

Hannes Strass

Faculty of Computer Science, Institute of Artificial Intelligence, Computational Logic Group

Counterfactual Regret Minimisation

Lecture 8, 10th Jun 2024 // Algorithmic Game Theory, SS 2024

Previously ...

- A **behaviour strategy** assigns move probabilities to information sets.
- A **belief system** assigns probabilities to histories in information sets.
- An **assessment** is a pair (behaviour strategy profile, belief system).
- A **sequentially rational** assessment plays best responses “everywhere”.
- An assessment satisfies **consistency of beliefs** whenever the belief system’s probabilities match what is expected from everyone playing according to the behaviour strategy profile.
- An assessment is a **weak sequential equilibrium** iff it is both sequentially rational and satisfies consistency of beliefs.
- Mixed Nash equilibria for normal-form games and subgame perfect equilibria for sequential perfect-information games are special cases of weak sequential equilibria for extensive-form games.

Motivation

Main Question

- How to algorithmically solve imperfect-information games ...
- ...or at least devise good strategies or play them well in practice?

Motivation

Main Question

- How to algorithmically solve imperfect-information games ...
- ...or at least devise good strategies or play them well in practice?

Transformation to Normal Form?

Incurs an **exponential blowup**:

For every player $i \in P$, there are up to $|M_i| \cdot |\{j_j \in J \mid p^{(j_j)} = i\}|$ many behaviour strategies (pure strategies in the normal-form game).

Motivation

Main Question

- How to algorithmically solve imperfect-information games ...
- ...or at least devise good strategies or play them well in practice?

Transformation to Normal Form?

Incurs an exponential blowup:

For every player $i \in P$, there are up to $|M_i| |\{ \mathcal{J}_j \in \mathcal{J} \mid p(\mathcal{J}_j)=i \}|$ many behaviour strategies (pure strategies in the normal-form game).

Algorithms for sequential (perfect-information) games?

- Player i 's best move in $\mathcal{J}_j \in \mathcal{J}$ depends on the player's beliefs $\beta_i: \mathcal{J}_j \rightarrow [0, 1]$.

Motivation

Main Question

- How to algorithmically solve imperfect-information games ...
- ...or at least devise good strategies or play them well in practice?

Transformation to Normal Form?

Incurs an exponential blowup:

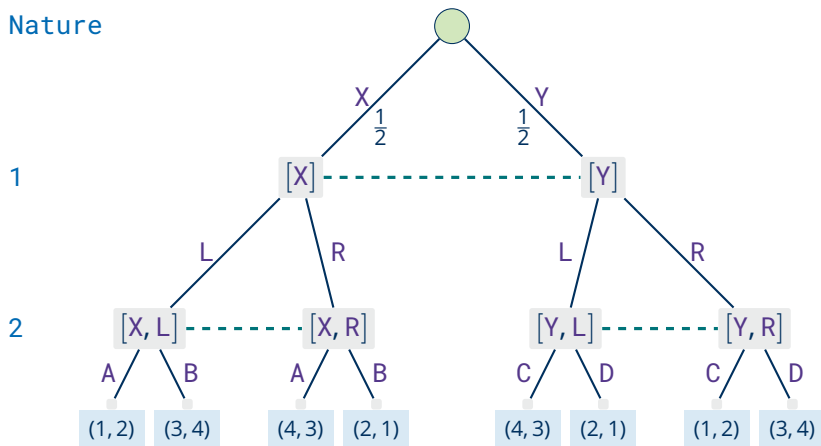
For every player $i \in P$, there are up to $|M_i| |\{ \mathcal{J}_j \in \mathcal{J} \mid p^{(\mathcal{J}_j)}=i \}|$ many behaviour strategies (pure strategies in the normal-form game).

Algorithms for sequential (perfect-information) games?

- Player i 's best move in $\mathcal{J}_j \in \mathcal{J}$ depends on the player's beliefs $\beta_i: \mathcal{J}_j \rightarrow [0, 1]$.
- Consistent beliefs about \mathcal{J}_j in turn depend (in general) on probabilities of moves in other information sets (even on other paths of play).

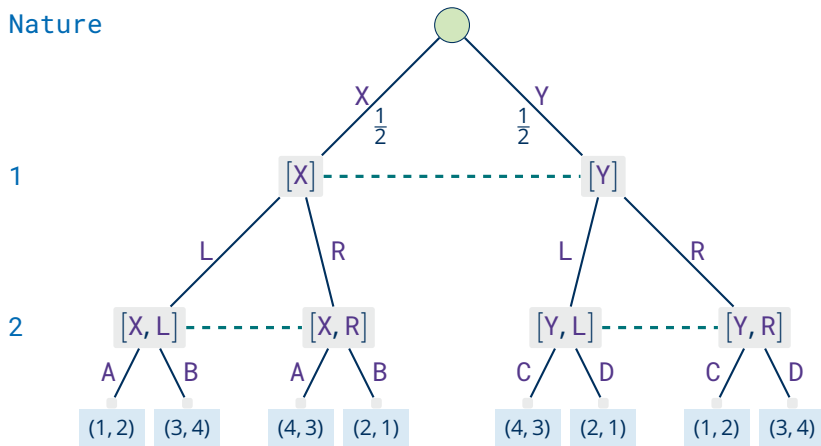
Motivation: Example

Nature



Motivation: Example

Nature



The best move for 2 in $\{[X, L], [X, R]\}$ depends on what 2 does in $\{[Y, L], [Y, R]\}$:
If 2 prefers C, then 1 will prefer L and thus 2 should prefer B. (Same for D and A.)

Motivation: Regret Matching

Before minimising regret in imperfect-information extensive-form games, we start with the simpler case of normal-form games ...

Motivation: Regret Matching

Before minimising regret in imperfect-information extensive-form games, we start with the simpler case of normal-form games ...

Recall

Let $(P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form, $i \in P$, and $s_j \in S_j$. The **regret** of i playing s_j w.r.t. opponent profile $\boldsymbol{\pi}_{-i}$ is

$$r_{\boldsymbol{\pi}_{-i}, s_j} := \left(\max_{\pi_k \in \Pi_i} U_i(\boldsymbol{\pi}_{-i}, \pi_k) \right) - U_i(\boldsymbol{\pi}_{-i}, s_j)$$

Motivation: Regret Matching

Before minimising regret in imperfect-information extensive-form games, we start with the simpler case of normal-form games ...

Recall

Let $(P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form, $i \in P$, and $s_j \in S_j$. The **regret** of i playing s_j w.r.t. opponent profile $\boldsymbol{\pi}_{-i}$ is

$$r_{\boldsymbol{\pi}_{-i}, s_j} := \left(\max_{\pi_k \in \Pi_i} U_i(\boldsymbol{\pi}_{-i}, \pi_k) \right) - U_i(\boldsymbol{\pi}_{-i}, s_j)$$

Difference between what player i could have had optimally vs. what they got.

Motivation: Regret Matching

Before minimising regret in imperfect-information extensive-form games, we start with the simpler case of normal-form games ...

Recall

Let $(P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form, $i \in P$, and $s_j \in S_j$. The **regret** of i playing s_j w.r.t. opponent profile $\boldsymbol{\pi}_{-i}$ is

$$r_{\boldsymbol{\pi}_{-i}, s_j} := \left(\max_{\pi_k \in \Pi_i} U_i(\boldsymbol{\pi}_{-i}, \pi_k) \right) - U_i(\boldsymbol{\pi}_{-i}, s_j)$$

Difference between what player i could have had optimally vs. what they got.

Regret is zero iff a best response is played.

Motivation: Regret Matching

Before minimising regret in imperfect-information extensive-form games, we start with the simpler case of normal-form games ...

Recall

Let $(P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form, $i \in P$, and $s_j \in S_j$. The **regret** of i playing s_j w.r.t. opponent profile $\boldsymbol{\pi}_{-i}$ is

$$r_{\boldsymbol{\pi}_{-i}, s_j} := \left(\max_{\pi_k \in \Pi_i} U_i(\boldsymbol{\pi}_{-i}, \pi_k) \right) - U_i(\boldsymbol{\pi}_{-i}, s_j)$$

Difference between what player i could have had optimally vs. what they got.
Regret is zero iff a best response is played.

↪ Minimise regret over time in order to approach playing best responses.

Overview

Correlated Equilibria

Regret Matching

Counterfactual Regret Minimisation

Correlated Equilibria

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.
- Another mixed Nash equilibrium is $\left(\left(\frac{100}{101}, \frac{1}{101} \right), \left(\frac{100}{101}, \frac{1}{101} \right) \right)$:

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.
- Another mixed Nash equilibrium is $\left(\left(\frac{100}{101}, \frac{1}{101} \right), \left(\frac{100}{101}, \frac{1}{101} \right) \right)$:
Both cars mostly stop and there is a positive probability of accidents.

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.
- Another mixed Nash equilibrium is $\left(\left(\frac{100}{101}, \frac{1}{101} \right), \left(\frac{100}{101}, \frac{1}{101} \right) \right)$:
Both cars mostly stop and there is a positive probability of accidents.
- A more desirable outcome would be: $\left\{ (\text{Stop, Go}) \mapsto \frac{1}{2}, (\text{Go, Stop}) \mapsto \frac{1}{2} \right\}$:

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.
- Another mixed Nash equilibrium is $\left(\left(\frac{100}{101}, \frac{1}{101} \right), \left(\frac{100}{101}, \frac{1}{101} \right) \right)$:
Both cars mostly stop and there is a positive probability of accidents.
- A more desirable outcome would be: $\left\{ (\text{Stop, Go}) \mapsto \frac{1}{2}, (\text{Go, Stop}) \mapsto \frac{1}{2} \right\}$:
However, mixed Nash equilibria cannot realise this.

