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Navigating ASP Solution Spaces

Hanoi, 2nd November 2024

Motivation

Searching for a Bicycle



Motivation

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Motivation

Combinatorial Search Problems

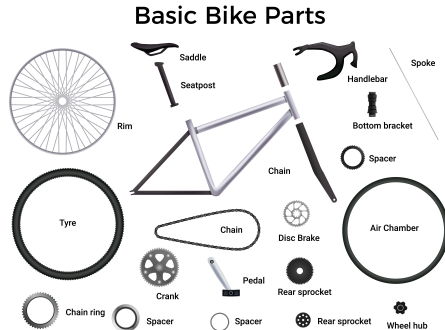


Figure 1: Bunt Vektor erstellt von macrovector - de.freepik.com

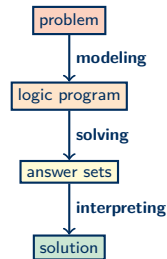
Answer Set Programming (ASP)

knowledge representation



Declarative problem solving

- planning
- product configuration
- diagnosis
- ⋮



ASP Modelling and Solving

```
#const n=14.  
{q(I, 1..n)} == 1 :- I = 1..n.  
{q(1..n, J)} == 1 :- J = 1..n.  
:- {q(D-J,J)} >=2, D=2..2*n.  
:- {q(D+J,J)} >=2, D=1-n..n-1.
```

solver



```
Answer: 1  
q(5,13) q(7,14) q(2,8) q(6,11) q(4,7) q(1,3) q(9,10)  
q(12,12) q(3,2) q(8,5) q(10,6) q(14,9) q(11,4) q(13,1)  
Answer: 2  
q(2,12) q(1,9) q(7,13) q(6,11) q(4,7) q(12,14) q(9,10)  
q(3,3) q(5,4) q(8,5) q(10,6) q(14,8) q(11,1) q(13,2)  
Answer: 3  
q(1,13) q(7,14) q(3,9) q(6,11) q(4,7) q(2,4) q(9,10)  
q(12,12) q(5,3) q(10,6) q(14,8) q(8,1) q(13,5) q(11,2)  
:  
Answer: 365596  
q(4,13) q(1,9) q(7,14) q(3,8) q(2,6) q(8,11) q(11,12)  
q(5,4) q(12,10) q(9,5) q(6,1) q(13,7) q(10,3) q(14,2)  
SATISFIABLE
```

Navigating ASP Solution Spaces

```
#const n=14.  
{q(I, 1..n)} == 1 :- I = 1..n.  
{q(1..n, J)} == 1 :- J = 1..n.  
:- {q(D-J,J)} >=2, D=2..2*n.  
:- {q(D+J,J)} >=2, D=1-n..n-1.
```

Diverse Solutions:

Solution: 1

q(1,12) q(2,8) q(3,6) q(4,14) q(5,9) q(6,2) q(7,5)
q(14,1) q(9,11) q(10,7) q(11,10) q(12,4) q(13,13) q(8,3)

Solution: 2

q(1,1) q(2,10) q(3,5) q(4,7) q(5,12) q(6,3) q(7,11)
q(8,2) q(9,14) q(10,9) q(11,4) q(12,13) q(13,8) q(14,6)

Solution: 3

q(1,11) q(2,2) q(3,10) q(4,6) q(5,3) q(6,1) q(7,13)
q(8,7) q(9,12) q(10,14) q(11,8) q(12,5) q(13,9) q(14,4)

Quantitative Reasoning:

- * zoom in
- * zoom out
- * ...

Visual Approach:

- * zoom in
- * zoom out
- * ...

Outline

- Preliminaries
- Weighted Faceted Navigation
- Diverse Answer Sets
- Representative Answer Sets
- Visual Approach for Solution Space Exploration
- Conclusion

Preliminaries

Definition (logic program)

A (normal disjunctive) *logic program* Π over a set of atoms $\{\alpha_0, \dots, \alpha_n\}$ is a finite set of rules r of the form:

$$\alpha_0 \mid \dots \mid \alpha_k \leftarrow \alpha_{k+1}, \dots, \alpha_m, \sim \alpha_{m+1}, \dots, \sim \alpha_n. \text{ where } 0 \leq k \leq m \leq n$$

Remark: We focus on ground programs without extended rules.

$\mathcal{AS}(\Pi)$... **answer sets** (solutions)

$2^{\mathcal{AS}(\Pi)}$... **solution space**

$\mathcal{BC}(\Pi) := \bigcup \mathcal{AS}(\Pi)$... **brave consequences**

$\alpha \in \mathcal{BC}(\Pi)$... **partial solution**

$\mathcal{CC}(\Pi) := \bigcap \mathcal{AS}(\Pi)$... **cautious consequences**

Part 1 Weighted Faceted Navigation

Systematic Faceted Navigation

$\Pi: a|b. c|d \leftarrow b. e.$

Systematic Faceted Navigation

Π : $a|b.$ $c|d \leftarrow b.$ $e.$

Facets: $\mathcal{F}(\Pi) = \{a, b, c, d, \bar{a}, \bar{b}, \bar{c}, \bar{d}\}$

ANSWER 1: a, e

ANSWER 2: b, c, e

ANSWER 3: b, d, e

Systematic Faceted Navigation

Π : a|b. c|d ← b. e.

$$\text{Facets: } \mathcal{F}(\Pi) := \underbrace{\{a, b, c, d\}}_{\mathcal{F}^+(\Pi) := \mathcal{BC}(\Pi) \setminus \mathcal{CC}(\Pi)} \cup \underbrace{\{\bar{a}, \bar{b}, \bar{c}, \bar{d}\}}_{\mathcal{F}^-(\Pi) := \{\bar{\alpha} \mid \alpha \in \mathcal{F}^+(\Pi)\}}$$

ANSWER 1: a, e

ANSWER 2: b, c, e

ANSWER 3: b, d, e

Systematic Faceted Navigation

Π : a|b. c|d ← b. e.

