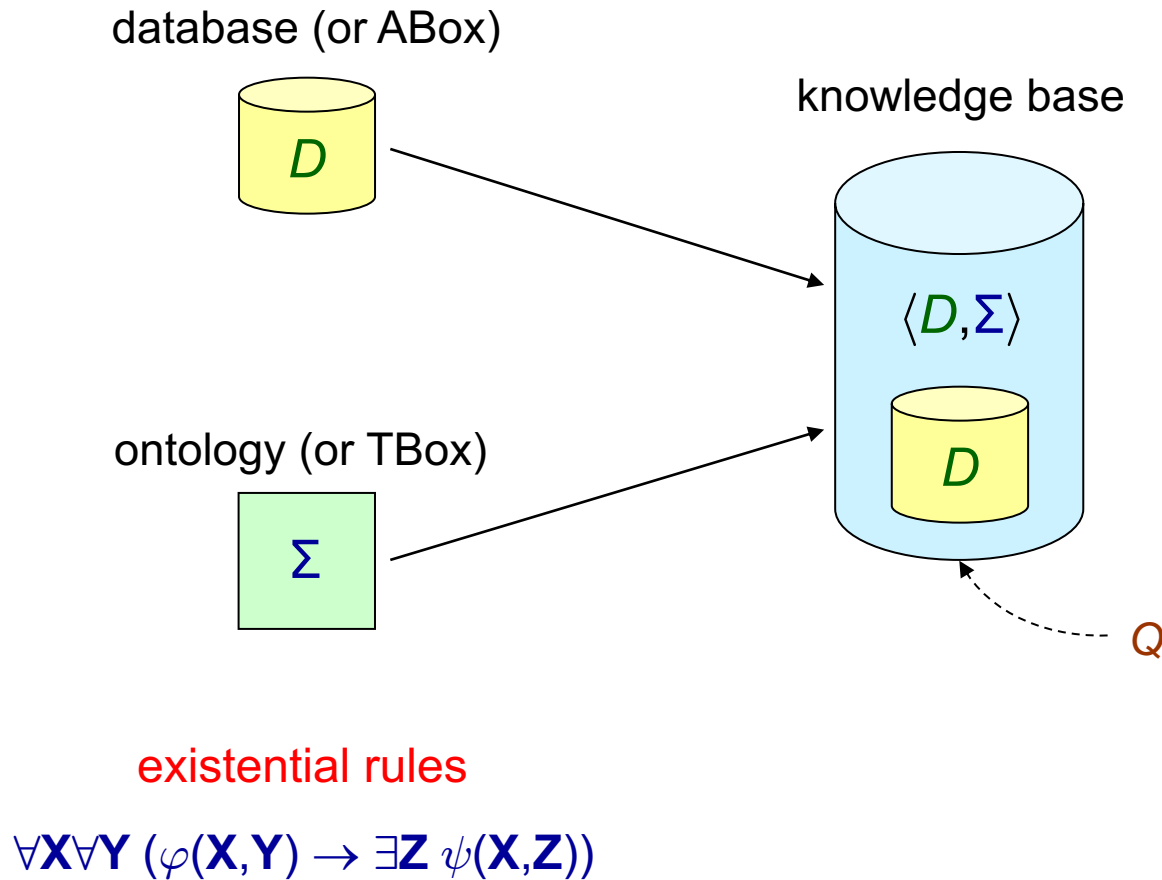
then there exists $g \supseteq h|_{\mathbf{X}}$ such that $g(\psi(\mathbf{X}, \mathbf{Z})) \subseteq J$

$\{t \mapsto h(t) \mid t \in \mathbf{X}\}$ – the **restriction** of h to \mathbf{X}

- Given a set Σ of existential rules, J is a **model** of Σ , written as $J \models \Sigma$, if the following holds: for each $\sigma \in \Sigma$, $J \models \sigma$
- It can be shown that $J \models \Sigma$ iff J is a model of the first-order theory $\bigwedge_{\sigma \in \Sigma} \sigma$



Ontology-Based Query Answering (OBQA)



Syntax of Conjunctive Queries

A **conjunctive query (CQ)** is an expression

$$\exists \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}))$$

- \mathbf{X} and \mathbf{Y} are tuples of variables of \mathbf{V}
- $\varphi(\mathbf{X}, \mathbf{Y})$ is a conjunction of atoms (possibly with constants)

