

Preserving Constraints with the Stable Chase

David Carral Markus Krötzsch *Maximilian Marx* Ana Ozaki
Sebastian Rudolph

TU Dresden

2018-03-27

ICDT 2018

Full paper: <https://iccl.inf.tu-dresden.de/web/Incidentals/en>

A bit of background

Motivation

- ▶ ontological modelling on knowledge graphs using *tuple-generating dependencies (TGDs)*: $\varphi(\mathbf{x}, \mathbf{y}) \rightarrow \exists z. \psi(\mathbf{x}, z)$
- ▶ Ontologies for Knowledge Graphs: Breaking the Rules, Krötzsch & Thost [ISWC 2016]

A bit of background

Motivation

- ▶ ontological modelling on knowledge graphs using *tuple-generating dependencies (TGDs)*: $\varphi(\mathbf{x}, \mathbf{y}) \rightarrow \exists z. \psi(\mathbf{x}, z)$
- ▶ Ontologies for Knowledge Graphs: Breaking the Rules, Krötzsch & Thost [ISWC 2016]

Observation

- ▶ Some functional dependencies may not hold, but assuming them doesn't change any (boolean) query answers.
- ▶ \rightsquigarrow “*incidental functional dependencies*”
- ▶ Query rewriting becomes easier if (some) incidentals are known.

A bit of background

Motivation

- ▶ ontological modelling on knowledge graphs using *tuple-generating dependencies (TGDs)*: $\varphi(\mathbf{x}, \mathbf{y}) \rightarrow \exists z. \psi(\mathbf{x}, z)$
- ▶ Ontologies for Knowledge Graphs: Breaking the Rules, Krötzsch & Thost [ISWC 2016]

Observation

- ▶ Some functional dependencies may not hold, but assuming them doesn't change any (boolean) query answers.
- ▶ \rightsquigarrow “*incidental functional dependencies*”
- ▶ Query rewriting becomes easier if (some) incidentals are known.

Now

- ▶ What about *incidental TGDs*?

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model.

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model. Add $\rho = R(y, z) \rightarrow \exists x. R(x, y)$:

$$\dots \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (2)$$

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model. Add $\rho = R(y, z) \rightarrow \exists x. R(x, y)$:

$$\dots \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (2)$$

- ▶ Clearly, $\Sigma \not\models \rho$.

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model. Add $\rho = R(y, z) \rightarrow \exists x. R(x, y)$:

$$\dots \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (2)$$

- ▶ Clearly, $\Sigma \not\models \rho$.
- ▶ Is there a *boolean conjunctive query (BCQ)* separating the two models?

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model. Add $\rho = R(y, z) \rightarrow \exists x. R(x, y)$:

$$\dots \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (2)$$

- ▶ Clearly, $\Sigma \not\models \rho$.
- ▶ Is there a *boolean conjunctive query* (BCQ) separating the two models?
- ▶ No, $\text{BCQ}(\Sigma) = \text{BCQ}(\Sigma \cup \{\rho\})$.

Incidental TGDs

Example

Consider $\Sigma = \{\exists x, y. R(x, y), \quad R(x, y) \rightarrow \exists z. R(y, z)\}$. Then

$$\bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (1)$$

is the unique universal model. Add $\rho = R(y, z) \rightarrow \exists x. R(x, y)$:

$$\dots \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \bullet \xrightarrow{R} \dots \quad (2)$$

- ▶ Clearly, $\Sigma \not\models \rho$.
- ▶ Is there a *boolean conjunctive query* (BCQ) separating the two models?
- ▶ No, $\text{BCQ}(\Sigma) = \text{BCQ}(\Sigma \cup \{\rho\})$.

Definition

A TGD ρ is *incidental* for a set Σ of TGDs if $\text{BCQ}(\Sigma) = \text{BCQ}(\Sigma \cup \{\rho\})$.

$\text{ICDT}(\Sigma)$ is the set of all TGDs incidental for Σ .