Facets: $\mathcal{F}(\Pi) = \{a, b, c, d, \bar{a}, \bar{b}, \bar{c}, \bar{d}\}$

Routes: $\Delta^\Pi := \{\langle f_0, \dots, f_n \rangle \mid f_i \in \mathcal{F}(\Pi), 0 \leq i \leq n\} \cup \{\epsilon\}$

ANSWER 1: a, e

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Systematic Faceted Navigation

Π : $a|b. c|d \leftarrow b. e.$

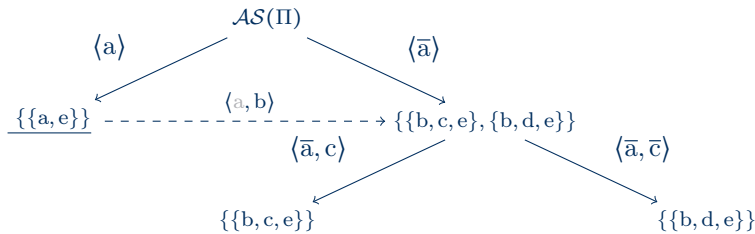
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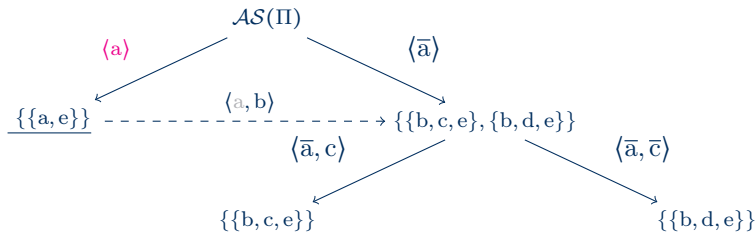
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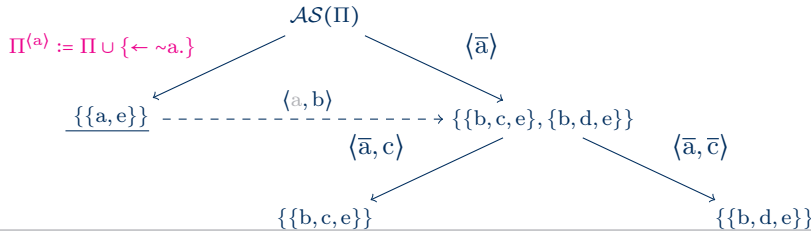
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~~ANSWER 2: b, c, e~~

~~ANSWER 3: b, d, e~~



Systematic Faceted Navigation

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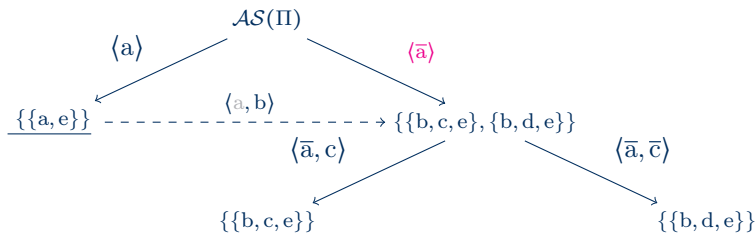
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ANSWER 1: a, e

ANSWER 2: b, c, e

ANSWER 3: b, d, e



Systematic Faceted Navigation

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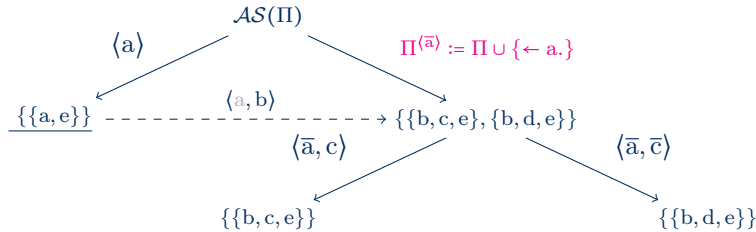
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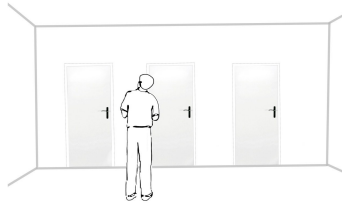
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ANSWER 3: b, d, e



What is the effect of taking a certain navigation step?

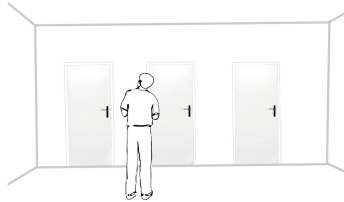
Can we somehow characterize sub-spaces beforehand?



[1] Johannes Klaus Fichte, S.A.G., Dominik Rusovac. **Rushing and Strolling among Answer Sets - Navigation Made Easy**
Proceedings of the 36th AAAI Conference on Artificial Intelligence (AAAI 2022), 2022.

What is the effect of taking a certain navigation step?

Can we somehow characterize sub-spaces beforehand?



 **Let's do some counting!**

Quantifying effects of navigation steps

The Weight of a Facet

Definition (weighting function)

We call $\# : \{\Pi^\delta \mid \delta \in \Delta^\Pi\} \rightarrow \mathbb{N}$ *weighting function*, whenever $\#(\Pi^\delta) > 0$, if $|\mathcal{AS}(\Pi)| \geq 2$.

Definition (weight)

Let $\delta \in \Delta^\Pi$, $f \in \mathcal{F}(\Pi)$ and δ' be a redirection of δ w.r.t. f . The *weight* of f w.r.t. $\#, \Pi^\delta$ and δ' is defined as:

$$\omega_{\#}(f, \Pi^\delta, \delta') := \begin{cases} \#(\Pi^\delta) - \#(\Pi^{\delta'}), & \text{if } \langle \delta, f \rangle \notin \Delta_s^\Pi \text{ and } \delta' \neq \epsilon; \\ \#(\Pi^\delta) - \#(\Pi^{\langle \delta, f \rangle}), & \text{otherwise.} \end{cases}$$

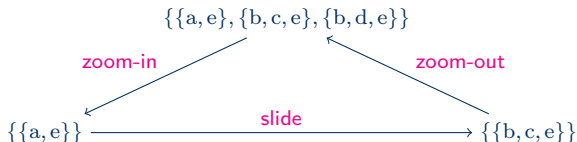
The Weight of a Facet

Definition (weight)

Let $\delta \in \Delta^\Pi$, $f \in \mathcal{F}(\Pi)$ and δ' be a redirection of δ w.r.t. f . The *weight* of f w.r.t. $\#, \Pi^\delta$ and δ' is defined as:

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Effects:



Which Weighting Function? Absolute vs. Relative Weights

Natural choice?

Which Weighting Function? Absolute vs. Relative Weights

Natural choice?

- Absolute Weight:
Count Answer Sets with $\omega_{\#AS}$

$$\mathcal{AS}(\Pi) = \{\{a, e\}, \{b, c, e\}, \{b, d, e\}\}$$

$$\omega_{\#AS}(b, \Pi, \epsilon) = 1$$



$$\mathcal{AS}(\Pi^{(b)}) = \{\{b, c, e\}, \{b, d, e\}\}$$

Which Weighting Function? Absolute vs. Relative Weights

Natural choice?