The most important query language used in practice

Forms the **SELECT-FROM-WHERE** fragment of SQL

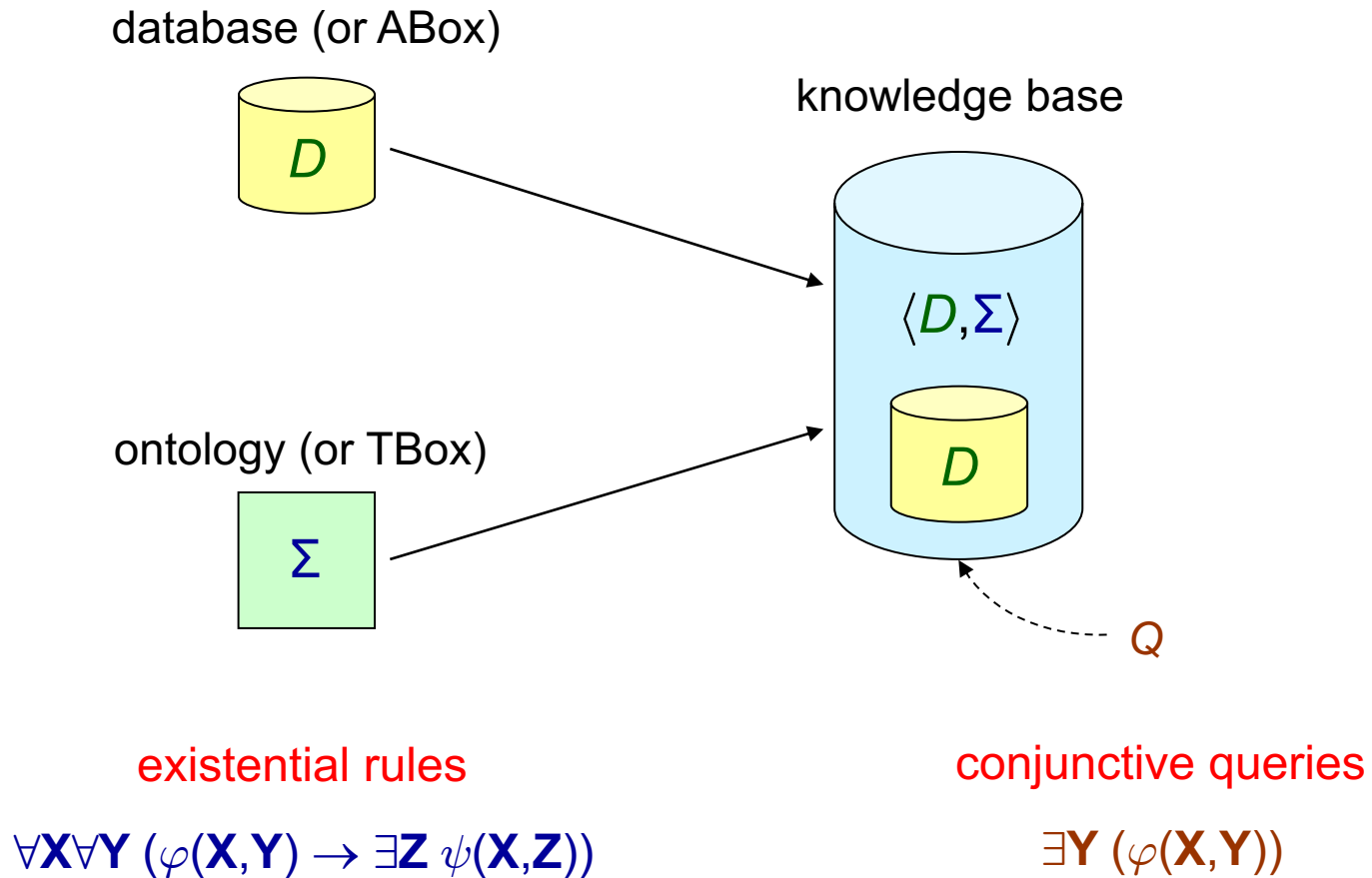


Semantics of Conjunctive Queries

- A **match** of a CQ $\exists \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}))$ in an instance \mathcal{J} is a homomorphism h such that $h(\varphi(\mathbf{X}, \mathbf{Y})) \subseteq \mathcal{J}$ i.e., all the atoms of the query are satisfied
- The **answer** to $Q = \exists \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}))$ over \mathcal{J} is the set of tuples
$$Q(\mathcal{J}) = \{h(\mathbf{X}) \mid h \text{ is a match of } Q \text{ in } \mathcal{J}\}$$
- The answer consists of the witnesses for the **free variables** of the query



Ontology-Based Query Answering (OBQA)



OBQA: Formal Definition

active domain – constants occurring in D

CQ-Answering:

Input: database D , existential rules Σ , CQ $Q = \exists \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}))$, tuple $\mathbf{t} \in \text{adom}(D)^{|\mathbf{X}|}$

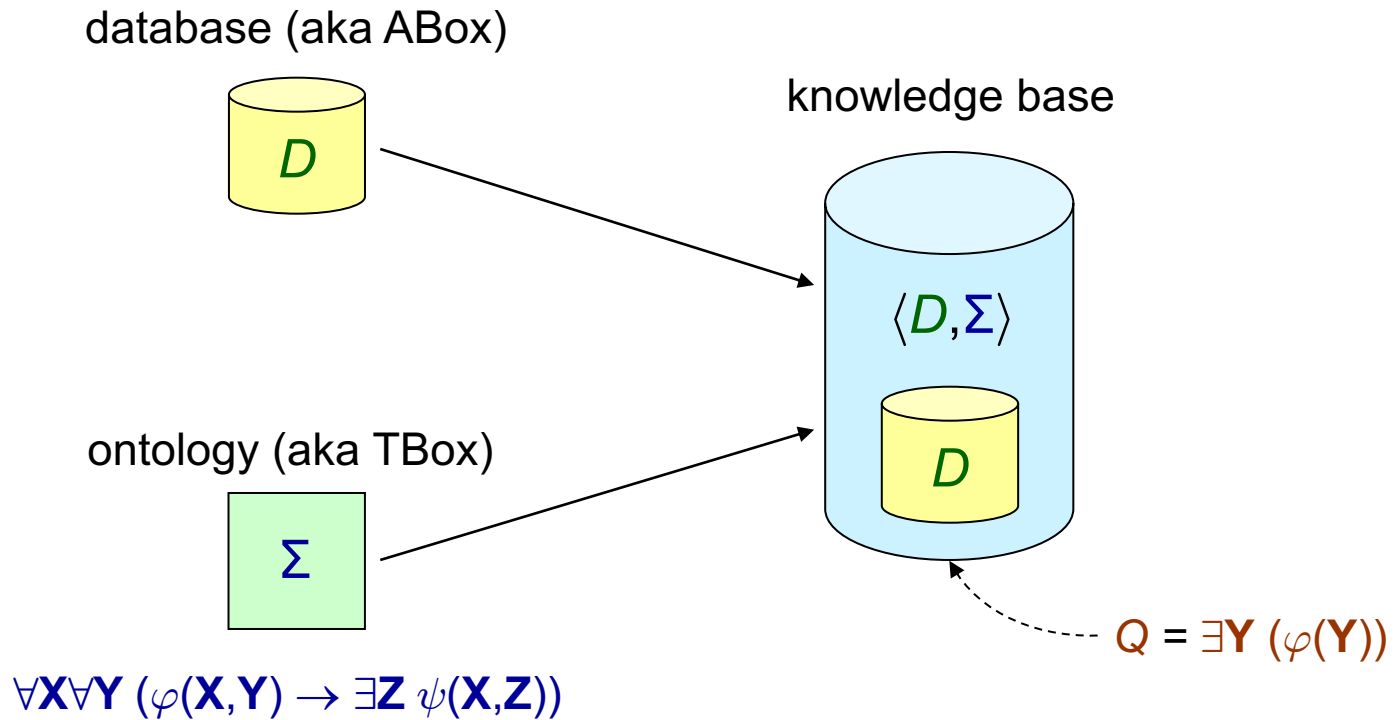
Question: decide whether $\mathbf{t} \in \text{certain}(Q, \langle D, \Sigma \rangle) = \bigcap_{J \in \text{models}(D \wedge \Sigma)} Q(J)_{\downarrow}$