The finite case

Definition

INCIDENTAL: Given Σ set of TGDs and ρ TGD, decide whether $\rho \in \text{ICDT}(\Sigma)$.

The finite case

Definition

INCIDENTAL: Given Σ set of TGDs and ρ TGD, decide whether $\rho \in \text{ICDT}(\Sigma)$.

Theorem

Let Σ be a set of TGDs with finite universal model \mathcal{I} .
Then $\rho \in \text{ICDT}(\Sigma)$ iff $\text{core } \mathcal{I} \models \rho$.

The finite case

Definition

INCIDENTAL: Given Σ set of TGDs and ρ TGD, decide whether $\rho \in \text{ICDT}(\Sigma)$.

Theorem

Let Σ be a set of TGDs with finite universal model \mathcal{I} .
Then $\rho \in \text{ICDT}(\Sigma)$ iff $\text{core } \mathcal{I} \models \rho$.

- ▶ Use the *core chase* to compute $\text{core } \mathcal{I}$
- ▶ check $\text{core } \mathcal{I} \models \rho$
- ▶ \rightsquigarrow INCIDENTAL is decidable if Σ has a finite universal model.

The finite case

Definition

INCIDENTAL: Given Σ set of TGDs and ρ TGD, decide whether $\rho \in \text{ICDT}(\Sigma)$.

Theorem

Let Σ be a set of TGDs with finite universal model \mathcal{I} .
Then $\rho \in \text{ICDT}(\Sigma)$ iff $\text{core } \mathcal{I} \models \rho$.

- ▶ Use the *core chase* to compute $\text{core } \mathcal{I}$
- ▶ check $\text{core } \mathcal{I} \models \rho$
- ▶ \rightsquigarrow INCIDENTAL is decidable if Σ has a finite universal model.
- ▶ But what can we say in general?

Deciding INCIDENTAL

Theorem

INCIDENTAL is Π_2^0 -complete, and thus neither in RE nor in coRE.

Deciding INCIDENTAL?

Theorem

INCIDENTAL is Π_2^0 -complete, and thus neither in RE nor in coRE.

- ▶ Can we do better if BCQ entailment is decidable?

Deciding INCIDENTAL?

Theorem

INCIDENTAL is Π_2^0 -complete, and thus neither in RE nor in CORE.

- ▶ Can we do better if BCQ entailment is decidable?

Theorem

Let \mathcal{C} be a class of sets of TGDs for which BCQ entailment is decidable. Then INCIDENTAL is in CORE for any $\Sigma \in \mathcal{C}$.

Deciding INCIDENTAL?

Theorem

INCIDENTAL is Π_2^0 -complete, and thus neither in RE nor in CORE.

- ▶ Can we do better if BCQ entailment is decidable?

Theorem

Let \mathcal{C} be a class of sets of TGDs for which BCQ entailment is decidable. Then INCIDENTAL is in CORE for any $\Sigma \in \mathcal{C}$.

- ▶ Idea: if $\rho \notin \text{ICDT}(\Sigma)$, there is a BCQ q with $\Sigma \not\models q$ and $\Sigma \cup \{\rho\} \models q$.
- ▶ Can we do better?

Deciding INCIDENTAL?

Theorem

INCIDENTAL is Π_2^0 -complete, and thus neither in RE nor in CORE.

- ▶ Can we do better if BCQ entailment is decidable?

Theorem

Let \mathcal{C} be a class of sets of TGDs for which BCQ entailment is decidable. Then INCIDENTAL is in CORE for any $\Sigma \in \mathcal{C}$.

- ▶ Idea: if $\rho \notin \text{ICDT}(\Sigma)$, there is a BCQ q with $\Sigma \not\models q$ and $\Sigma \cup \{\rho\} \models q$.
- ▶ Can we do better?
- ▶ Unfortunately, no.