- Absolute Weight:
Count Answer Sets with $\omega_{\#_{AS}}$

Counting answer sets is hard ☹ [3]

$$\mathcal{AS}(\Pi) = \{\{a, e\}, \{b, c, e\}, \{b, d, e\}\}$$

$$\omega_{\#_{AS}}(b, \Pi, \epsilon) = 1$$



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[2] Johannes K Fichte, Markus Hecher, Michael Morak, and Stefan Woltran. **Answer set solving with bounded treewidth revisited**. In LPNMR 2017.

Which Weighting Function? Absolute vs. Relative Weights

Natural choice?

- Absolute Weight:
Count Answer Sets with $\omega_{\#AS}$

Counting answer sets is hard ☹ [3]

Relative Weights:
cheaper methods to quantify effects

- Count Supported Models with $\omega_{\#S}$

$$\mathcal{AS}(\Pi) = \{\{a, e\}, \{b, c, e\}, \{b, d, e\}\}$$

$$\omega_{\#S}(b, \Pi, \epsilon) = 1$$



$$\mathcal{AS}(\Pi^{(b)}) = \{\{b, c, e\}, \{b, d, e\}\}$$

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Which Weighting Function? Absolute vs. Relative Weights

Natural choice?

- Absolute Weight:
Count Answer Sets with $\omega_{\#_{AS}}$

Counting answer sets is hard ☹ [fichte2017answer]

Relative Weights:
cheaper methods to quantify effects

- Count Supported Models with $\omega_{\#_S}$
- Count Facets with $\omega_{\#_{\mathcal{F}}}$

$$\mathcal{AS}(\Pi) = \{\{a, e\}, \{b, c, e\}, \{b, d, e\}\}$$

$$\omega_{\#_{\mathcal{F}}}(\bar{b}, \Pi, \epsilon) = 4$$



$$\mathcal{AS}(\Pi^{(\bar{b})}) = \{\{b, c, e\}, \{b, d, e\}\}$$

$$\mathcal{AS}(\Pi) = \{\{a, e\}, \{b, c, e\}, \{b, d, e\}\}$$

$$\omega_{\#_{\mathcal{F}}}(\bar{c}, \Pi, \epsilon) = 2$$



$$\mathcal{AS}(\Pi^{(\bar{c})}) = \{\{a, e\}, \{b, d, e\}\}$$

[2] Johannes K Fichte, Markus Hecher, Michael Morak, and Stefan Woltran. **Answer set solving with bounded treewidth revisited.** In LPNMR 2017.

Rushing and Strolling among Answer Sets

Definition (strictly goal-oriented navigation mode)

The *strictly goal-oriented* navigation mode $\nu_{\text{sgo}}^{\#} : \Delta_{\text{s}}^{\Pi} \times \mathcal{F}(\Pi) \rightarrow 2^{\mathcal{AS}(\Pi)}$ is defined by:

$$\nu_{\text{sgo}}^{\#}(\delta, f) := \begin{cases} \mathcal{AS}(\Pi^{(\delta, f)}), & \text{if } f \in \max_{\omega_{\#}}(\Pi^{\delta}); \\ \mathcal{AS}(\Pi^{\delta}), & \text{otherwise.} \end{cases}$$

Definition (explore navigation mode)

















The *explore* navigation mode $\nu_{\text{expl}}^{\#} : \Delta_{\text{s}}^{\Pi} \times \mathcal{F}(\Pi) \rightarrow 2^{\mathcal{AS}(\Pi)}$ is defined by:

$$\nu_{\text{expl}}^{\#}(\delta, f) := \begin{cases} \mathcal{AS}(\Pi^{(\delta, f)}), & \text{if } f \in \min_{\omega_{\#}}(\Pi^{\delta}); \\ \mathcal{AS}(\Pi^{\delta}), & \text{otherwise.} \end{cases}$$

Quantitative Arguments

	2		5		1		9	
8			2		3			6
	3			6			7	
6	6	1		2	2 6			
5	4			2		8	1	9
				2 5	2 5	7		
	9			3			8	
2			8		4			7
	1		9		7		6	

How to solve this Sudoku as quick as possible?

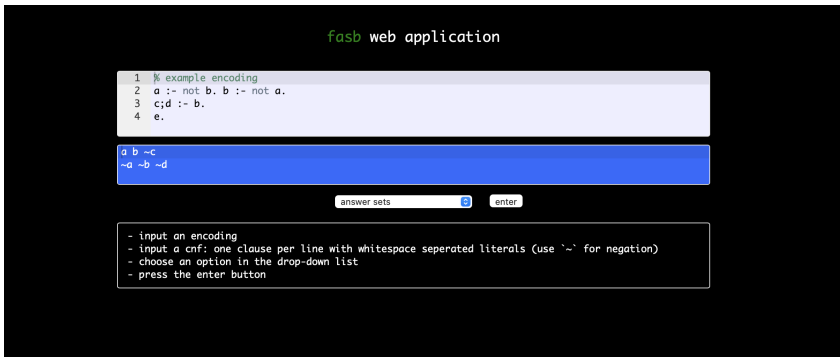
1								
2								
3								
4								
5								
6								
7								
8								
	1	2	3	4	5	6	7	8

Which moves (queens) have the **least** (1/4)/**most** (3/4) impact?

fasb – Faceted Answer Set Browser

REPL on top of clingo solver implementing: ν_{go} , $\nu_{sgo}^{\#}$, $\nu_{expl}^{\#}$ for $\# \in \{\#_{AS}, \#_{\mathcal{F}}\}$

<https://github.com/drwadu/fasb>



The screenshot shows the 'fasb web application' interface. It features a text input area with the following example encoding:

```
1 % example encoding
2 a :- not b, b :- not a.
3 c;d :- b.
4 e.
```

Below the input is a blue box containing the selected answer set:

```
a b ~c
~a ~b ~d
```

Underneath the blue box is a dropdown menu with 'answer sets' selected and an 'enter' button.

At the bottom, a list of instructions is provided:

- input an encoding
- input a cnf: one clause per line with whitespace separated literals (use '~' for negation)
- choose an option in the drop-down list
- press the enter button

<https://drwadu.github.io/web-fasb.github.io/>

Concluding on Weighted Faceted Navigation

- Concept is rather easy to understand
- Answer set counting is hard
 - IASCAR [3]
 - Quantum faceted navigation [4]
- Facet counting is easier (practical feasibility) [5]

[3] Johannes Klaus Fichte, S.A.G., Markus Hecher, Dominik Rusovac. **IASCAR: Incremental Answer Set Counting by Anytime Refinement** Theory and Practice of Logic Programming, 24(3):505-532, May 2024.

[4] Riccardo Romanello, Davide Della Giustina, Stefano Pessotto, Carla Piazza. **Speeding up Answer Set Programming by Quantum Computing** QUASAR '24: Proceedings of the 2024 Workshop on Quantum Search and Information Retrieval Pages 1 - 8, 2024.