$$\begin{aligned} \mathbf{t} \in \text{certain}(Q, \langle D, \Sigma \rangle) & \text{ iff } \mathbf{t} \in \bigcap_{J \in \text{models}(D \wedge \Sigma)} Q(J)_{\downarrow} \\ & \text{ iff } \forall J \in \text{models}(D \wedge \Sigma), J \models \exists \mathbf{Y} (\varphi(\mathbf{t}, \mathbf{Y})) \\ & \text{ iff } D \wedge \Sigma \models \exists \mathbf{Y} (\varphi(\mathbf{t}, \mathbf{Y})) \end{aligned}$$

Boolean CQ (BCQ) – no free variables

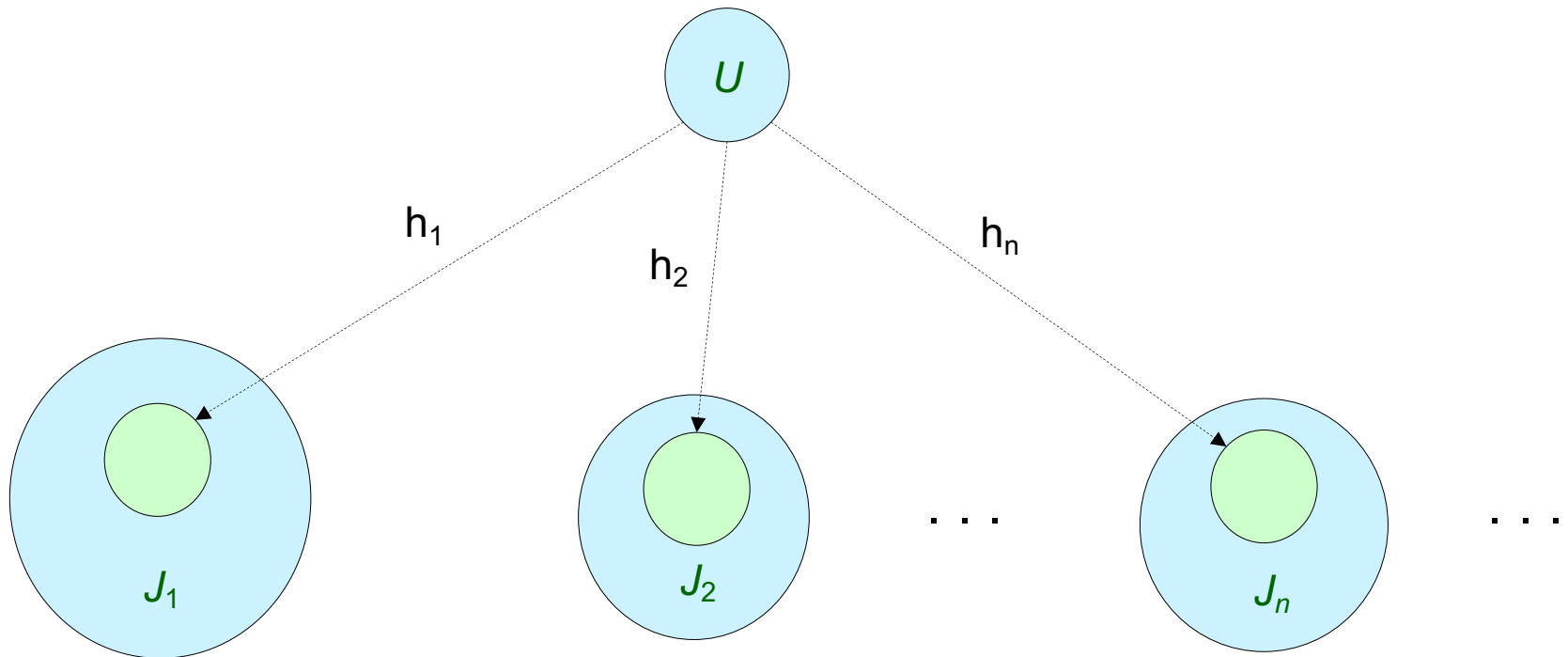


BCQ-Answering: Our Main Decision Problem



decide whether $D \wedge \Sigma \models Q$

Universal Models (a.k.a. Canonical Models)



An instance U is a **universal model** of $D \wedge \Sigma$ if the following holds:

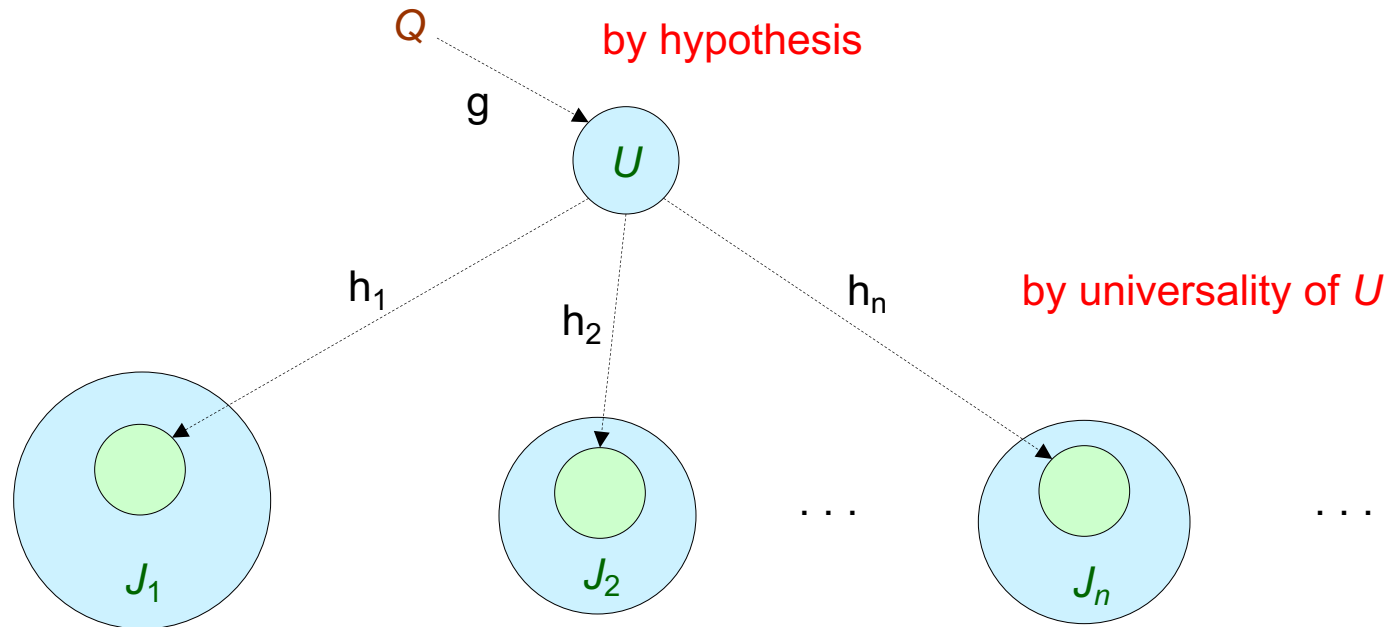
1. U is a model of $D \wedge \Sigma$
2. $\forall J \in \text{models}(D \wedge \Sigma)$, there exists a homomorphism h_J such that $h_J(U) \subseteq J$