Correlated Equilibria: Motivation

Traffic Lights

Two cars both want to cross an intersection. If a car stops, it does not get to the other side. If only one car goes, it gets to the other side. If both cars go, there is an accident.

| (Car1, Car2) | Stop | Go |
|--------------|-------|-------------|
| Stop | (0,0) | (0,1) |
| Go | (1,0) | (-100,-100) |

- The pure Nash equilibria are (Stop, Go) and (Go, Stop):
In both equilibria, one car never gets to move.
- Another mixed Nash equilibrium is $\left(\left(\frac{100}{101}, \frac{1}{101} \right), \left(\frac{100}{101}, \frac{1}{101} \right) \right)$:
Both cars mostly stop and there is a positive probability of accidents.
- A more desirable outcome would be: $\left\{ (\text{Stop, Go}) \mapsto \frac{1}{2}, (\text{Go, Stop}) \mapsto \frac{1}{2} \right\}$:
However, mixed Nash equilibria cannot realise this. **Traffic lights can!**

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.
- The distribution $\psi: \mathcal{S} \rightarrow [0, 1]$ for this is fixed and known to all players.

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.
- The distribution $\psi: \mathcal{S} \rightarrow [0, 1]$ for this is fixed and known to all players.
- For a chosen $(s_1, \dots, s_n) \in \mathcal{S}$, each player $i \in P$ gets **private** advice $s_i \in S_i$.

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.
- The distribution $\psi: \mathcal{S} \rightarrow [0, 1]$ for this is fixed and known to all players.
- For a chosen $(s_1, \dots, s_n) \in \mathcal{S}$, each player $i \in P$ gets private advice $s_i \in S_i$.
- Knowing $\{\mathbf{s} \in \mathcal{S} \mid \psi(\mathbf{s}) > 0\}$, player i may be able to infer advice of others.

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.
- The distribution $\psi: \mathcal{S} \rightarrow [0, 1]$ for this is fixed and known to all players.
- For a chosen $(s_1, \dots, s_n) \in \mathcal{S}$, each player $i \in P$ gets private advice $s_i \in S_i$.
- Knowing $\{\mathbf{s} \in \mathcal{S} \mid \psi(\mathbf{s}) > 0\}$, player i may be able to infer advice of others.
- Correlated equilibrium now means:
No player has an incentive to deviate from the signal's advice.

Correlated Equilibrium: Intuition

- An external device chooses a strategy profile $\mathbf{s} \in \mathcal{S}$ randomly.
- The distribution $\psi: \mathcal{S} \rightarrow [0, 1]$ for this is fixed and known to all players.
- For a chosen $(s_1, \dots, s_n) \in \mathcal{S}$, each player $i \in P$ gets private advice $s_i \in S_i$.
- Knowing $\{\mathbf{s} \in \mathcal{S} \mid \psi(\mathbf{s}) > 0\}$, player i may be able to infer advice of others.
- Correlated equilibrium now means:
No player has an incentive to deviate from the signal's advice.

Example

In the traffic lights game, assume $\psi = \left\{ (\text{Stop}, \text{Go}) \mapsto \frac{1}{2}, (\text{Go}, \text{Stop}) \mapsto \frac{1}{2}, \dots \right\}$:

- If **Car1** receives signal **Stop**, then it knows **Car2** must have received **Go**.
- Thus its best choice is to **Stop**.
- Symmetrically for **Car1** receiving signal **Go**, and **Car2**.

Correlated Equilibrium: Definition

Definition [Aumann, 1974]

Let $(P, \mathbf{S}, \mathbf{u})$ be a game in normal form with $P = \{1, \dots, n\}$.

A probability distribution ψ on $\mathcal{S} = S_1 \times \dots \times S_n$ is a **correlated equilibrium** iff for every $i \in P$, $s_j \in S_j$, and $s_k \in S_i$, we have

$$\sum_{\substack{\mathbf{s} \in \mathcal{S}, \\ \mathbf{s}_i = s_j}} \left(\psi(\mathbf{s}) \cdot \left(u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}) \right) \right) \leq 0$$

Roughly: Following the signal's advice incurs no (positive) regret.

Correlated Equilibrium: Definition

Definition [Aumann, 1974]

Let $(P, \mathbf{S}, \mathbf{u})$ be a game in normal form with $P = \{1, \dots, n\}$.

A probability distribution ψ on $\mathcal{S} = S_1 \times \dots \times S_n$ is a **correlated equilibrium** iff for every $i \in P$, $s_j \in S_j$, and $s_k \in S_i$, we have

$$\sum_{\substack{\mathbf{s} \in \mathcal{S}, \\ \mathbf{s}_j = s_j}} \left(\psi(\mathbf{s}) \cdot \left(u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}) \right) \right) \leq 0$$

Roughly: Following the signal's advice incurs no (positive) regret.

Observation

Every (mixed) Nash equilibrium $\boldsymbol{\pi} = (\pi_1, \dots, \pi_n)$ induces a correlated equilibrium $\psi_{\boldsymbol{\pi}} := \{(s_1, \dots, s_n) \mapsto \pi_1(s_1) \cdot \dots \cdot \pi_n(s_n) \mid (s_1, \dots, s_n) \in \mathcal{S}\}$.

Correlated Equilibrium: Definition

Definition [Aumann, 1974]

Let $(P, \mathbf{S}, \mathbf{u})$ be a game in normal form with $P = \{1, \dots, n\}$.

A probability distribution ψ on $\mathcal{S} = S_1 \times \dots \times S_n$ is a **correlated equilibrium** iff for every $i \in P$, $s_j \in S_j$, and $s_k \in S_i$, we have

$$\sum_{\substack{\mathbf{s} \in \mathcal{S}, \\ \mathbf{s}_i = s_j}} \left(\psi(\mathbf{s}) \cdot \left(u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}) \right) \right) \leq 0$$

Roughly: Following the signal's advice incurs no (positive) regret.

Observation

Every (mixed) Nash equilibrium $\boldsymbol{\pi} = (\pi_1, \dots, \pi_n)$ induces a correlated equilibrium $\psi_{\boldsymbol{\pi}} := \{(s_1, \dots, s_n) \mapsto \pi_1(s_1) \cdot \dots \cdot \pi_n(s_n) \mid (s_1, \dots, s_n) \in \mathcal{S}\}$.

Correlated: Players no longer mix their strategies independently.

Correlated Equilibrium: Example (1)

Battle of the Partners

Two partners, **Cat** and **Dee**, think about how to spend the evening. Each has their personal preference what to do, but overall they want to spend the evening together.

| (Cat, Dee) | Cinema | Dancing |
|------------|--------|---------|
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

Correlated Equilibrium: Example (1)

Battle of the Partners

Two partners, **Cat** and **Dee**, think about how to spend the evening. Each has their personal preference what to do, but overall they want to spend the evening together.

| (Cat, Dee) | Cinema | Dancing |
|------------|--------|---------|
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

For the mixed Nash equilibrium $\boldsymbol{\pi} = (\pi_{\text{Cat}}, \pi_{\text{Dee}}) = \left(\left(\frac{2}{3}, \frac{1}{3} \right), \left(\frac{1}{3}, \frac{2}{3} \right) \right)$

Correlated Equilibrium: Example (1)

Battle of the Partners

Two partners, **Cat** and **Dee**, think about how to spend the evening. Each has their personal preference what to do, but overall they want to spend the evening together.

| (Cat, Dee) | Cinema | Dancing |
|------------|--------|---------|
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

For the mixed Nash equilibrium $\pi = (\pi_{\text{Cat}}, \pi_{\text{Dee}}) = \left(\left(\frac{2}{3}, \frac{1}{3} \right), \left(\frac{1}{3}, \frac{2}{3} \right) \right)$, we get

$$\psi_{\pi} = \left\{ \begin{array}{l} (\text{Cinema}, \text{Cinema}) \mapsto \frac{2}{9}, (\text{Cinema}, \text{Dancing}) \mapsto \frac{4}{9}, \\ (\text{Dancing}, \text{Cinema}) \mapsto \frac{1}{9}, (\text{Dancing}, \text{Dancing}) \mapsto \frac{2}{9} \end{array} \right\}$$

with $U_{\text{Cat}}(\psi_{\pi}) = U_{\text{Dee}}(\psi_{\pi}) = 4\frac{2}{3}$.

Correlated Equilibrium: Example (2)

To verify that ψ_π is a correlated equilibrium, we have the following cases:

Correlated Equilibrium: Example (2)

To verify that ψ_π is a correlated equilibrium, we have the following cases:

- $i = \text{Cat}, s_j = \text{Cinema}, s_k = \text{Dancing}$:

$$\begin{aligned} & \psi(\text{Cinema}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Cinema}) - u_{\text{Cat}}(\text{Cinema}, \text{Cinema})) + \\ & \psi(\text{Cinema}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Dancing}) - u_{\text{Cat}}(\text{Cinema}, \text{Dancing})) = \\ & \frac{2}{9} \cdot (0 - 10) + \frac{4}{9} \cdot (7 - 2) = -\frac{20}{9} + \frac{20}{9} \leq 0 \end{aligned}$$

Correlated Equilibrium: Example (2)

To verify that ψ_π is a correlated equilibrium, we have the following cases:

- $i = \text{Cat}, s_j = \text{Cinema}, s_k = \text{Dancing}$:

$$\begin{aligned} & \psi(\text{Cinema}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Cinema}) - u_{\text{Cat}}(\text{Cinema}, \text{Cinema})) + \\ & \psi(\text{Cinema}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Dancing}) - u_{\text{Cat}}(\text{Cinema}, \text{Dancing})) = \\ & \frac{2}{9} \cdot (0 - 10) + \frac{4}{9} \cdot (7 - 2) = -\frac{20}{9} + \frac{20}{9} \leq 0 \end{aligned}$$

- $i = \text{Cat}, s_j = \text{Dancing}, s_k = \text{Cinema}$:

$$\begin{aligned} & \psi(\text{Dancing}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Cinema}, \text{Cinema}) - u_{\text{Cat}}(\text{Dancing}, \text{Cinema})) + \\ & \psi(\text{Dancing}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Cinema}, \text{Dancing}) - u_{\text{Cat}}(\text{Dancing}, \text{Dancing})) = \\ & \frac{1}{9} \cdot (10 - 0) + \frac{2}{9} \cdot (2 - 7) = \frac{10}{9} + \left(-\frac{10}{9}\right) \leq 0 \end{aligned}$$

Correlated Equilibrium: Example (2)

To verify that ψ_π is a correlated equilibrium, we have the following cases:

- $i = \text{Cat}, s_j = \text{Cinema}, s_k = \text{Dancing}$:

$$\begin{aligned} & \psi(\text{Cinema}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Cinema}) - u_{\text{Cat}}(\text{Cinema}, \text{Cinema})) + \\ & \psi(\text{Cinema}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Dancing}) - u_{\text{Cat}}(\text{Cinema}, \text{Dancing})) = \\ & \frac{2}{9} \cdot (0 - 10) + \frac{4}{9} \cdot (7 - 2) = -\frac{20}{9} + \frac{20}{9} \leq 0 \end{aligned}$$

- $i = \text{Cat}, s_j = \text{Dancing}, s_k = \text{Cinema}$:

$$\begin{aligned} & \psi(\text{Dancing}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Cinema}, \text{Cinema}) - u_{\text{Cat}}(\text{Dancing}, \text{Cinema})) + \\ & \psi(\text{Dancing}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Cinema}, \text{Dancing}) - u_{\text{Cat}}(\text{Dancing}, \text{Dancing})) = \\ & \frac{1}{9} \cdot (10 - 0) + \frac{2}{9} \cdot (2 - 7) = \frac{10}{9} + \left(-\frac{10}{9}\right) \leq 0 \end{aligned}$$

Due to $u_{\text{Dee}}(s_1, s_2) = u_{\text{Cat}}(s_2, s_1)$, this also covers the cases for $i = \text{Dee}$.