[5] Dominik Rusovac, Markus Hecher, Martin Gebser, S.A.G., Johannes K. Fichte. **Navigating and Querying Answer Sets: How Hard Is It Really and Why?** Proceedings of the 21st International Conference on Principles of Knowledge Representation and Reasoning (KR 2024).

Part 2 Diverse Answer Sets

Similar/Diverse Solutions in ASP [6]

Divers Answer Sets

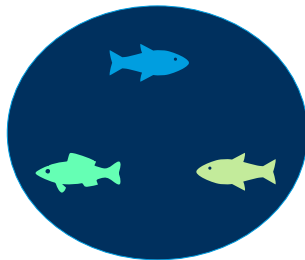
- n k-DIVERSE SOLUTIONS
- $n = |S|$, S ... collection of AS
- $\Delta(S) \geq k$
- $\Delta : 2^{AS} \rightarrow \mathbb{N}^0$

[6] Thomas Eiter, Esra Erdem, Halit Erdogan, Michael Fink: Finding similar/diverse solutions in answer set programming. Theory Pract. Log. Program. 13(3): 303-359 (2013)

Similar/Diverse Solutions in ASP [6]

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- $\Delta : 2^{AS} \rightarrow \mathbb{N}^0$
- default Δ : minimal pairwise hamming distance

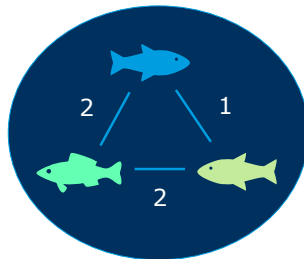


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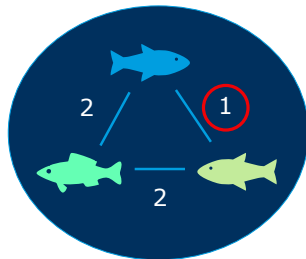


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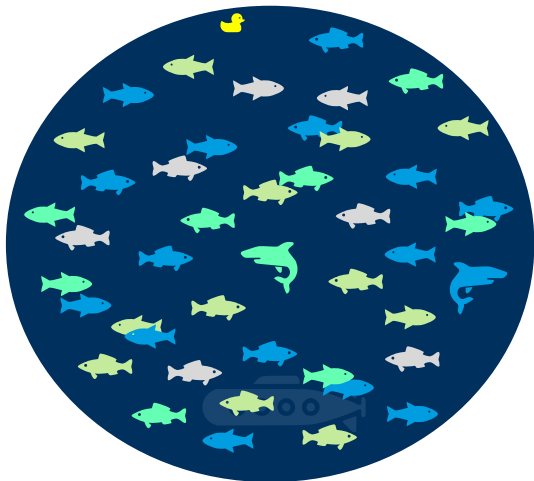
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Methods:

- enumeration and postprocessing
- parallel solving
- iterative solving

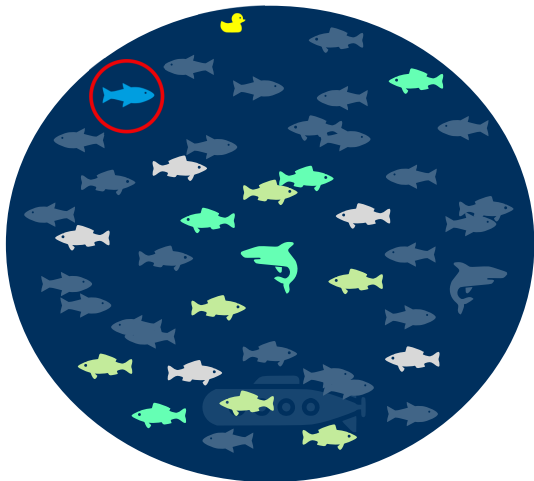
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Reworking Methods [7]



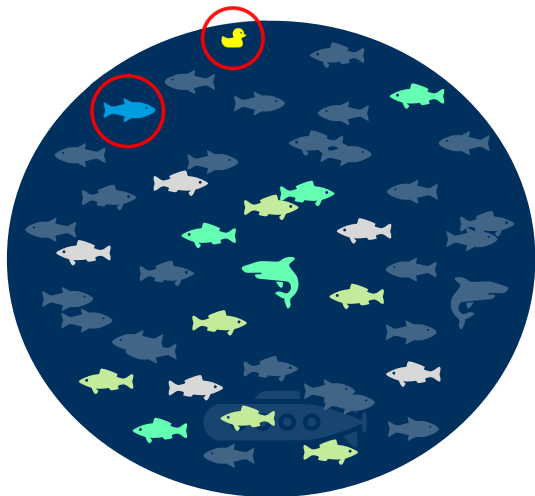
[7] Elisa Böhl, S.A.G. Tunas - **Fishing for Diverse Answer Sets: A Multi-Shot Trade up Strategy**; LPNMR 2022.

Reworking Methods [7]



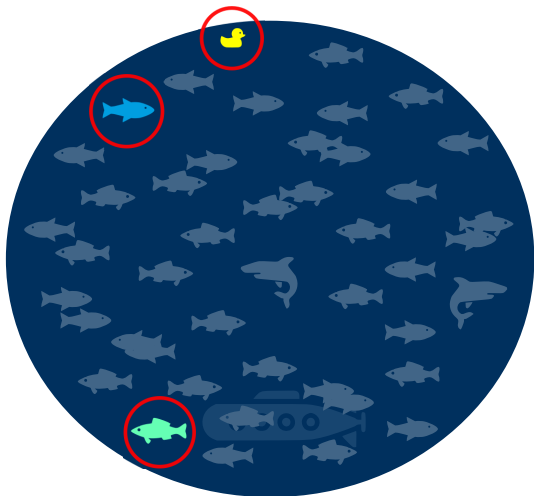
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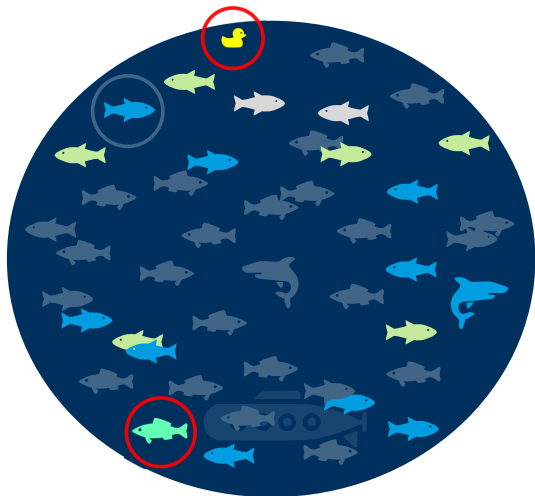
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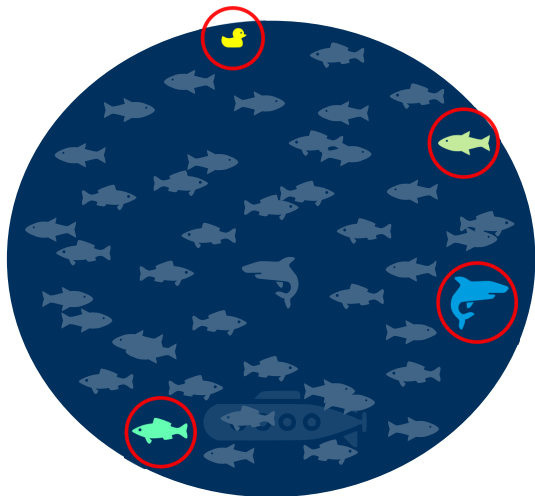
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Reworking Methods [7]