Query Answering via Universal Models

Theorem: $D \wedge \Sigma \models Q$ iff $U \models Q$, where U is a universal model of $D \wedge \Sigma$

Proof: (\Rightarrow) Trivial since, for every $J \in \text{models}(D \wedge \Sigma)$, $J \models Q$

(\Leftarrow) By exploiting the universality of U



$$\begin{aligned} \forall J \in \text{models}(D \wedge \Sigma), \exists h_J \text{ such that } h_J(g(Q)) \subseteq J &\Rightarrow \forall J \in \text{models}(D \wedge \Sigma), J \models Q \\ &\Rightarrow D \wedge \Sigma \models Q \end{aligned}$$



The Chase Procedure

- **Fundamental algorithmic tool** used in databases
- It has been applied to a **wide range of problems**:
 - Checking containment of queries under constraints
 - Computing data exchange solutions
 - Computing certain answers in data integration settings
 - ...

... what's the reason for the ubiquity of the chase in databases?

it constructs universal models



The Chase Procedure

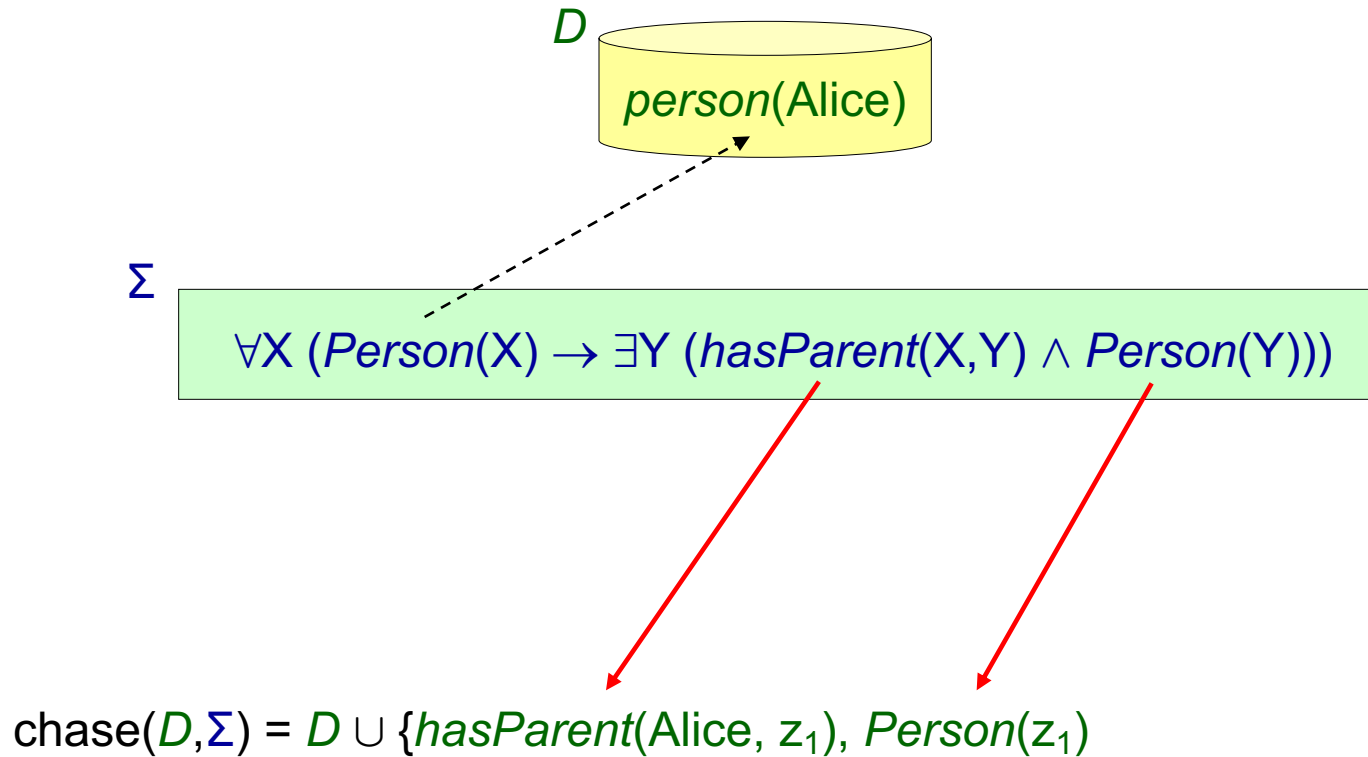


Σ

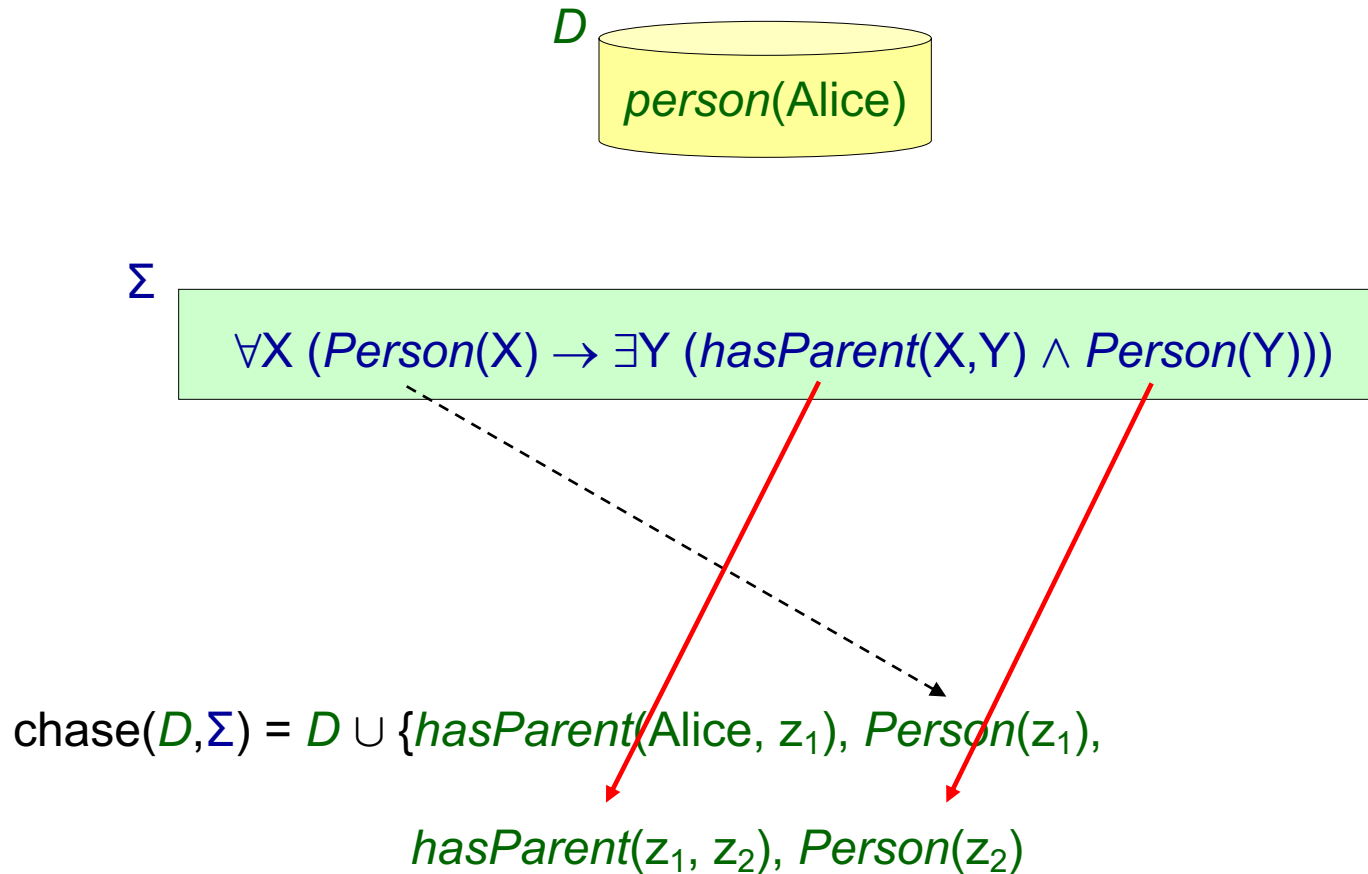
$\forall X (Person(X) \rightarrow \exists Y (hasParent(X,Y) \wedge Person(Y)))$