Undecidability of INCIDENTAL

Theorem

There is a class \mathcal{C} of sets of TGDs and a full dependency ρ such that

- ▶ *BCQ entailment for $\Sigma \in \mathcal{C}$ is decidable,*
- ▶ *$\Sigma \cup \{\rho\} \in \mathcal{C}$ for any $\Sigma \in \mathcal{C}$, and*
- ▶ *checking $\rho \in \text{ICDT}(\Sigma)$ is undecidable.*

Undecidability of INCIDENTAL

Theorem

There is a class \mathcal{C} of sets of TGDs and a full dependency ρ such that

- ▶ *BCQ entailment for $\Sigma \in \mathcal{C}$ is decidable,*
- ▶ *$\Sigma \cup \{\rho\} \in \mathcal{C}$ for any $\Sigma \in \mathcal{C}$, and*
- ▶ *checking $\rho \in \text{ICDT}(\Sigma)$ is undecidable.*

What about incidentals in general?

- ▶ Recall: in the finite case, $\rho \in \text{ICDT}(\Sigma)$ iff $\text{core } \mathcal{I} \models \rho$
- ▶ Is there some universal model that entails all incidental TGDs?
- ▶ The core looks like a promising candidate.

Cores of infinite instances

Different definitions of *core* agree on finite instances, but differ in general.

Definition

An instance \mathcal{I} is a *core* if every endomorphism $h : \mathcal{I} \rightarrow \mathcal{I}$ is an embedding.
A core \mathcal{I} is a core of \mathcal{J} if $\mathcal{I} = \mathcal{J}|_{h(\mathcal{J})}$ for an endomorphism $h : \mathcal{J} \rightarrow \mathcal{J}$.

Cores of infinite instances

Different definitions of *core* agree on finite instances, but differ in general.

Definition

An instance \mathcal{I} is a *core* if every endomorphism $h : \mathcal{I} \rightarrow \mathcal{I}$ is an embedding.
A core \mathcal{I} is a core of \mathcal{J} if $\mathcal{I} = \mathcal{J}|_{h(\mathcal{J})}$ for an endomorphism $h : \mathcal{J} \rightarrow \mathcal{J}$.

Unfortunately, there are sets Σ of TGDs with universal models \mathcal{I} such that

- ▶ \mathcal{I} doesn't have a core,
- ▶ \mathcal{I} has two non-isomorphic cores, or
- ▶ \mathcal{I} has a core that is not a model of Σ .

Cores of infinite instances

Different definitions of *core* agree on finite instances, but differ in general.

Definition

An instance \mathcal{I} is a *core* if every endomorphism $h : \mathcal{I} \rightarrow \mathcal{I}$ is an embedding. A core \mathcal{I} is a core of \mathcal{J} if $\mathcal{I} = \mathcal{J}|_{h(\mathcal{J})}$ for an endomorphism $h : \mathcal{J} \rightarrow \mathcal{J}$.

Unfortunately, there are sets Σ of TGDs with universal models \mathcal{I} such that

- ▶ \mathcal{I} doesn't have a core,
- ▶ \mathcal{I} has two non-isomorphic cores, or
- ▶ \mathcal{I} has a core that is not a model of Σ .

Theorem

Let Σ be a set of TGDs. There is a core \mathcal{I} with $\mathcal{I} \models \Sigma$, $\text{BCQ}(\mathcal{I}) = \text{BCQ}(\Sigma)$, and $\rho \in \text{ICDT}(\Sigma)$ iff $\mathcal{I} \models \rho$.

Cores of infinite instances

Different definitions of *core* agree on finite instances, but differ in general.

Definition

An instance \mathcal{I} is a *core* if every endomorphism $h : \mathcal{I} \rightarrow \mathcal{I}$ is an embedding. A core \mathcal{I} is a core of \mathcal{J} if $\mathcal{I} = \mathcal{J}|_{h(\mathcal{J})}$ for an endomorphism $h : \mathcal{J} \rightarrow \mathcal{J}$.