Problem Definition



collection S

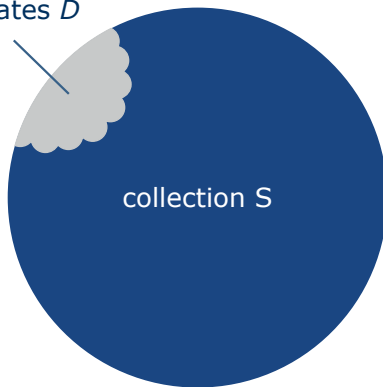
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Reworking Methods [7]

Problem Definition

$$- |S \setminus S'| \leq m$$

m deletion
candidates D



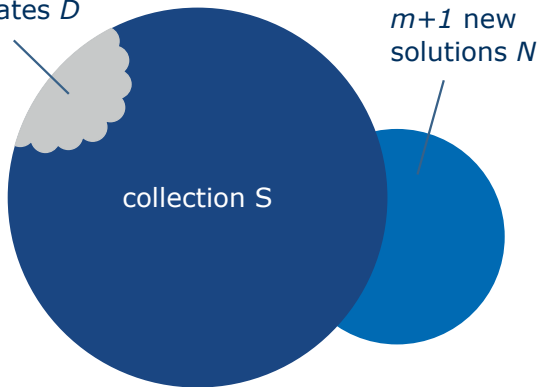
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Reworking Methods [7]

Problem Definition

- $|S'| > |S|$
- $|S \setminus S'| \leq m$

m deletion
candidates D



[7] Elisa Böhl, S.A.G. Tunas - **Fishing for Diverse Answer Sets: A Multi-Shot Trade up Strategy**; LPNMR 2022.

Reworking Methods [7]

Problem Definition

- $|S'| > |S|$
- $|S \setminus S'| \leq m$
- $\Delta(S') \geq k$
- NP-complete



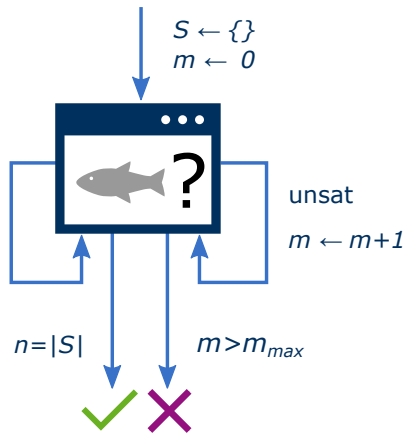
[7] Elisa Böhl, S.A.G. Tunas - **Fishing for Diverse Answer Sets: A Multi-Shot Trade up Strategy**; LPNMR 2022.

Tunas - Trade Up Navigation for Answer Sets

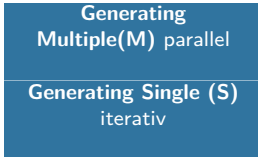
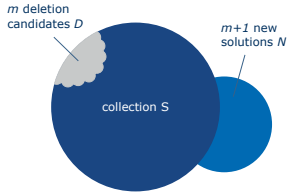
Properties

- comparatively fast
- anytime approach
- multi-shot
 - additive grounding
 - concealment and deletion of atoms
 - counting over changing domain

AS's N
Del.Can. D
 $S \leftarrow (S \setminus D) \cup N$
 $m \leftarrow 0$
Ground &
Release



Tunas - Elaborations



Nondeterministic Choosing (ND)	Iterative Choosing (IT)
<i>ASP</i> guesses deletion candidates	<i>wrapper</i> iterates over deletion candidates
TunasMND	TunasMIT
X	TunasS

Concluding on Diverse Answer Sets

- Diverse collections give a nice overview on the solutionspace
- Multi-shot ASP is good choice to iteratively improve collections
- User needs to specify diversity measure (and provide it as ASP encoding)

Part 3 Representative Answer Sets

Collecting Something of Everything

$\mathcal{AS}(\Pi_0)$:

$$s_1 = \{\blacksquare, \blacktriangle\}$$

$$s_2 = \{\bullet, \blacktriangle\}$$

$$s_3 = \{\blacklozenge, \blackcross\}$$

$$s_4 = \{\blacksquare, \blacklozenge\}$$

$$s_5 = \{\blackcross, \blacktriangledown, \blackplus\}$$

$$s_6 = \{\bullet, \blacktriangledown, \blackplus\}$$

$T = \{\text{at}(\Pi_0)\}$

Collecting Something of Everything

$\mathcal{AS}(\Pi_0)$:

$$s_1 = \{\blacksquare, \blacktriangle\}$$

$$s_2 = \{\bullet, \blacktriangle\}$$

$$s_3 = \{\blacklozenge, \blacktimes\}$$

$$s_4 = \{\blacksquare, \blacklozenge\}$$

$$s_5 = \{\blacktimes, \blacktriangledown, \blackplus\}$$

$$s_6 = \{\bullet, \blacktriangledown, \blackplus\}$$

$T = \{\text{at}(\Pi_0)\}$

– $S = \{s_1, s_2, s_4, s_5\}$ is sound over T ,

Collecting Something of Everything

$\mathcal{AS}(\Pi_0)$:

$$s_1 = \{\blacksquare, \blacktriangle\}$$

$$s_2 = \{\bullet, \blacktriangle\}$$

$$s_3 = \{\blacklozenge, \times\}$$

$$s_4 = \{\blacksquare, \blacklozenge\}$$

$$s_5 = \{\times, \blacktriangledown, \oplus\}$$

$$s_6 = \{\bullet, \blacktriangledown, \oplus\}$$

$T = \{\text{at}(\Pi_0)\}$

- $S = \{s_1, s_2, s_4, s_5\}$ is sound over T ,
- S is not a packing over T as atoms \blacktriangle and \blacksquare appear twice.