Correlated Equilibria: Example (3)

Assume that both **Cat** and **Dee** have access to the result of one fair coin toss:

- If the coin shows heads, both go to the concert;
- if the coin shows tails, both go to the cinema.

Correlated Equilibria: Example (3)

Assume that both **Cat** and **Dee** have access to the result of one fair coin toss:

- If the coin shows heads, both go to the concert;
- if the coin shows tails, both go to the cinema.

This leads to the following (additional) correlated equilibrium:

$$\psi = \left\{ (\text{Cinema, Cinema}) \mapsto \frac{1}{2}, (\text{Dancing, Dancing}) \mapsto \frac{1}{2}, \dots \right\}$$

Correlated Equilibria: Example (3)

Assume that both **Cat** and **Dee** have access to the result of one fair coin toss:

- If the coin shows heads, both go to the concert;
- if the coin shows tails, both go to the cinema.

This leads to the following (additional) correlated equilibrium:

$$\psi = \left\{ (\text{Cinema, Cinema}) \mapsto \frac{1}{2}, (\text{Dancing, Dancing}) \mapsto \frac{1}{2}, \dots \right\}$$

with associated payoffs $U_{\text{Cat}}(\psi) = U_{\text{Dee}}(\psi) = \frac{1}{2} \cdot 10 + \frac{1}{2} \cdot 7 = 8\frac{1}{2}$.

Correlated Equilibria: Example (3)

Assume that both **Cat** and **Dee** have access to the result of one fair coin toss:

- If the coin shows heads, both go to the concert;
- if the coin shows tails, both go to the cinema.

This leads to the following (additional) correlated equilibrium:

$$\psi = \left\{ (\text{Cinema}, \text{Cinema}) \mapsto \frac{1}{2}, (\text{Dancing}, \text{Dancing}) \mapsto \frac{1}{2}, \dots \right\}$$

with associated payoffs $U_{\text{Cat}}(\psi) = U_{\text{Dee}}(\psi) = \frac{1}{2} \cdot 10 + \frac{1}{2} \cdot 7 = 8\frac{1}{2}$.

To verify that ψ is a correlated equilibrium, we (essentially) verify that:

$$\begin{aligned} \psi(\text{Cinema}, \text{Cinema}) \cdot (u_{\text{Cat}}(\text{Dancing}, \text{Cinema}) - u_{\text{Cat}}(\text{Cinema}, \text{Cinema})) &\leq 0 \\ \psi(\text{Dancing}, \text{Dancing}) \cdot (u_{\text{Cat}}(\text{Cinema}, \text{Dancing}) - u_{\text{Cat}}(\text{Dancing}, \text{Dancing})) &\leq 0 \end{aligned}$$

which holds because $\frac{1}{2} \cdot (0 - 10) = -5 \leq 0$ and $\frac{1}{2} \cdot (2 - 7) = -2\frac{1}{2} \leq 0$.

Correlated Equilibria Form a Convex Set

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a strategic game in normal form.

For any two correlated equilibria ψ_1 and ψ_2 , and for any $\alpha \in [0, 1]$, we find that $\psi_\alpha := \{\mathbf{s} \mapsto \alpha \cdot \psi_1(\mathbf{s}) + (1 - \alpha) \cdot \psi_2(\mathbf{s}) \mid \mathbf{s} \in \mathcal{S}\}$ is a correlated equilibrium.

Correlated Equilibria Form a Convex Set

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a strategic game in normal form.

For any two correlated equilibria ψ_1 and ψ_2 , and for any $\alpha \in [0, 1]$, we find that $\psi_\alpha := \{\mathbf{s} \mapsto \alpha \cdot \psi_1(\mathbf{s}) + (1 - \alpha) \cdot \psi_2(\mathbf{s}) \mid \mathbf{s} \in \mathcal{S}\}$ is a correlated equilibrium.

Proof.

Let $\alpha \in [0, 1]$ and consider any $i \in P$, $s_j, s_k \in S_i$. We have

$$\begin{aligned} & \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} (\psi_\alpha(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}))) \\ &= \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} ((\alpha \cdot \psi_1(\mathbf{s}) + (1 - \alpha) \cdot \psi_2(\mathbf{s})) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}))) \\ &= \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} \left((\alpha \cdot \psi_1(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}))) + ((1 - \alpha) \cdot \psi_2(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s}))) \right) \\ &= \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} \left(\alpha \cdot \psi_1(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s})) \right) + \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} \left((1 - \alpha) \cdot \psi_2(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s})) \right) \\ &= \alpha \cdot \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} \left(\psi_1(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s})) \right) + (1 - \alpha) \cdot \sum_{\mathbf{s} \in \mathcal{S}, s_i = s_j} \left(\psi_2(\mathbf{s}) \cdot (u_i(s_k, \mathbf{s}_{-i}) - u_i(\mathbf{s})) \right) \leq 0 \quad \square \end{aligned}$$

Regret Matching

Learning to Play

Learning in Games: General Setting

- A (normal-form) game is played repeatedly for time points $t = 1, 2, \dots$
- After the game at time point t has ended, player (say) i has access to all strategy profiles $\mathbf{s}^1, \mathbf{s}^2, \dots, \mathbf{s}^t$ played previously, and their payoffs to i .
- Using this information, the player can devise a (mixed) strategy π_i^{t+1} to play at time point $t + 1$.

Learning to Play

Learning in Games: General Setting

- A (normal-form) game is played repeatedly for time points $t = 1, 2, \dots$
- After the game at time point t has ended, player (say) i has access to all strategy profiles $\mathbf{s}^1, \mathbf{s}^2, \dots, \mathbf{s}^t$ played previously, and their payoffs to i .
- Using this information, the player can devise a (mixed) strategy π_i^{t+1} to play at time point $t + 1$.

How can we evaluate whether a learner (player) is “doing well”?

Learning to Play

Learning in Games: General Setting

- A (normal-form) game is played repeatedly for time points $t = 1, 2, \dots$
- After the game at time point t has ended, player (say) i has access to all strategy profiles $\mathbf{s}^1, \mathbf{s}^2, \dots, \mathbf{s}^t$ played previously, and their payoffs to i .
- Using this information, the player can devise a (mixed) strategy π_i^{t+1} to play at time point $t + 1$.

How can we evaluate whether a learner (player) is “doing well”?

Hindsight Rationality

After playing the game for $t \rightarrow \infty$ time points, the player “cannot think of” a function $\Phi: \Pi_i \rightarrow \Pi_i$ that would strictly increase their payoff in hindsight.

Learning to Play

Learning in Games: General Setting

- A (normal-form) game is played repeatedly for time points $t = 1, 2, \dots$
- After the game at time point t has ended, player (say) i has access to all strategy profiles $\mathbf{s}^1, \mathbf{s}^2, \dots, \mathbf{s}^t$ played previously, and their payoffs to i .
- Using this information, the player can devise a (mixed) strategy π_i^{t+1} to play at time point $t + 1$.

How can we evaluate whether a learner (player) is “doing well”?

Hindsight Rationality

After playing the game for $t \rightarrow \infty$ time points, the player “cannot think of” a function $\Phi: \Pi_i \rightarrow \Pi_i$ that would strictly increase their payoff in hindsight.

Can **learning** (dynamic, local) lead to **equilibria** (static, global)?

Regret Matching

In what follows, we assume a fixed normal-form game $G = (P, \mathbf{S}, \mathbf{u})$ to be played at time points $t = 1, 2, \dots, T$ and take the perspective of $i \in P$.

Regret Matching

In what follows, we assume a fixed normal-form game $G = (P, \mathbf{S}, \mathbf{u})$ to be played at time points $t = 1, 2, \dots, T$ and take the perspective of $i \in P$.

At each time step $t \leq T$, i 's one-time regret of not having played $s_k \in S_i$ is:

$$r_i^t(s_k) := u_i(s_k, \mathbf{s}_{-i}^t) - u_i(\mathbf{s}^t)$$

Regret Matching

In what follows, we assume a fixed normal-form game $G = (P, \mathbf{S}, \mathbf{u})$ to be played at time points $t = 1, 2, \dots, T$ and take the perspective of $i \in P$.

At each time step $t \leq T$, i 's one-time regret of not having played $s_k \in S_i$ is:

$$r_i^t(s_k) := u_i(s_k, \mathbf{s}_{-i}^t) - u_i(\mathbf{s}^t)$$

At time point T , the accumulated regret of a strategy $s_k \in S_i$ is thus:

$$R_i^T(s_k) := \sum_{1 \leq t \leq T} r_i^t(s_k)$$

Regret Matching

In what follows, we assume a fixed normal-form game $G = (P, \mathbf{S}, \mathbf{u})$ to be played at time points $t = 1, 2, \dots, T$ and take the perspective of $i \in P$.