Unfortunately, there are sets Σ of TGDs with universal models \mathcal{I} such that

- ▶ \mathcal{I} doesn't have a core,
- ▶ \mathcal{I} has two non-isomorphic cores, or
- ▶ \mathcal{I} has a core that is not a model of Σ .

Theorem

Let Σ be a set of TGDs. There is a core \mathcal{I} with $\mathcal{I} \models \Sigma$, $\text{BCQ}(\mathcal{I}) = \text{BCQ}(\Sigma)$, and $\rho \in \text{ICDT}(\Sigma)$ iff $\mathcal{I} \models \rho$.

- ▶ Can we generalise the core chase to this setting?

The stable chase by example

$$\Sigma = \{\exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z)\}$$

The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



n_0 n_1

The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



n_0 n_1 n_{-1} n_0 n_1 n_2

The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



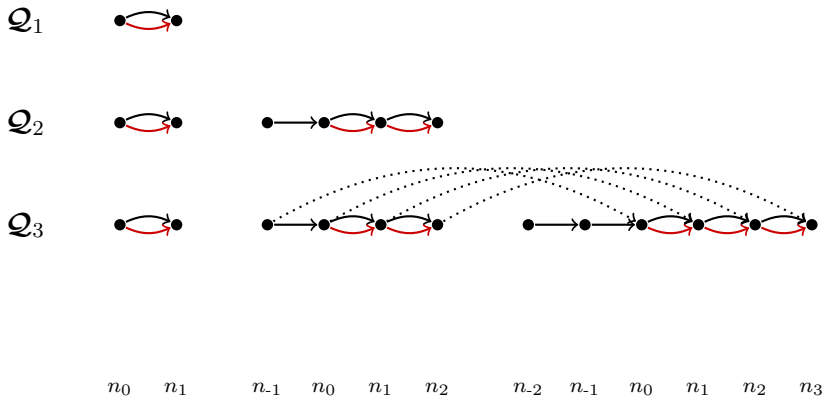
$n_0 \quad n_1$

$n_{-1} \quad n_0 \quad n_1 \quad n_2$

$n_{-2} \quad n_{-1} \quad n_0 \quad n_1 \quad n_2 \quad n_3$

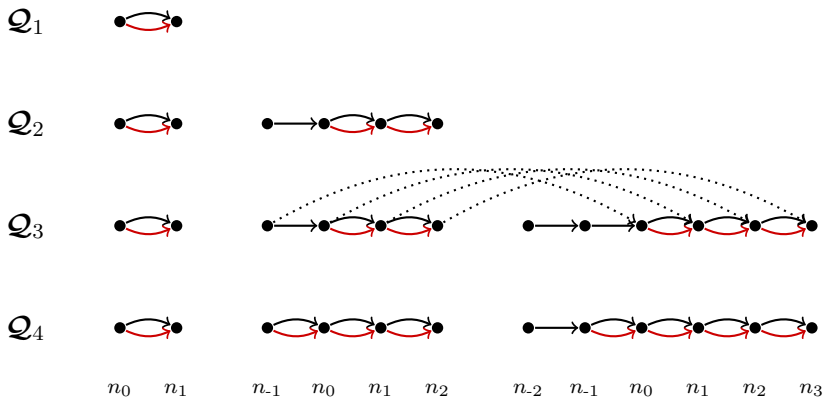
The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