Collecting Something of Everything

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$$s_1 = \{\blacksquare, \blacktriangle\}$$

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$$s_6 = \{\bullet, \blacktriangledown, \blackplus\}$$

$T = \{\text{at}(\Pi_0)\}$

- $S = \{s_1, s_2, s_4, s_5\}$ is sound over T ,
- S is not a packing over T as atoms \blacktriangle and \blacksquare appear twice.
- By removing s_1 from S , we obtain a perfect collection over T .

Representative Collections [8]

- collection S : set of answer sets; target atoms T
- Soundness: all target atoms covered; $T \subseteq \cup S$
- Diversity: self information / Shannon entropy ¹, $p_S(a_i) = \frac{m_i}{\sum_{j=1}^n m_j}$, with m_i frequency of atom a_i :

$$H[T|S] := \sum_{a \in T} p_S(a) \log_2 \frac{1}{p_S(a)}$$

$$D(T|S) := 2^{H[T|S]} \in [0, |T|]$$

¹T. Leinster, 'Entropy and diversity: the axiomatic approach', Cambridge university press, 2021

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- normalisation into representativeness:

$$R(T|S) := \frac{D(T|S)}{|T|} \in [0, 1]$$

[8] Elisa Böhl, S.A.G, Dominik Rusovac. Representative Answer Sets: Collecting Something of Everything. Proceedings of the 26th European Conference on Artificial Intelligence (ECAI 2023), 271–278, September 2023.

¹T. Leinster, 'Entropy and diversity: the axiomatic approach', Cambridge university press, 2021

Example

$$s_1 = \{\blacksquare, \blacktriangle\}$$

$$s_4 = \{\blacksquare, \blacklozenge\}$$

$$s_2 = \{\bullet, \blacktriangle\}$$

$$s_5 = \{\blackcross, \blacktriangledown, \blackplus\}$$

$$s_3 = \{\blacklozenge, \blackcross\}$$

$$s_6 = \{\bullet, \blacktriangledown, \blackplus\}$$

$$T = \{\text{at}(\Pi_0)\}, S = \{s_1, s_2, s_4, s_5\}$$

$$S|_T^m = \{\blacklozenge^1, \blacksquare^2, \bullet^1, \blacktriangle^2, \blackcross^1, \blackplus^1, \blacktriangledown^1\}$$

$$p_S(a) : \frac{1}{9}, \frac{2}{9}, \frac{1}{9}, \frac{2}{9}, \frac{1}{9}, \frac{1}{9}, \frac{1}{9}$$

Entropy	$H[T S]$	$= \sum_{a \in T} p_S(a) \log_2 \frac{1}{p_S(a)}$	≈ 2.7165
Diversity	$D(T S)$	$= 2^{H[T S]}$	≈ 6.573
Representativeness	$R(T S)$	$= \frac{D(T S)}{ T }$	≈ 0.94

Example cont.

$$s_1 = \{\blacksquare, \blacktriangle\}$$

$$s_4 = \{\blacksquare, \blacklozenge\}$$

$$s_2 = \{\bullet, \blacktriangle\}$$

$$s_5 = \{\blackcross, \blacktriangledown, \blackplus\}$$

$$s_3 = \{\blacklozenge, \blackcross\}$$

$$s_6 = \{\bullet, \blacktriangledown, \blackplus\}$$

$$T = \{\text{at}(\Pi_0)\}, S' = \{s_2, s_4, s_5\}$$

$$S|_T^m = \{\blacklozenge^1, \blacksquare^1, \bullet^1, \blacktriangle^1, \blackcross^1, \blackplus^1, \blacktriangledown^1\}$$

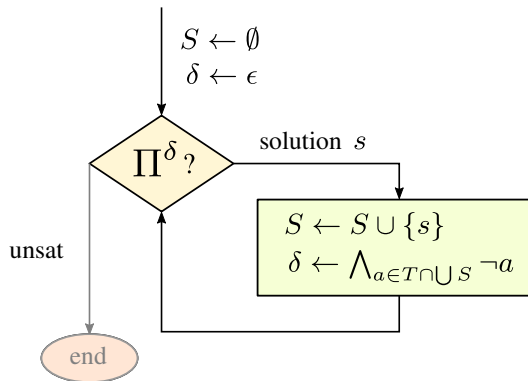
$$p_S(a) : \frac{1}{7}, \frac{1}{7}, \frac{1}{7}, \frac{1}{7}, \frac{1}{7}, \frac{1}{7}, \frac{1}{7} \text{ (uniform distribution)}$$

Entropy	$H[T S]$	$= \sum_{a \in T} p_S(a) \log_2 \frac{1}{p_S(a)}$	$= 7 \frac{1}{7} \log_2 7 = \log_2 7$
Diversity	$D(T S)$	$= 2^{H[T S]}$	$= 2^{\log_2 7} = 7$
Representativeness	$R(T S)$	$= \frac{D(T S)}{ T }$	$= \frac{7}{7} = 1$

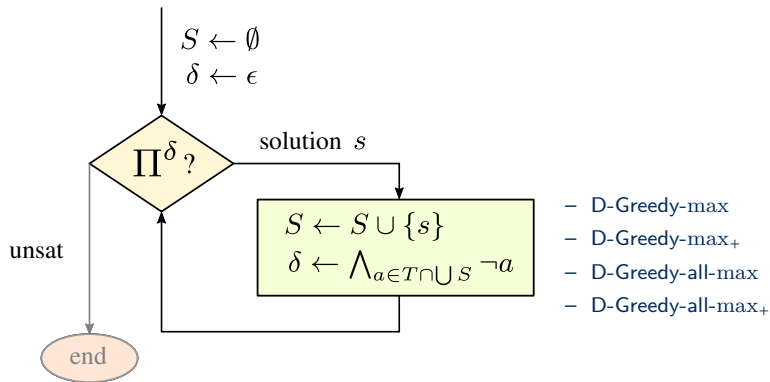
Obtaining Representative Collections

- Approach: Faceted Answer Set Navigation
 - activating a facet: propagation of a truth value
 - counting facets enables to measure uncertainty
- Algorithms: Greedy for diversity (D) and soundness (S)