$\text{chase}(D, \Sigma) = D \cup$

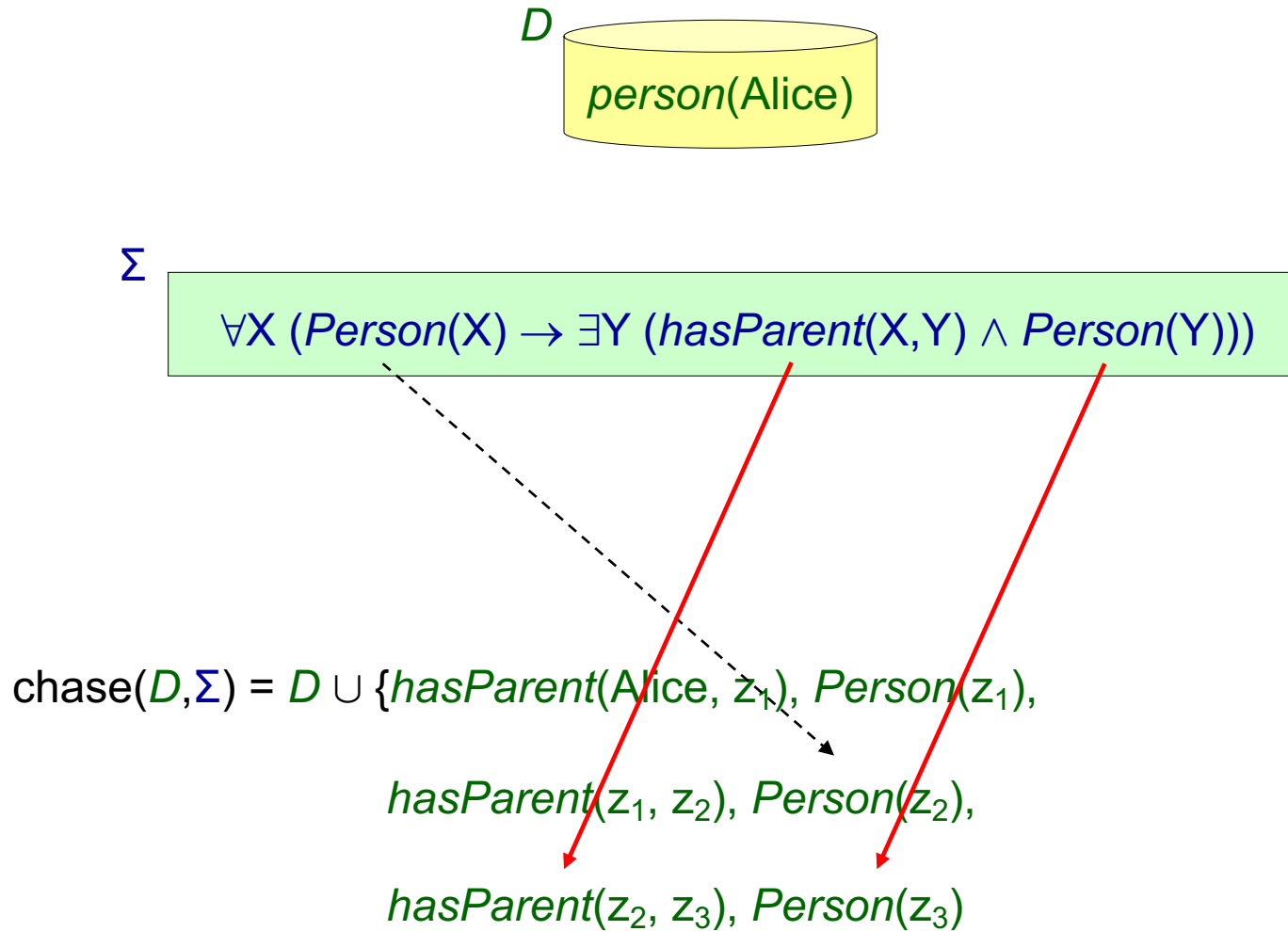
The Chase Procedure



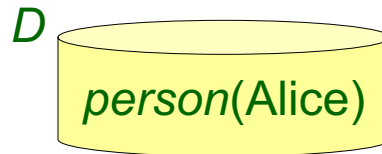
The Chase Procedure



The Chase Procedure



The Chase Procedure



Σ

$\forall X (Person(X) \rightarrow \exists Y (hasParent(X,Y) \wedge Person(Y)))$

$\text{chase}(D, \Sigma) = D \cup \{hasParent(Alice, z_1), Person(z_1),$

$hasParent(z_1, z_2), Person(z_2),$

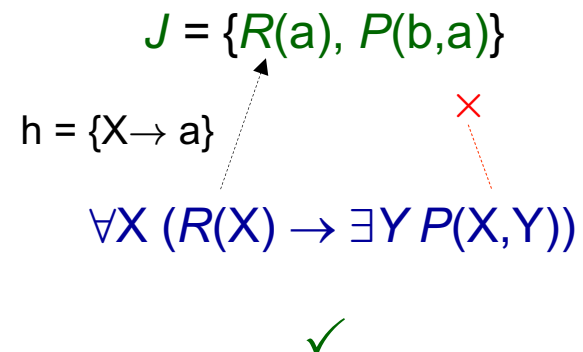
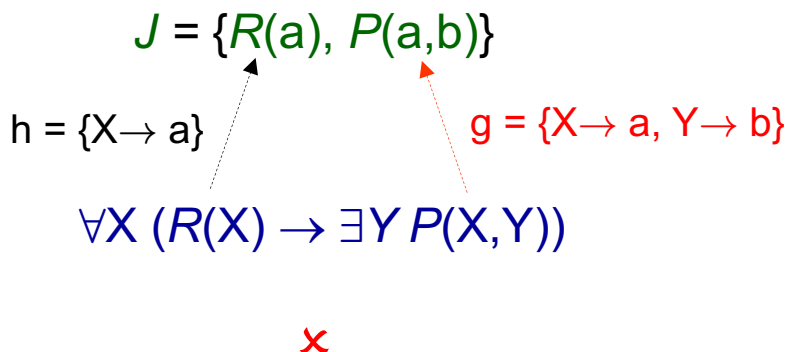
$hasParent(z_2, z_3), Person(z_3), \dots$

infinite instance



The Chase Procedure: Formal Definition

- **Chase rule** - the building block of the chase procedure
- A rule $\sigma = \forall \mathbf{X} \forall \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}) \rightarrow \exists \mathbf{Z} \psi(\mathbf{X}, \mathbf{Z}))$ is **applicable** to instance J if:
 1. There exists a homomorphism h such that $h(\varphi(\mathbf{X}, \mathbf{Y})) \subseteq J$
 2. There is no $g \supseteq h|_{\mathbf{X}}$ such that $g(\psi(\mathbf{X}, \mathbf{Z})) \subseteq J$



The Chase Procedure: Formal Definition

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- A rule $\sigma = \forall \mathbf{X} \forall \mathbf{Y} (\varphi(\mathbf{X}, \mathbf{Y}) \rightarrow \exists \mathbf{Z} \psi(\mathbf{X}, \mathbf{Z}))$ is **applicable** to instance J if:
 1. There exists a homomorphism h such that $h(\varphi(\mathbf{X}, \mathbf{Y})) \subseteq J$
 2. There is no $g \supseteq h|_{\mathbf{X}}$ such that $g(\psi(\mathbf{X}, \mathbf{Z})) \subseteq J$
- Let $J_+ = J \cup \{g(\psi(\mathbf{X}, \mathbf{Z}))\}$, where $g \supseteq h|_{\mathbf{X}}$ and $g(\mathbf{Z})$ are “fresh” nulls not in J
- The result of applying σ to J is J_+ , denoted $J \langle \sigma, h \rangle J_+$ - **single chase step**



The Chase Procedure: Formal Definition

- A **finite chase** of D w.r.t. Σ is a finite sequence

$$D \langle \sigma_1, h_1 \rangle J_1 \langle \sigma_2, h_2 \rangle J_2 \langle \sigma_3, h_3 \rangle J_3 \dots \langle \sigma_n, h_n \rangle J_n$$

where no rule from Σ is applicable in J_n .