At each time step $t \leq T$, i 's one-time regret of not having played $s_k \in S_i$ is:

$$r_i^t(s_k) := u_i(s_k, \mathbf{s}_{-i}^t) - u_i(\mathbf{s}^t)$$

At time point T , the accumulated regret of a strategy $s_k \in S_i$ is thus:

$$R_i^T(s_k) := \sum_{1 \leq t \leq T} r_i^t(s_k)$$

The probabilities at $T + 1$ are then set to be proportional to **positive** regret:

$$\pi_i^{T+1}(s_j) := \begin{cases} \frac{[R_i^T(s_j)]^+}{R_i^{T,+}} & \text{if } R_i^{T,+} > 0, \quad \text{where } R_i^{T,+} := \sum_{s_k \in S_i} [R_i^T(s_k)]^+, \\ \frac{1}{|S_i|} & \text{otherwise.} \end{cases} \quad \text{for } s_j \in S_i$$

($[x]^+ := \max\{x, 0\}$ for all $x \in \mathbb{R}$.)

Regret Matching

In what follows, we assume a fixed normal-form game $G = (P, \mathbf{S}, \mathbf{u})$ to be played at time points $t = 1, 2, \dots, T$ and take the perspective of $i \in P$.

At each time step $t \leq T$, i 's one-time regret of not having played $s_k \in S_i$ is:

$$r_i^t(s_k) := u_i(s_k, \mathbf{s}_{-i}^t) - u_i(\mathbf{s}^t)$$

At time point T , the accumulated regret of a strategy $s_k \in S_i$ is thus:

$$R_i^T(s_k) := \sum_{1 \leq t \leq T} r_i^t(s_k)$$

The probabilities at $T + 1$ are then set to be proportional to **positive** regret:

$$\pi_i^{T+1}(s_j) := \begin{cases} \frac{[R_i^T(s_j)]^+}{R_i^{T,+}} & \text{if } R_i^{T,+} > 0, \quad \text{where } R_i^{T,+} := \sum_{s_k \in S_i} [R_i^T(s_k)]^+, \\ \frac{1}{|S_i|} & \text{otherwise.} \end{cases} \quad \text{for } s_j \in S_i$$

($[x]^+ := \max\{x, 0\}$ for all $x \in \mathbb{R}$.)

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| | | | | | |
|-----|---|---|-----------------------------------|------------------------------------|--------------------------|
| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|--------------------------|

Regret Matching: Example

| (Cat, Dee) | Cinema | Dancing |
|------------|--------|---------|
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 2 | (Dancing, Cinema) | 10 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 2 | (Dancing, Cinema) | 10 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |
| 3 | (Cinema, Dancing) | 5 | 10 | 10 | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 2 | (Dancing, Cinema) | 10 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |
| 3 | (Cinema, Dancing) | 5 | 10 | 10 | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Cinema, Cinema) | -10 | 10 | 0 | {Cinema \mapsto 1, Dancing \mapsto 0} |

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 2 | (Dancing, Cinema) | 10 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |
| 3 | (Cinema, Dancing) | 5 | 10 | 10 | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Cinema, Cinema) | -10 | 10 | 0 | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 5 | (Cinema, Dancing) | 5 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |

Regret Matching: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $\overline{\text{Cinema}} = \text{Dancing}$ and $\overline{\text{Dancing}} = \text{Cinema}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | $r_{\text{Cat}}^T(\overline{s_{\text{Cat}}^T})$ | $R_{\text{Cat}}^T(\text{Cinema})$ | $R_{\text{Cat}}^T(\text{Dancing})$ | π_{Cat}^{T+1} |
|-----|---|---|-----------------------------------|------------------------------------|---|
| 1 | (Cinema, Dancing) | 5 | 0 | 5 | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 2 | (Dancing, Cinema) | 10 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |
| 3 | (Cinema, Dancing) | 5 | 10 | 10 | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Cinema, Cinema) | -10 | 10 | 0 | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 5 | (Cinema, Dancing) | 5 | 10 | 5 | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } |
| 6 | (Cinema, Cinema) | -10 | 10 | -5 | {Cinema \mapsto 1, Dancing \mapsto 0} |

Regret Matching: Correctness

For a given play sequence $(\mathbf{s}^t)_{t=1}^T$, and every $\mathbf{s}' \in \mathcal{S}$, define the **relative frequency** of \mathbf{s}' after T rounds via

$$\bar{\varphi}^T(\mathbf{s}') := \frac{1}{T} \cdot |\{1 \leq t \leq T \mid \mathbf{s}^t = \mathbf{s}'\}|$$

Theorem [Hart and Mas-Colell, 2000]

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form.

If every player plays according to regret matching, then $(\bar{\varphi}^t)_{t=1}^T$ converges to the set of correlated equilibria of G as $T \rightarrow \infty$.

Regret Matching: Correctness

For a given play sequence $(\mathbf{s}^t)_{t=1}^T$, and every $\mathbf{s}' \in \mathcal{S}$, define the **relative frequency** of \mathbf{s}' after T rounds via

$$\bar{\varphi}^T(\mathbf{s}') := \frac{1}{T} \cdot |\{1 \leq t \leq T \mid \mathbf{s}^t = \mathbf{s}'\}|$$

Theorem [Hart and Mas-Colell, 2000]

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form.

If every player plays according to regret matching, then $(\bar{\varphi}^t)_{t=1}^T$ converges to the set of correlated equilibria of G as $T \rightarrow \infty$.

More precisely: For any $\varepsilon > 0$, there is a $T_0 \geq 0$ such that for all $T > T_0$, there is a correlated equilibrium ψ_T of G whose distance from $\bar{\varphi}^T$ is at most ε .

Regret Matching: Correctness

For a given play sequence $(\mathbf{s}^t)_{t=1}^T$, and every $\mathbf{s}' \in \mathcal{S}$, define the **relative frequency** of \mathbf{s}' after T rounds via

$$\bar{\varphi}^T(\mathbf{s}') := \frac{1}{T} \cdot |\{1 \leq t \leq T \mid \mathbf{s}^t = \mathbf{s}'\}|$$

Theorem [Hart and Mas-Colell, 2000]

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form.

If every player plays according to regret matching, then $(\bar{\varphi}^t)_{t=1}^T$ converges to the set of correlated equilibria of G as $T \rightarrow \infty$.

More precisely: For any $\varepsilon > 0$, there is a $T_0 \geq 0$ such that for all $T > T_0$, there is a correlated equilibrium ψ_T of G whose distance from $\bar{\varphi}^T$ is at most ε .

Note: The result does not say that relative frequencies converge to a *point*.

Regret Matching: Correctness

For a given play sequence $(\mathbf{s}^t)_{t=1}^T$, and every $\mathbf{s}' \in \mathcal{S}$, define the **relative frequency** of \mathbf{s}' after T rounds via

$$\bar{\varphi}^T(\mathbf{s}') := \frac{1}{T} \cdot |\{1 \leq t \leq T \mid \mathbf{s}^t = \mathbf{s}'\}|$$

Theorem [Hart and Mas-Colell, 2000]

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a noncooperative game in normal form.

If every player plays according to regret matching, then $(\bar{\varphi}^t)_{t=1}^T$ converges to the set of correlated equilibria of G as $T \rightarrow \infty$.

More precisely: For any $\varepsilon > 0$, there is a $T_0 \geq 0$ such that for all $T > T_0$, there is a correlated equilibrium ψ_T of G whose distance from $\bar{\varphi}^T$ is at most ε .

Note: The result does not say that relative frequencies converge to a *point*.

↪ Since all players must use regret matching, it will be used in **self-play**.

Regret Matching in Self-Play: Example

| (Cat, Dee) | Cinema | Dancing |
|------------|--------|---------|
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| | | | | | |
|-----|---|--------------------|--------------------|--------------------------|--------------------------|
| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|--------------------------|--------------------------|

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 3 | (Cinema, Dancing) | (10,10) | (10,10) | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 3 | (Cinema, Dancing) | (10,10) | (10,10) | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Dancing, Dancing) | (5,10) | (0,10) | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } | {Cinema \mapsto 0, Dancing \mapsto 1} |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 3 | (Cinema, Dancing) | (10,10) | (10,10) | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Dancing, Dancing) | (5,10) | (0,10) | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 5 | (Cinema, Dancing) | (5,15) | (5,10) | {Cinema \mapsto $\frac{1}{4}$, Dancing \mapsto $\frac{3}{4}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 3 | (Cinema, Dancing) | (10,10) | (10,10) | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Dancing, Dancing) | (5,10) | (0,10) | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 5 | (Cinema, Dancing) | (5,15) | (5,10) | {Cinema \mapsto $\frac{1}{4}$, Dancing \mapsto $\frac{3}{4}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 6 | (Dancing, Dancing) | (0,15) | (-5,10) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 0, Dancing \mapsto 1} |

Regret Matching in Self-Play: Example

| | | |
|------------|--------|---------|
| (Cat, Dee) | Cinema | Dancing |
| Cinema | (10,7) | (2,2) |
| Dancing | (0,0) | (7,10) |

We denote $R_i^T = (R_i^T(\text{Cinema}), R_i^T(\text{Dancing}))$ for $i \in \{\text{Cat}, \text{Dee}\}$.

| T | $\mathbf{s}^T = (s_{\text{Cat}}^T, s_{\text{Dee}}^T)$ | R_{Cat}^T | R_{Dee}^T | π_{Cat}^{T+1} | π_{Dee}^{T+1} |
|-----|---|--------------------|--------------------|---|---|
| 1 | (Cinema, Dancing) | (0,5) | (5,0) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 1, Dancing \mapsto 0} |
| 2 | (Dancing, Cinema) | (10,5) | (5,10) | {Cinema \mapsto $\frac{2}{3}$, Dancing \mapsto $\frac{1}{3}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 3 | (Cinema, Dancing) | (10,10) | (10,10) | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } | {Cinema \mapsto $\frac{1}{2}$, Dancing \mapsto $\frac{1}{2}$ } |
| 4 | (Dancing, Dancing) | (5,10) | (0,10) | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 5 | (Cinema, Dancing) | (5,15) | (5,10) | {Cinema \mapsto $\frac{1}{4}$, Dancing \mapsto $\frac{3}{4}$ } | {Cinema \mapsto $\frac{1}{3}$, Dancing \mapsto $\frac{2}{3}$ } |
| 6 | (Dancing, Dancing) | (0,15) | (-5,10) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 0, Dancing \mapsto 1} |
| 7 | (Dancing, Dancing) | (-5,15) | (-15,10) | {Cinema \mapsto 0, Dancing \mapsto 1} | {Cinema \mapsto 0, Dancing \mapsto 1} |

Rate of Convergence

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the (external) **overall regret** of player $i \in P$ after T rounds via

$$R_i^T := \max_{\hat{\boldsymbol{\pi}}_i \in \Pi_i} \left\{ \sum_{t=1}^T (U_i(\hat{\boldsymbol{\pi}}_i, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}_i^t, \boldsymbol{\pi}_{-i}^t)) \right\}$$

Rate of Convergence

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the (external) **overall regret** of player $i \in P$ after T rounds via

$$R_i^T := \max_{\hat{\boldsymbol{\pi}}_i \in \Pi_i} \left\{ \sum_{t=1}^T (U_i(\hat{\boldsymbol{\pi}}_i, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}_i^t, \boldsymbol{\pi}_{-i}^t)) \right\}$$

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a normal-form game and let player $i \in P$ use regret matching in the sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles.