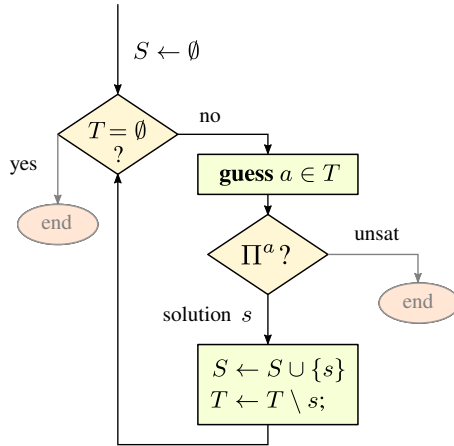
Algorithm: D-Greedy



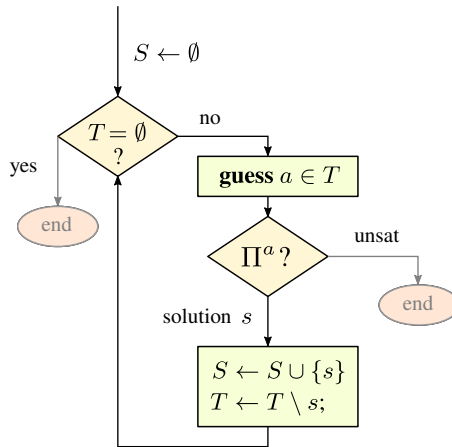
Algorithm: D-Greedy



Algorithm: S-Greedy



Algorithm: S-Greedy



- S-Greedy
- S-Greedy-Sieve
(search on route $V_{i=1} t_i$)

Concluding on Representative Collections

- Experiments showed, if quality of outcome matters, the more complex heuristics pay off (D-Greedy-all-max₊)
- Otherwise, less complex methods (S-Greedy-Sieve) are much faster → hybrid approach
- Entropy a reasonable measure for diversity of solutions

Part 4 Visual Approach for Solution Space Exploration

NEXAS: A Visual Tool for Navigating and Exploring Argumentation Solution Spaces [9]



[9] Raimund Dachsel, S.A.G., Markus Krötzsch, Julián Méndez, Dominik Rusovac, Mei Yang. **NEXAS: A Visual Tool for Navigating and Exploring Argumentation Solution Spaces**; COMMA 2022. <https://imld.de/nexas>

Visualization of AF Extensions

ConArg

Download Documentation Web Interface Rob People Benchmarks Contribution Publications

ID
LINK
stroke

Semiring

- Dung
- Fuzzy
- Weighted
- Probabilistic

Graph

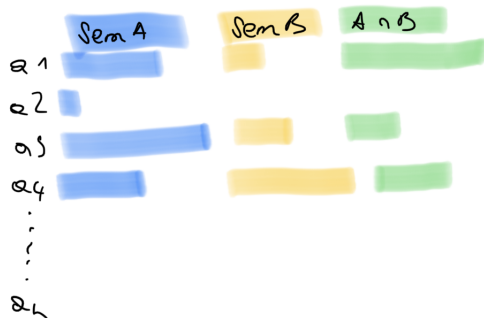
arg(a1).
arg(a2).
arg(a3).
arg(a4).
arg(a5).
arg(a6).
arg(a7).
arg(a8).

Output

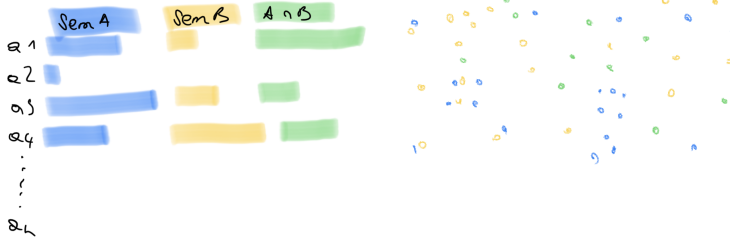
semantic: preferred enumerate

Last update: June 24, 2021 | contact: stefano.bistarelli@unipg.it

Use Case 1: Compare two semantics

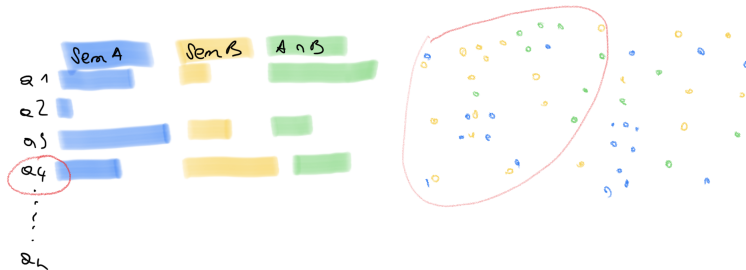


Use Case 1: Compare two semantics



Use Case 2: Very large solution space

Only compute particular sub-space of the whole solution space, where some arguments are either contained in all extensions or in none.



Use Case 3: Navigate towards desired solution sub-space

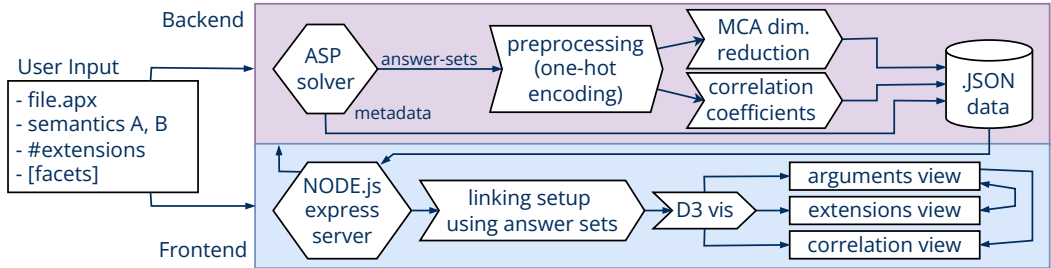
Show for which arguments one can zoom-in (arguments that are credulously but not skeptically accepted)



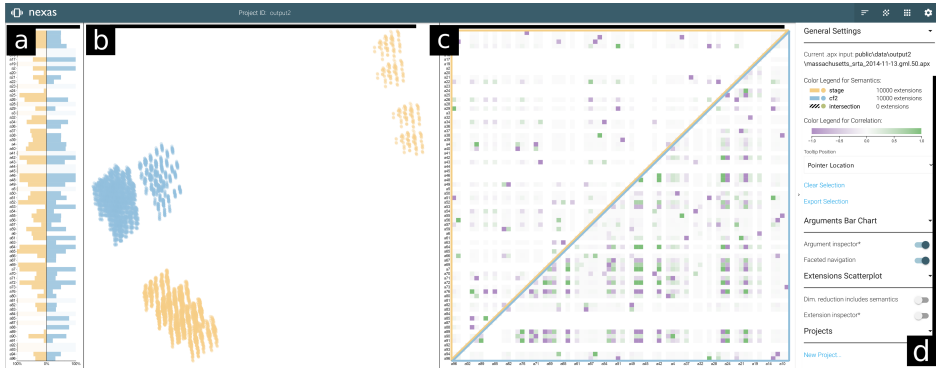
Design Goals

- DG-1: Intuitive and Familiar Representations.** We aim to foster intuitive understanding of the views by using traditional representations of the AF components while also encoding relevant information that the users can obtain insights from.
- DG-2: Highlight Component Relations.** A major challenge is to understand how components affect others. Thus, we aim to make these relations visible through linked interactions to foster understanding of the underlying framework.
- DG-3: Maintainable and Customizable.** The system design must be flexible and allow incorporation of further components in future iterations.
- DG-4: Support Several Tasks and Workflows.** We aim to support tasks with disjoint purposes and thus the available interactions must reflect such purposes.
- DG-5: Ready-to-use.** We aim to minimize setup complexity of the tool to account for various user environments.