Then, $\text{chase}(D, \Sigma)$ is defined as the instance J_n

all applicable rules will eventually be applied

- An **infinite chase** of D w.r.t. Σ is a **fair** finite sequence

$$D \langle \sigma_1, h_1 \rangle J_1 \langle \sigma_2, h_2 \rangle J_2 \langle \sigma_3, h_3 \rangle J_3 \dots \langle \sigma_n, h_n \rangle J_n \dots$$

and $\text{chase}(D, \Sigma)$ is **defined** as the instance $\bigcup_{k \geq 0} J_k$ (with $J_0 = D$)

least fixpoint of a monotonic operator - chase step



Chase: A Universal Model

Theorem: $\text{chase}(D, \Sigma)$ is a universal model of $D \wedge \Sigma$

the result of the chase after k applications of the chase step

Proof:

- By construction, $\text{chase}(D, \Sigma) \in \text{models}(D \wedge \Sigma)$
- It remains to show that $\text{chase}(D, \Sigma)$ can be homomorphically embedded into every other model of $D \wedge \Sigma$
- Fix an arbitrary instance $J \in \text{models}(D \wedge \Sigma)$. We need to show that there exists h such that $h(\text{chase}(D, \Sigma)) \subseteq J$
- By induction on the number of applications of the chase step, we show that for every $k \geq 0$, there exists h_k such that $h_k(\text{chase}^{[k]}(D, \Sigma)) \subseteq J$, and h_k is compatible with h_{k-1}
- Clearly, $\cup_{k \geq 0} h_k$ is a well-defined homomorphism that maps $\text{chase}(D, \Sigma)$ to J
- The claim follows with $h = \cup_{k \geq 0} h_k$



Chase: Uniqueness Property

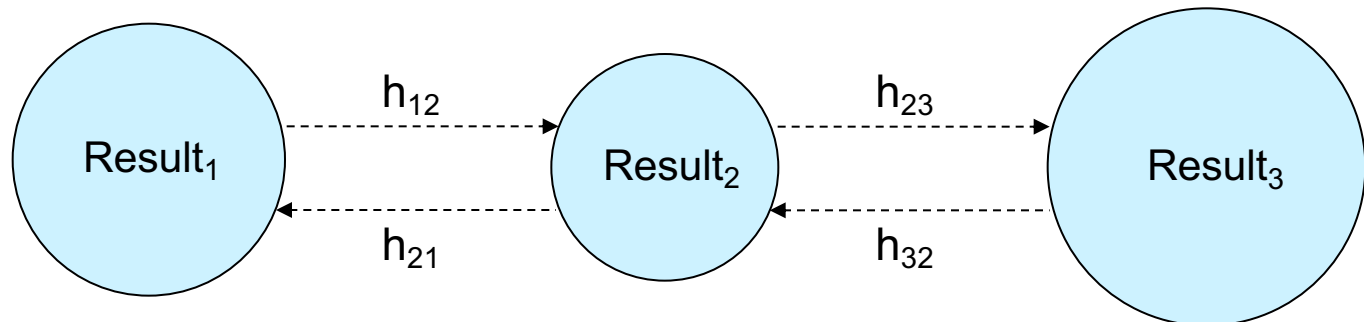
- The result of the chase is **not unique** - depends on the order of rule application

$$D = \{P(a)\} \quad \sigma_1 = \forall X (P(X) \rightarrow \exists Y R(Y)) \quad \sigma_2 = \forall X (P(X) \rightarrow R(X))$$

$$\text{Result}_1 = \{P(a), R(z), R(a)\} \quad \sigma_1 \text{ then } \sigma_2$$

$$\text{Result}_2 = \{P(a), R(a)\} \quad \sigma_2 \text{ then } \sigma_1$$

- But, it is **unique up to homomorphic equivalence**



- Thus, it is **unique** for query answering purposes

Query Answering via the Chase

Theorem: $D \wedge \Sigma \models Q$ iff $U \models Q$, where U is a universal model of $D \wedge \Sigma$

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Theorem: $\text{chase}(D, \Sigma)$ is a universal model of $D \wedge \Sigma$

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Corollary: $D \wedge \Sigma \models Q$ iff $\text{chase}(D, \Sigma) \models Q$

- We can tame the first dimension of infinity by exploiting the chase procedure
- But, **what about the second dimension of infinity?** - the chase may be infinite



Rest of the Lecture

- Undecidability of BCQ-Answering
- Gaining decidability - terminating chase
- Full Existential Rules
- Acyclic Existential Rules



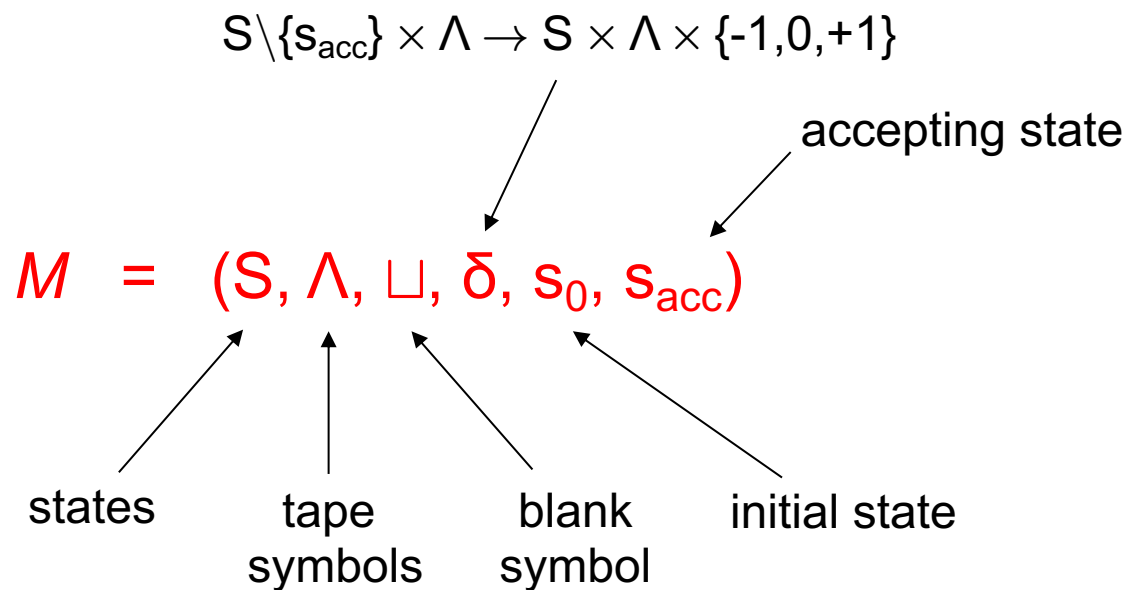
Undecidability of BCQ-Answering

Theorem: BCQ-Answering is **undecidable**

Proof : By simulating a deterministic Turing machine with an empty tape



Deterministic Turing Machine (DTM)



$$\delta(s_1, \alpha) = (s_2, \beta, +1)$$

IF at some time instant τ the machine is in state s_1 , the cursor points to cell κ , and this cell contains α