Then $R_i^T \leq \omega \cdot \sqrt{T}$, where the constant $\omega \in \mathbb{R}$ depends only on \mathbf{u} .

Rate of Convergence

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the (external) **overall regret** of player $i \in P$ after T rounds via

$$R_i^T := \max_{\hat{\boldsymbol{\pi}} \in \Pi_i} \left\{ \sum_{t=1}^T (U_i(\hat{\boldsymbol{\pi}}, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}_i^t, \boldsymbol{\pi}_{-i}^t)) \right\}$$

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a normal-form game and let player $i \in P$ use regret matching in the sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles.

Then $R_i^T \leq \omega \cdot \sqrt{T}$, where the constant $\omega \in \mathbb{R}$ depends only on \mathbf{u} .

The **average overall regret** is then $\bar{R}_i^T := \frac{1}{T} \cdot R_i^T$.

Rate of Convergence

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the (external) **overall regret** of player $i \in P$ after T rounds via

$$R_i^T := \max_{\hat{\boldsymbol{\pi}}_i \in \Pi_i} \left\{ \sum_{t=1}^T (U_i(\hat{\boldsymbol{\pi}}_t, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}_i^t, \boldsymbol{\pi}_{-i}^t)) \right\}$$

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a normal-form game and let player $i \in P$ use regret matching in the sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles.

Then $R_i^T \leq \omega \cdot \sqrt{T}$, where the constant $\omega \in \mathbb{R}$ depends only on \mathbf{u} .

The **average overall regret** is then $\bar{R}_i^T := \frac{1}{T} \cdot R_i^T$.

Proposition

\bar{R}_i^T tends to zero as $T \rightarrow \infty$ iff $\bar{\boldsymbol{\varphi}}^T$ tends to the set of correlated equilibria.

The Case of Two-Player Zero-Sum Games

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the **average mixed strategy** $\bar{\pi}_i^T$ of player $i \in P$ after T rounds via

$$\bar{\pi}_i^T(s_j) := \frac{1}{T} \cdot \sum_{t=1}^T \pi_i^t(s_j) \quad \text{for } s_j \in S_i$$

The Case of Two-Player Zero-Sum Games

For a given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of mixed-strategy profiles, define the **average mixed strategy** $\bar{\pi}_i^T$ of player $i \in P$ after T rounds via

$$\bar{\pi}_i^T(s_j) := \frac{1}{T} \cdot \sum_{t=1}^T \pi_i^t(s_j) \quad \text{for } s_j \in S_i$$

Theorem

Let $G = (P, \mathbf{S}, \mathbf{u})$ be a **two-player, zero-sum** normal-form game, i.e. $P = \{1, 2\}$, and let $(\boldsymbol{\pi}^t)_{t=1}^T$ be obtained from both players using regret matching. Then as $T \rightarrow \infty$, the pair $(\bar{\pi}_1^T, \bar{\pi}_2^T)$ converges to the set of **Nash equilibria** of G .

Regret Matching⁺

The computation of the accumulated (possibly negative) regret of a strategy $s_k \in S_i$ can be rewritten as:

$$R_i^T(s_k) := R_i^{T-1}(s_k) + r_i^T(s_k) \quad \text{with } R_i^0(s_k) := 0$$

Regret Matching⁺

The computation of the accumulated (possibly negative) regret of a strategy $s_k \in S_i$ can be rewritten as:

$$R_i^T(s_k) := R_i^{T-1}(s_k) + r_i^T(s_k) \quad \text{with } R_i^0(s_k) := 0$$

Tammelin [2014] observed a better convergence when this is replaced by

$$R_i^{T,+}(s_k) := \left[R_i^{T-1}(s_k) \right]^+ + r_i^T(s_k)$$

Regret Matching⁺

The computation of the accumulated (possibly negative) regret of a strategy $s_k \in S_i$ can be rewritten as:

$$R_i^T(s_k) := R_i^{T-1}(s_k) + r_i^T(s_k) \quad \text{with } R_i^0(s_k) := 0$$

Tammelin [2014] observed a better convergence when this is replaced by

$$R_i^{T,+}(s_k) := \left[R_i^{T-1}(s_k) \right]^+ + r_i^T(s_k)$$

The probabilities at $T + 1$ are again set to be proportional to positive regret:

$$\pi_i^{T+1}(s_j) := \begin{cases} \frac{R_i^{T,+}(s_j)}{R_i^{T,+}} & \text{if } R_i^{T,+} > 0, \quad \text{where } R_i^{T,+} := \sum_{s_k \in S_i} R_i^{T,+}(s_k), \\ \frac{1}{|S_i|} & \text{otherwise.} \end{cases} \quad \text{for } s_j \in S_i$$

Regret Matching⁺

The computation of the accumulated (possibly negative) regret of a strategy $s_k \in S_i$ can be rewritten as:

$$R_i^T(s_k) := R_i^{T-1}(s_k) + r_i^T(s_k) \quad \text{with } R_i^0(s_k) := 0$$

Tammelin [2014] observed a better convergence when this is replaced by

$$R_i^{T,+}(s_k) := \left[R_i^{T-1}(s_k) \right]^+ + r_i^T(s_k)$$

The probabilities at $T + 1$ are again set to be proportional to positive regret:

$$\pi_i^{T+1}(s_j) := \begin{cases} \frac{R_i^{T,+}(s_j)}{R_i^{T,+}} & \text{if } R_i^{T,+} > 0, \quad \text{where } R_i^{T,+} := \sum_{s_k \in S_i} R_i^{T,+}(s_k), \\ \frac{1}{|S_i|} & \text{otherwise.} \end{cases} \quad \text{for } s_j \in S_i$$

RM⁺ reacts more quickly when a previously poor action improves over time.

Counterfactual Regret Minimisation

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

Solution of Zinkevich, Johanson, Bowling, and Piccione [2007]

- Define new notion of **counterfactual regret**:
Assume the player played to deliberately reach a certain information set.

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

Solution of Zinkevich, Johanson, Bowling, and Piccione [2007]

- Define new notion of **counterfactual regret**:
Assume the player played to deliberately reach a certain information set.
- Then for **games with perfect recall**:

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

Solution of Zinkevich, Johanson, Bowling, and Piccione [2007]

- Define new notion of **counterfactual regret**:
Assume the player played to deliberately reach a certain information set.
- Then for **games with perfect recall**:
 - Regret matching can be applied to each information set independently.

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

Solution of Zinkevich, Johanson, Bowling, and Piccione [2007]

- Define new notion of **counterfactual regret**:
Assume the player played to deliberately reach a certain information set.
- Then for **games with perfect recall**:
 - Regret matching can be applied to each information set independently.
 - Counterfactual regret is an upper bound for actual regret (main theorem).

From Normal Form to Extensive Form

Solving Imperfect-Information Games: Main Ideas

- Traverse the game tree in a backward induction-like fashion.
- Apply regret matching at each decision point (information set).

Problem

Optimal moves depend on probabilities of moves in other information sets.

Solution of Zinkevich, Johanson, Bowling, and Piccione [2007]

- Define new notion of **counterfactual regret**:
Assume the player played to deliberately reach a certain information set.
- Then for **games with perfect recall**:
 - Regret matching can be applied to each information set independently.
 - Counterfactual regret is an upper bound for actual regret (main theorem).
 - Thus minimising counterfactual regret minimises actual regret.

Remember, Remember

Recall

$P(h' | h, \boldsymbol{\pi})$ is the probability that h' is reached when playing $\boldsymbol{\pi}$ from h on:

- $P(h | h, \boldsymbol{\pi}) = 1$ for all $h \in H$,
- $P(\square | h, \boldsymbol{\pi}) = 0$ for all $h \neq \square$, and
- $P([h'; m] | h, \boldsymbol{\pi}) = \pi_{p(\mathcal{J}_{h'})}(m | \mathcal{J}_{h'}) \cdot P(h' | h, \boldsymbol{\pi})$.

Remember, Remember

Recall

$P(h' | h, \pi)$ is the probability that h' is reached when playing π from h on:

- $P(h | h, \pi) = 1$ for all $h \in H$,
- $P(\square | h, \pi) = 0$ for all $h \neq \square$, and
- $P([h'; m] | h, \pi) = \pi_{p(\mathcal{J}_{h'})}(m | \mathcal{J}_{h'}) \cdot P(h' | h, \pi)$.