Technical Design

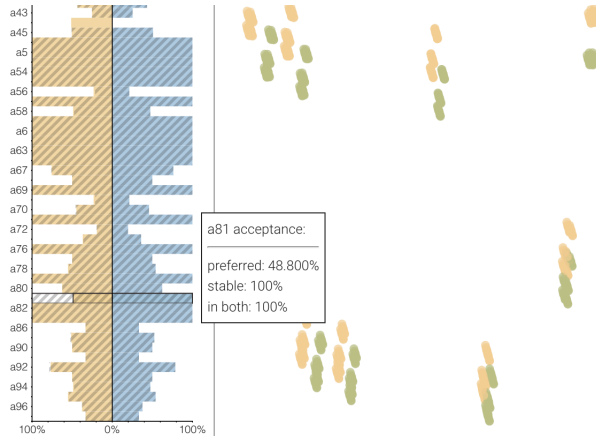


Visualization Design

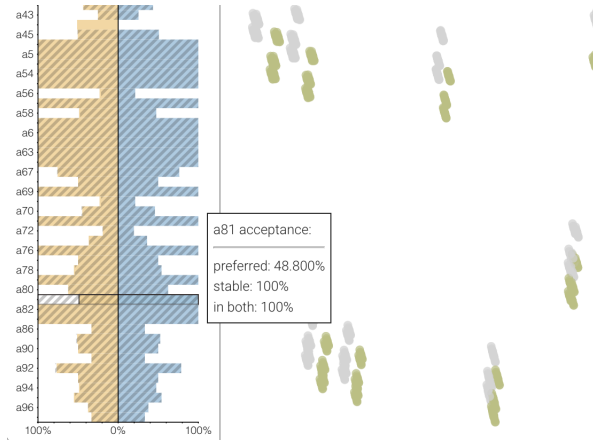


<https://imld.de/nexas>

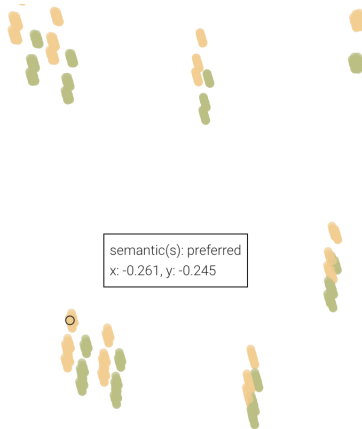
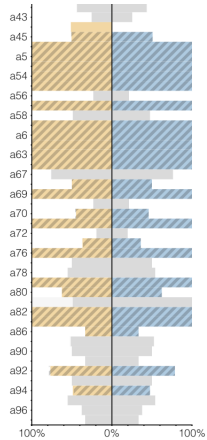
Argument View



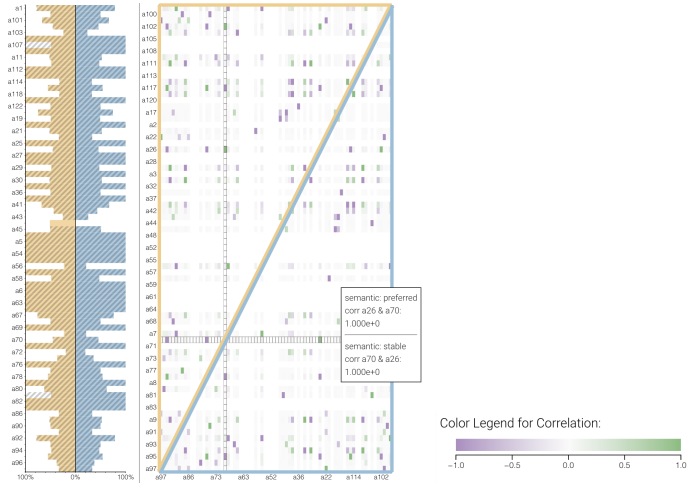
Argument View



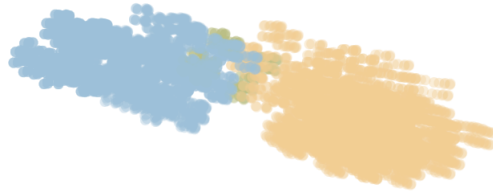
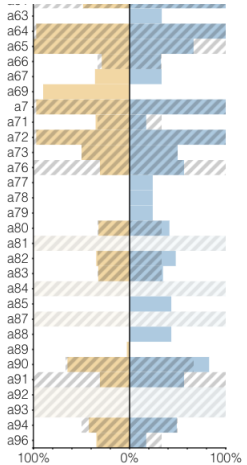
Extension View



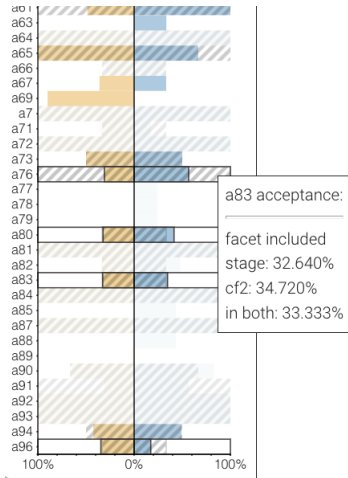
Correlation View



Faceted Navigation



Faceted Navigation



Sum up on Visualization

- Visual approach clearly supports solution space exploration
- Limits are in the representation of large solution spaces, if dimensional reduction should be used
- General: visual representation of large collections of sets is challenging

Summary & Future Work

Summary:

- Weighted faceted navigation allows to quantitatively explore the solution space
- Iterative reworking strategies to compute diverse answer sets
- Representative answer sets based on the concept of entropy
- Visual exploration of solution space

Future Work:

- Generalize to solution space navigation (not only for ASP relevant)
- Concrete applications
- Generalize visualization approach for answer sets

Thanks to all Collaborators



Elisa Böhl



Dominik Rusovac



Raimund Dachsel



Johannes Fichte



Markus Krötzsch



Julián Méndez

Thanks to our sponsors: BMBF (Grant 01IS20056_NAVAS), DFG (Grant TRR 248), FWF (Grant Y698)