THEN at instant $\tau+1$ the machine is in state s_2 , cell κ contains β , and the cursor points to cell $\kappa+1$



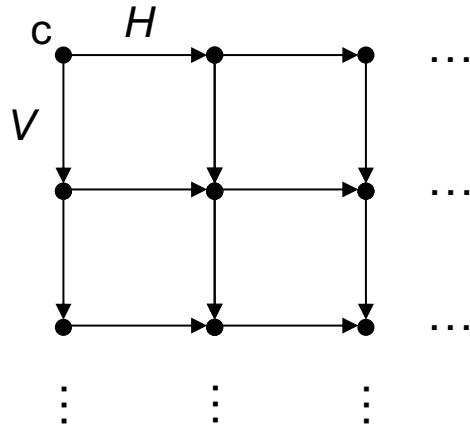
Undecidability of BCQ-Answering

Our Goal: Encode the computation of a DTM M with an empty tape using a database D , a set Σ of existential rules, and a BCQ Q such that

$$D \wedge \Sigma \models Q \text{ iff } M \text{ accepts}$$



Build an Infinite Grid



k -th horizontal line represents the
 k -th configuration of the machine

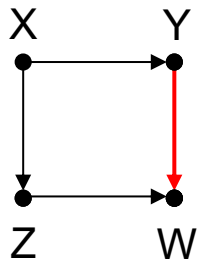
$$\forall X (Start(X) \rightarrow Node(X) \wedge Initial(X))$$

$$D = \{Start(c)\}$$

fixes the origin of the grid

$$\forall X (Node(X) \rightarrow \exists Y (H(X,Y) \wedge Node(Y)))$$

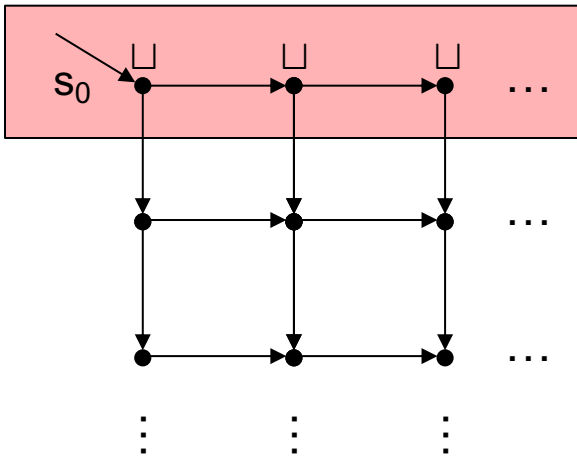
$$\forall X (Node(X) \rightarrow \exists Y (V(X,Y) \wedge Node(Y)))$$



$$\forall X \forall Y \forall Z \forall W (H(X,Y) \wedge H(Z,W) \wedge V(X,Z) \rightarrow V(Y,W))$$



Initialization Rules

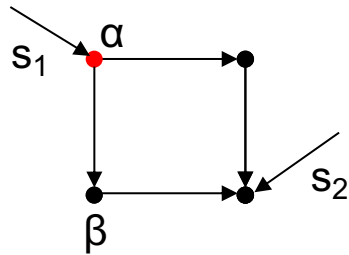


$$\forall X \forall Y (Initial(X) \wedge H(X, Y) \rightarrow Initial(Y))$$

$$\forall X (Start(X) \rightarrow Cursor[s_0](X))$$

$$\forall X (Initial(X) \rightarrow Symbol[\square](X))$$

Transition Rules



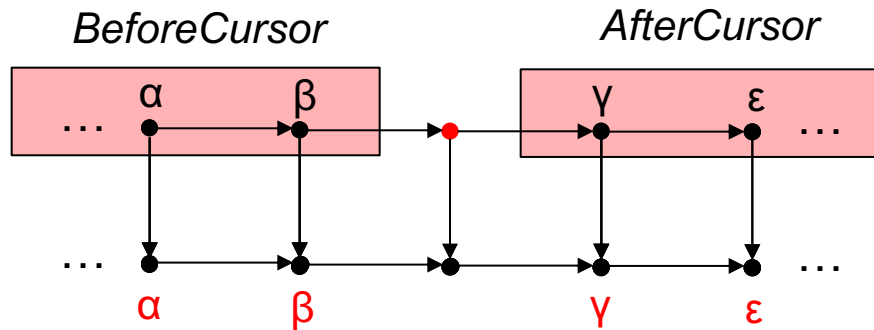
$$\delta(s_1, \alpha) = (s_2, \beta, +1)$$

$$\forall X \forall Y \forall Z (Cursor[s_1](X) \wedge Symbol[\alpha](X) \wedge V(X, Y) \wedge H(Y, Z) \rightarrow$$

$$Cursor[s_2](Z) \wedge Symbol[\beta](Y) \wedge Mark(X))$$



Inertia Rules



$$\forall X \forall Y (Mark(X) \wedge H(X, Y) \rightarrow AfterCursor(Y))$$

$$\forall X \forall Y (AfterCursor(X) \wedge H(X, Y) \rightarrow AfterCursor(Y))$$

$$\forall X \forall Y (AfterCursor(X) \wedge Symbol[\alpha](X) \wedge V(X, Y) \rightarrow Symbol[\alpha](Y))$$

...we have similar rules for the **cells before the cursor**

Accepting Rule

Once we reach the accepting state we accept

$$\forall X (Cursor[s_{acc}](X) \rightarrow Accept(X))$$

$D \wedge \Sigma \models \exists X Accept(X)$ iff the DTM M accepts



Undecidability of BCQ-Answering

Theorem: BCQ-Answering is **undecidable**

Proof : By simulating a deterministic Turing machine with an empty tape

...syntactic restrictions are needed!!!