Recall

The probability of reaching information set \mathcal{J}_j when playing π is thus

$$P(\mathcal{J}_j | \pi) := \sum_{h \in \mathcal{J}_j} P(h | \pi) \quad \text{where } P(h | \pi) \text{ denotes } P(h | \square, \pi)$$

Remember, Remember

Recall

$P(h' | h, \boldsymbol{\pi})$ is the probability that h' is reached when playing $\boldsymbol{\pi}$ from h on:

- $P(h | h, \boldsymbol{\pi}) = 1$ for all $h \in H$,
- $P(\square | h, \boldsymbol{\pi}) = 0$ for all $h \neq \square$, and
- $P([h'; m] | h, \boldsymbol{\pi}) = \pi_{p(\mathcal{J}_{h'})}(m | \mathcal{J}_{h'}) \cdot P(h' | h, \boldsymbol{\pi})$.

Recall

The probability of reaching information set \mathcal{J}_j when playing $\boldsymbol{\pi}$ is thus

$$P(\mathcal{J}_j | \boldsymbol{\pi}) := \sum_{h \in \mathcal{J}_j} P(h | \boldsymbol{\pi}) \quad \text{where } P(h | \boldsymbol{\pi}) \text{ denotes } P(h | \square, \boldsymbol{\pi})$$

Recall

Player i 's expected utility of playing $\boldsymbol{\pi}$ when history h has been reached is

$$U_i(\boldsymbol{\pi} | h) := \sum_{z \in Z} P(z | h, \boldsymbol{\pi}) \cdot u_i(z)$$

Towards Counterfactual Regret

Definition

Consider an extensive-form game with player $i \in P$ and information sets \mathcal{I} .

1. The **counterfactual probability** of **playing to reach** $h \in H$ is given by

$$P([\] | \boldsymbol{\pi}_{-i}) = 1 \text{ and } P([h'; m] | \boldsymbol{\pi}_{-i}) := \begin{cases} \pi_k(m | h') \cdot P(h' | \boldsymbol{\pi}_{-i}) & \text{if } p(h') = k \neq i, \\ P(h' | \boldsymbol{\pi}_{-i}) & \text{otherwise.} \end{cases}$$

We **counterfactually** assume that i **intentionally** played to reach \mathcal{I}_j .

Towards Counterfactual Regret

Definition

Consider an extensive-form game with player $i \in P$ and information sets \mathcal{J} .

1. The **counterfactual probability** of playing to reach $h \in H$ is given by

$$P([\] | \boldsymbol{\pi}_{-i}) = 1 \text{ and } P([h'; m] | \boldsymbol{\pi}_{-i}) := \begin{cases} \pi_k(m | h') \cdot P(h' | \boldsymbol{\pi}_{-i}) & \text{if } p(h') = k \neq i, \\ P(h' | \boldsymbol{\pi}_{-i}) & \text{otherwise.} \end{cases}$$

2. The **counterfactual probability** of **playing to reach** $\mathcal{J}_j \in \mathcal{J}$ is

$$P(\mathcal{J}_j | \boldsymbol{\pi}_{-i}) := \sum_{h \in \mathcal{J}_j} P(h | \boldsymbol{\pi}_{-i})$$

We **counterfactually** assume that i **intentionally** played to reach \mathcal{J}_j .

Towards Counterfactual Regret

Definition

Consider an extensive-form game with player $i \in P$ and information sets \mathcal{J} .

1. The **counterfactual probability** of playing to reach $h \in H$ is given by

$$P([\] | \boldsymbol{\pi}_{-i}) = 1 \text{ and } P([h'; m] | \boldsymbol{\pi}_{-i}) := \begin{cases} \pi_k(m | h') \cdot P(h' | \boldsymbol{\pi}_{-i}) & \text{if } p(h') = k \neq i, \\ P(h' | \boldsymbol{\pi}_{-i}) & \text{otherwise.} \end{cases}$$

2. The **counterfactual probability** of playing to reach $\mathcal{J}_j \in \mathcal{J}$ is

$$P(\mathcal{J}_j | \boldsymbol{\pi}_{-i}) := \sum_{h \in \mathcal{J}_j} P(h | \boldsymbol{\pi}_{-i})$$

3. The **counterfactual utility** of **playing to reach** \mathcal{J}_j and then playing $\boldsymbol{\pi}$ is

$$U_i(\boldsymbol{\pi} | \mathcal{J}_j) = \frac{\sum_{h \in \mathcal{J}_j} P(h | \boldsymbol{\pi}_{-i}) \cdot U_i(\boldsymbol{\pi} | h)}{P(\mathcal{J}_j | \boldsymbol{\pi}_{-i})} = \frac{\sum_{h \in \mathcal{J}_j} P(h | \boldsymbol{\pi}_{-i}) \cdot \sum_{z \in Z} P(z | h, \boldsymbol{\pi}) \cdot u_i(z)}{P(\mathcal{J}_j | \boldsymbol{\pi}_{-i})}$$

We **counterfactually** assume that i **intentionally** played to reach \mathcal{J}_j .

Counterfactual Regret

Definition

Consider $i \in P$ and $\mathcal{J}_j \in \mathcal{J}$ with $p(\mathcal{J}_j) = i$.

1. Denote the set of legal moves of i in \mathcal{J}_j by

$$M_i(\mathcal{J}_j) := \{m \in M_i \mid [h; m] \in H \text{ for some } h \in \mathcal{J}_j\}$$

Counterfactual Regret

Definition

Consider $i \in P$ and $\mathcal{I}_j \in \mathcal{I}$ with $p(\mathcal{I}_j) = i$.

1. Denote the set of legal moves of i in \mathcal{I}_j by

$$M_i(\mathcal{I}_j) := \{m \in M_i \mid [h; m] \in H \text{ for some } h \in \mathcal{I}_j\}$$

2. For behaviour strategy profile $\boldsymbol{\pi}$ and move $m \in M_i(\mathcal{I}_j)$, define modified profile $\langle \boldsymbol{\pi} \rangle_m^{\mathcal{I}_j}$ to be just like $\boldsymbol{\pi}$, except that in \mathcal{I}_j it always chooses m .

Counterfactual Regret

Definition

Consider $i \in P$ and $\mathcal{J}_j \in \mathcal{J}$ with $p(\mathcal{J}_j) = i$.

1. Denote the set of legal moves of i in \mathcal{J}_j by

$$M_i(\mathcal{J}_j) := \{m \in M_i \mid [h; m] \in H \text{ for some } h \in \mathcal{J}_j\}$$

2. For behaviour strategy profile $\boldsymbol{\pi}$ and move $m \in M_i(\mathcal{J}_j)$, define modified profile $\langle \boldsymbol{\pi} \rangle_m^{\mathcal{J}_j}$ to be just like $\boldsymbol{\pi}$, except that in \mathcal{J}_j it always chooses m .

3. The **immediate counterfactual regret** at time T is then defined by

$$r_i^T(\mathcal{J}_j) := \max_{m^* \in M_i(\mathcal{J}_j)} \sum_{t=1}^T P(\mathcal{J}_j \mid \boldsymbol{\pi}_{-i}^t) \cdot \left(U_i \left(\langle \boldsymbol{\pi}^t \rangle_{m^*}^{\mathcal{J}_j} \mid \mathcal{J}_j \right) - U_i(\boldsymbol{\pi}^t \mid \mathcal{J}_j) \right)$$

for any sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles.

Counterfactual Regret

Definition

Consider $i \in P$ and $\mathcal{J}_j \in \mathcal{J}$ with $p(\mathcal{J}_j) = i$.

1. Denote the set of legal moves of i in \mathcal{J}_j by

$$M_i(\mathcal{J}_j) := \{m \in M_i \mid [h; m] \in H \text{ for some } h \in \mathcal{J}_j\}$$

2. For behaviour strategy profile $\boldsymbol{\pi}$ and move $m \in M_i(\mathcal{J}_j)$, define modified profile $\langle \boldsymbol{\pi} \rangle_m^{\mathcal{J}_j}$ to be just like $\boldsymbol{\pi}$, except that in \mathcal{J}_j it always chooses m .

3. The **immediate counterfactual regret** at time T is then defined by

$$r_i^T(\mathcal{J}_j) := \max_{m^* \in M_i(\mathcal{J}_j)} \sum_{t=1}^T P(\mathcal{J}_j \mid \boldsymbol{\pi}_{-i}^t) \cdot \left(U_i \left(\langle \boldsymbol{\pi}^t \rangle_{m^*}^{\mathcal{J}_j} \mid \mathcal{J}_j \right) - U_i(\boldsymbol{\pi}^t \mid \mathcal{J}_j) \right)$$

for any sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles.

Key Feature: r_i^T can be minimised by controlling only $\pi_i(\mathcal{J}_j): M_i(\mathcal{J}_j) \rightarrow [0, 1]$.

Overall Regret \leq Immediate Regret

Given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$, the (external) **overall regret** of player i at time T is:

$$R_i^T = \max_{\boldsymbol{\pi}_i^* \in \Pi_i} \sum_{t=1}^T (U_i(\boldsymbol{\pi}_i^*, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}^t))$$

where $U_i(\boldsymbol{\pi})$ denotes $U_i(\boldsymbol{\pi} \mid \square)$.

Overall Regret \leq Immediate Regret

Given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$, the (external) **overall regret** of player i at time T is:

$$R_i^T = \max_{\boldsymbol{\pi}_i^* \in \Pi_i} \sum_{t=1}^T (U_i(\boldsymbol{\pi}_i^*, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}^t))$$

where $U_i(\boldsymbol{\pi})$ denotes $U_i(\boldsymbol{\pi} \mid \square)$.

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

In any extensive-form game with perfect recall, for any player $i \in P$ and any sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles:

$$R_i^T \leq \sum_{\substack{J_j \in \mathcal{J}, \\ \rho(J_j)=i}} [r_i^T(J_j)]^+$$

Overall Regret \leq Immediate Regret

Given sequence $(\boldsymbol{\pi}^t)_{t=1}^T$, the (external) **overall regret** of player i at time T is:

$$R_i^T = \max_{\boldsymbol{\pi}_i^* \in \Pi_i} \sum_{t=1}^T (U_i(\boldsymbol{\pi}_i^*, \boldsymbol{\pi}_{-i}^t) - U_i(\boldsymbol{\pi}^t))$$

where $U_i(\boldsymbol{\pi})$ denotes $U_i(\boldsymbol{\pi} \mid \square)$.