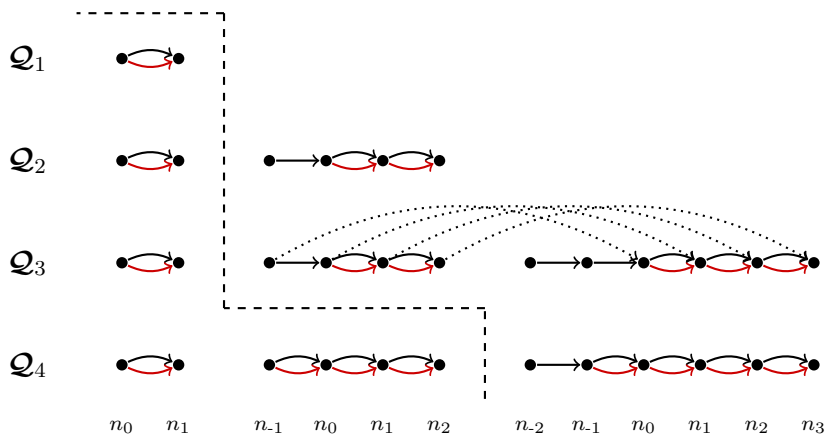
The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



The stable chase by example

$$\Sigma = \{ \exists x, y. R(x, y) \wedge S(x, y), \quad R(y, z) \rightarrow \exists x. R(x, y), \\ R(x, y) \wedge S(x, y) \rightarrow \exists z. R(y, z) \wedge S(y, z) \}$$



The stable chase

The idea

- ▶ Consider a sequence of initial segments of chase sequences (prefixes):
- ▶ apply TGDs to last instance and obtain a longer prefix, or
- ▶ *rewrite* prefix according to some non-embedding endomorphism between instances \rightsquigarrow enforce an embedding
- ▶ instances can only be rewritten finitely often and stabilise at some point
- ▶ The *stable chase* is the union of all stable instances.

The stable chase

The idea

- ▶ Consider a sequence of initial segments of chase sequences (prefixes):
- ▶ apply TGDs to last instance and obtain a longer prefix, or
- ▶ *rewrite* prefix according to some non-embedding endomorphism between instances \rightsquigarrow enforce an embedding
- ▶ instances can only be rewritten finitely often and stabilise at some point
- ▶ The *stable chase* is the union of all stable instances.

Theorem

For any set Σ of TGDs, the stable chase \mathcal{I} of Σ is a core with $\mathcal{I} \models \Sigma$, $\text{BCQ}(\mathcal{I}) = \text{BCQ}(\Sigma)$, and $\rho \in \text{ICDT}(\Sigma)$ iff $\mathcal{I} \models \rho$ for any full dependency ρ .

The stable chase

The idea

- ▶ Consider a sequence of initial segments of chase sequences (prefixes):
- ▶ apply TGDs to last instance and obtain a longer prefix, or
- ▶ *rewrite* prefix according to some non-embedding endomorphism between instances \rightsquigarrow enforce an embedding
- ▶ instances can only be rewritten finitely often and stabilise at some point
- ▶ The *stable chase* is the union of all stable instances.

Theorem

For any set Σ of TGDs, the stable chase \mathcal{I} of Σ is a core with $\mathcal{I} \models \Sigma$, $\text{BCQ}(\mathcal{I}) = \text{BCQ}(\Sigma)$, and $\rho \in \text{ICDT}(\Sigma)$ iff $\mathcal{I} \models \rho$ for any full dependency ρ .

- ▶ If Σ has a finite universal model \mathcal{J} , then core $\mathcal{J} = \mathcal{I}$.
- ▶ Beware: Stability of an instance is undecidable.

Conclusion & Outlook

Results

- ▶ Incidentalness is Π_2^0 -complete, and still not in RE even when BCQ entailment is decidable.
- ▶ Each set Σ of TGDs has a BCQ-equivalent core \mathcal{I} with $\mathcal{I} \models \text{ICDT}(\Sigma)$.
- ▶ The stable chase generalises the core chase to classes that don't admit finite universal models.
- ▶ The stable chase yields a core that characterises the full incidental dependencies.

Future work

- ▶ Further generalise the stable chase to characterise all incidentals.
- ▶ Investigate complexity of `INCIDENTAL` for decidable classes.
- ▶ Design (incomplete) algorithms that compute incidentals.