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

In any extensive-form game with perfect recall, for any player $i \in P$ and any sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles:

$$R_i^T \leq \sum_{\substack{\mathcal{J}_j \in \mathcal{J}, \\ \rho(\mathcal{J}_j) = i}} \left[r_i^T(\mathcal{J}_j) \right]^+$$

Thus: Minimising immediate regret in each \mathcal{J}_j minimises overall regret.

Regret Matching at Information Sets

Definition

Consider the sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles of past play.

1. Let $\mathcal{J}_j \in \mathcal{J}$ with $p(\mathcal{J}_j) = i$ and $m \in M_i(\mathcal{J}_j)$. The **accumulated regret** of m is

$$R_i^T(\mathcal{J}_j, m) := \sum_{t=1}^T P(\mathcal{J}_j | \boldsymbol{\pi}_{-i}^t) \cdot \left(U_i \left(\langle \boldsymbol{\pi}^t \rangle_m^{\mathcal{J}_j} \mid \mathcal{J}_j \right) - U_i(\boldsymbol{\pi}^t \mid \mathcal{J}_j) \right)$$

Regret Matching at Information Sets

Definition

Consider the sequence $(\boldsymbol{\pi}^t)_{t=1}^T$ of behaviour strategy profiles of past play.

1. Let $\mathcal{J}_j \in \mathcal{J}$ with $p(\mathcal{J}_j) = i$ and $m \in M_i(\mathcal{J}_j)$. The **accumulated regret** of m is

$$R_i^T(\mathcal{J}_j, m) := \sum_{t=1}^T P(\mathcal{J}_j | \boldsymbol{\pi}_{-j}^t) \cdot \left(U_i(\langle \boldsymbol{\pi}^t \rangle_m^{\mathcal{J}_j} | \mathcal{J}_j) - U_i(\boldsymbol{\pi}^t | \mathcal{J}_j) \right)$$

2. The probability of playing m at \mathcal{J}_j at time $T + 1$ is set to

$$\pi_i^{T+1}(\mathcal{J}_j)(m) := \begin{cases} \frac{[R_i^T(\mathcal{J}_j, m)]^+}{R_i^{T,+}} & \text{if } R_i^{T,+} > 0, \quad \text{where } R_i^{T,+} := \sum_{m \in M_i(\mathcal{J}_j)} [R_i^T(\mathcal{J}_j, m)]^+ \\ \frac{1}{|M_i(\mathcal{J}_j)|} & \text{otherwise.} \end{cases}$$

CFR: Algorithm (1)

Initialisation of global variables:

```
function init() {  
  foreach  $i \in \{1, 2\}$  do {  
    foreach  $\mathcal{J}_j \in \mathcal{J}$  with  $p(\mathcal{J}_j) = i$  do {  
      foreach  $m \in M_i(\mathcal{J}_j)$  do {  
         $regret[j][m] := 0$  // accumulated regret table  
         $strategy[j][m] := 0$  // accumulated strategy table  
         $profile[1][j][m] := 1/|M_i(\mathcal{J}_j)|$  // move distribution for  $\mathcal{J}_j$  at  $t = 1$   
      } } }  
  } } }
```

CFR: Algorithm (1)

Initialisation of global variables:

```
function init() {  
  foreach  $i \in \{1, 2\}$  do {  
    foreach  $\mathcal{J}_j \in \mathcal{J}$  with  $p(\mathcal{J}_j) = i$  do {  
      foreach  $m \in M_i(\mathcal{J}_j)$  do {  
         $regret[j][m] := 0$  // accumulated regret table  
         $strategy[j][m] := 0$  // accumulated strategy table  
         $profile[1][j][m] := 1/|M_i(\mathcal{J}_j)|$  // move distribution for  $\mathcal{J}_j$  at  $t = 1$   
      }  
    }  
  }  
}
```

Main Loop:

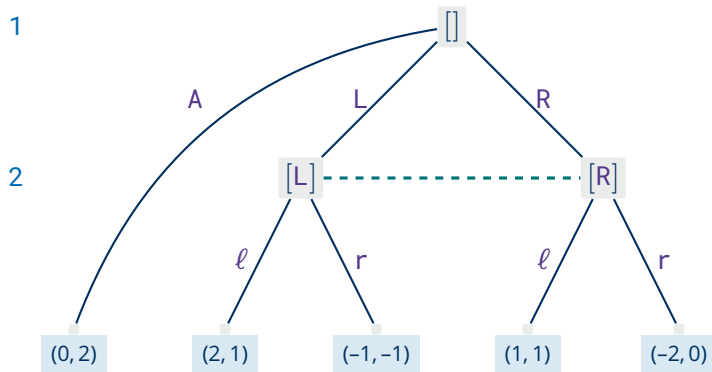
```
function solve( $T$ ) {  
  foreach  $t \in \{1, 2, \dots, T\}$  do {  
    foreach  $i \in \{1, 2\}$  do {  
      cfr( $\square, i, t, 1, 1$ )  
    }  
  }  
}
```

CFR: Algorithm (2)

```
function cfr( $h, i, t, p_1, p_2$ ) { // history, player, time point, reach probabilities
  if IS-TERMINAL( $h$ ) then return UTILITY $_i$ ( $s$ )
   $v_h := 0$  // initialise expected payoff at  $h \in \mathcal{J}_j$ 
  foreach  $m \in M_{p(\mathcal{J}_j)}(\mathcal{J}_j)$  do {  $v'_h[j][m] := 0$  } // initialise payoffs of single moves
  foreach  $m \in M_{p(\mathcal{J}_j)}(\mathcal{J}_j)$  do {
    if TURN( $h$ ) = 1 then {  $v'_h[j][m] := \text{cfr}([h; m], i, t, \text{profile}[t][j][m] \cdot p_1, p_2)$  }
    else {  $v'_h[j][m] := \text{cfr}([h; m], i, t, p_1, \text{profile}[t][j][m] \cdot p_2)$  }
     $v_h := v_h + \text{profile}[t][j][m] \cdot v'_h[j][m]$  // accumulate currently expected payoff
  }
  if TURN( $h$ ) =  $i$  then { // players minimise immediate regret of own moves
     $r^+ := 0$  // initialise sum of positive regrets
    for  $m \in M_i(\mathcal{J}_j)$  do { // update values needed for regret matching
       $\text{regret}[j][m] := \text{regret}[j][m] + p_{3-i} \cdot (v'_h[m] - v_h)$  // update accumulated cf regret
       $\text{strategy}[j][m] := \text{strategy}[j][m] + p_i \cdot \text{profile}[t][j][m]$  // update "frequency" of move
       $r^+ := r^+ + [\text{regret}[j][m]]^+$  // accumulate positive regret sum for normalisation
    }
    if  $r^+ > 0$  then { foreach  $m \in M_i(\mathcal{J}_j)$  do { // apply regret matching at  $\mathcal{J}_j$ 
       $\text{profile}[t+1][j][m] := [\text{regret}[j][m]]^+ / r^+$  } }
    else { foreach  $m \in M_i(\mathcal{J}_j)$  do {
       $\text{profile}[t+1][j][m] := 1 / |M_i(\mathcal{J}_j)|$  } } }
  }
  return  $v_h$  }
```

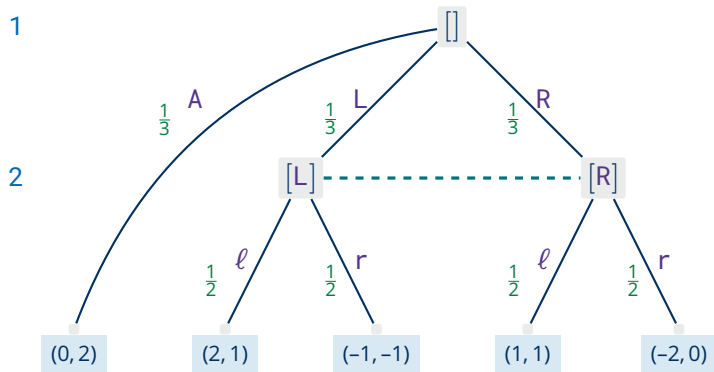

CFR: Example

Recall the following extensive-form game G_4 :



CFR: Example

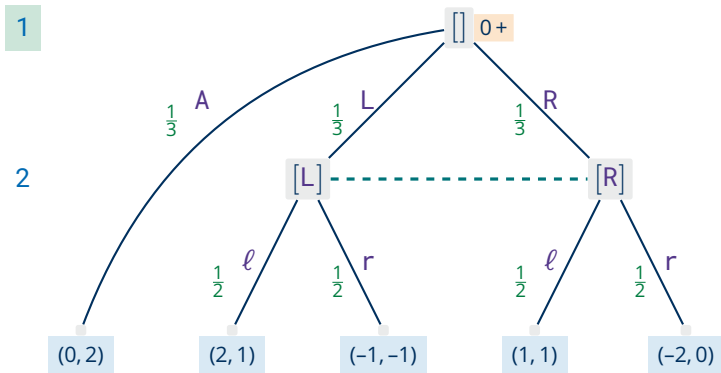
Recall the following extensive-form game G_4 :



(1) Initialise move probabilities by uniform distributions

CFR: Example

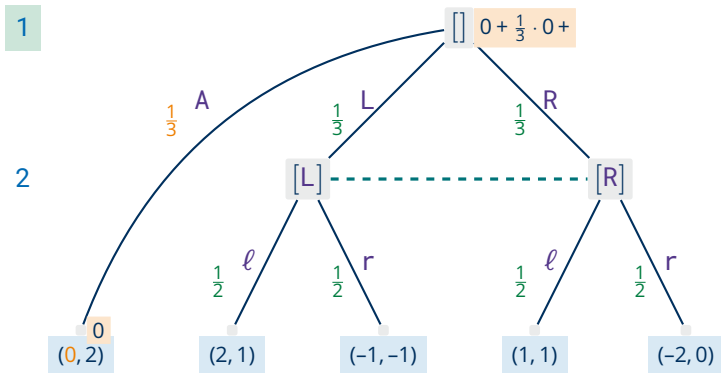
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

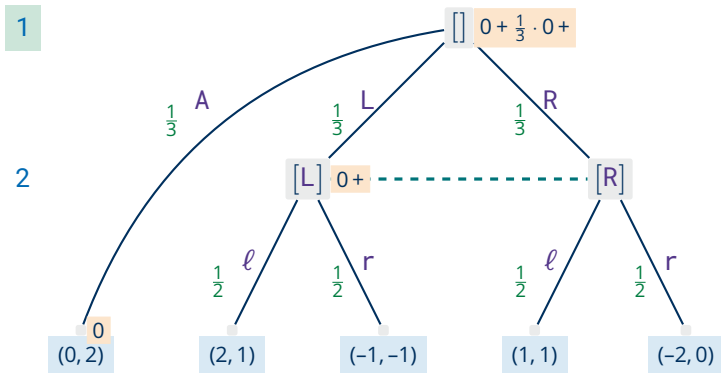
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

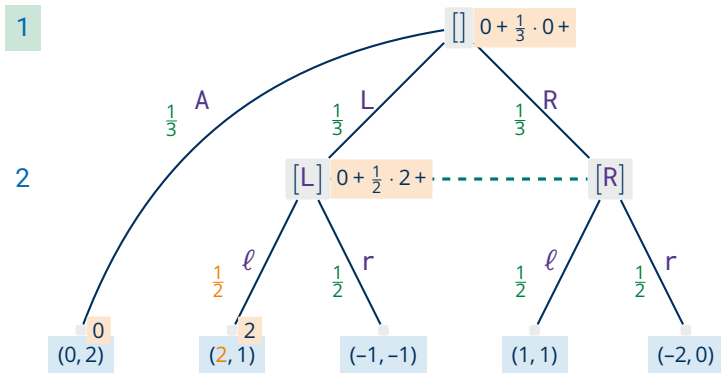
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

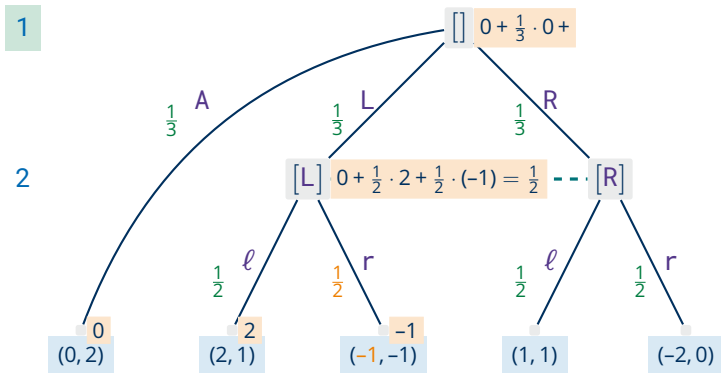
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

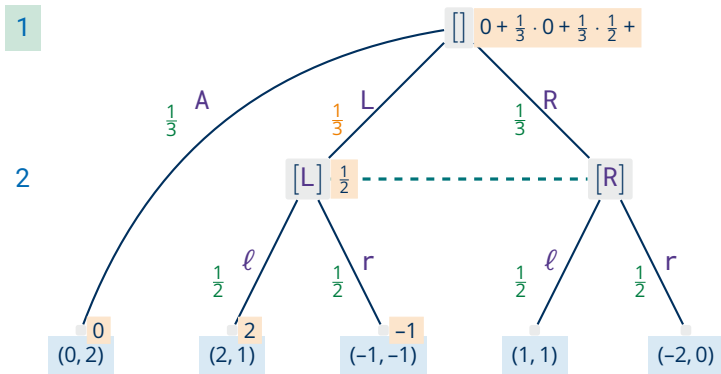
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

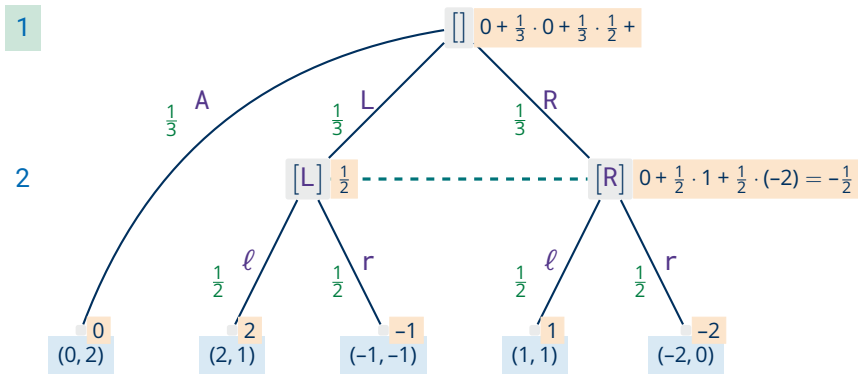
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

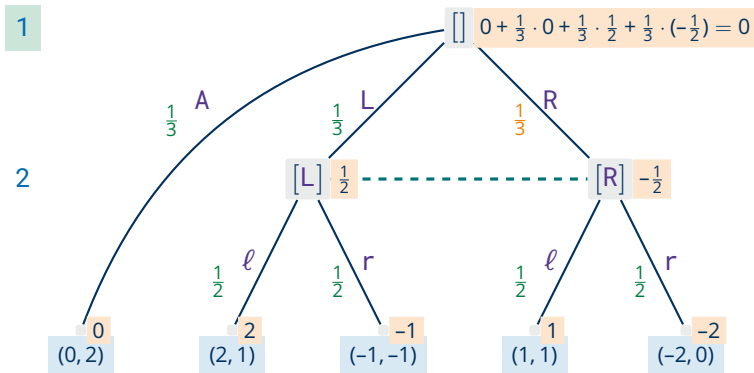
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

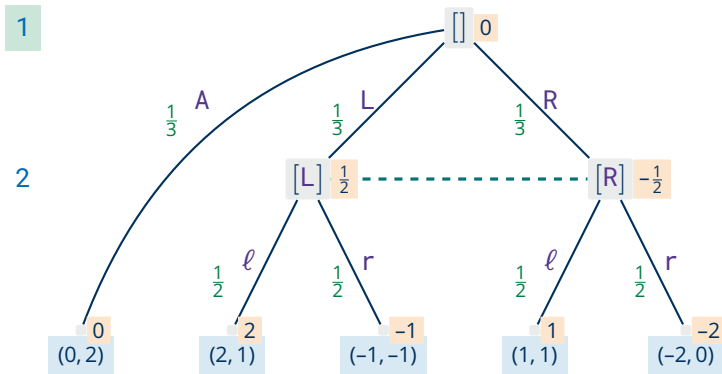
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

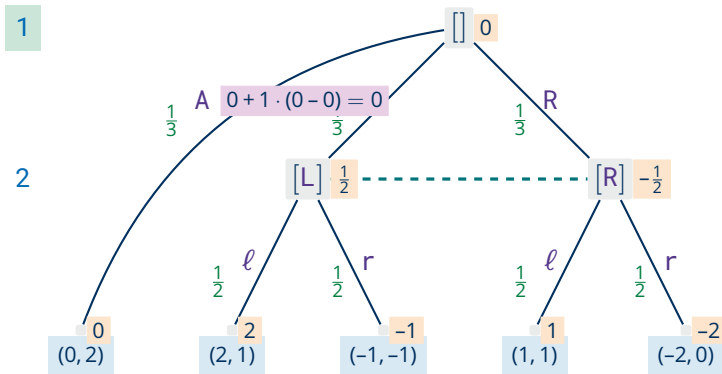
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

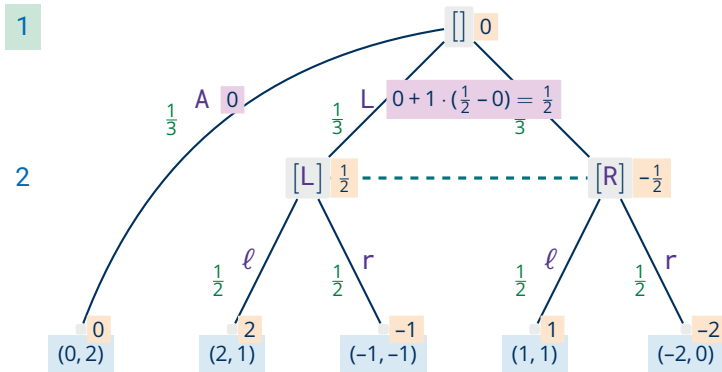
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

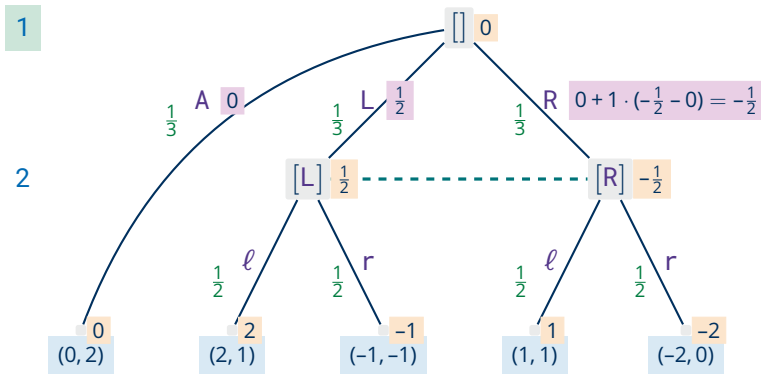
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

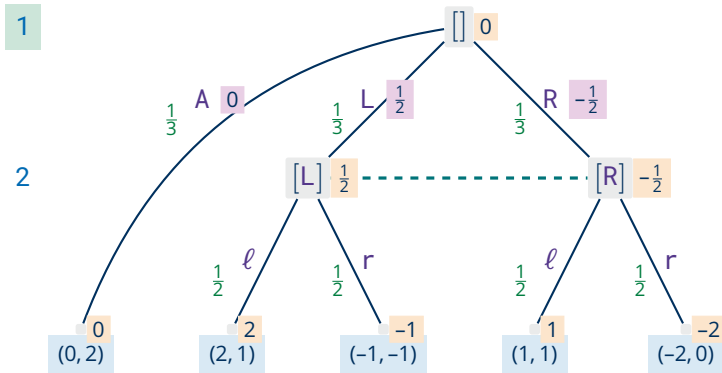
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

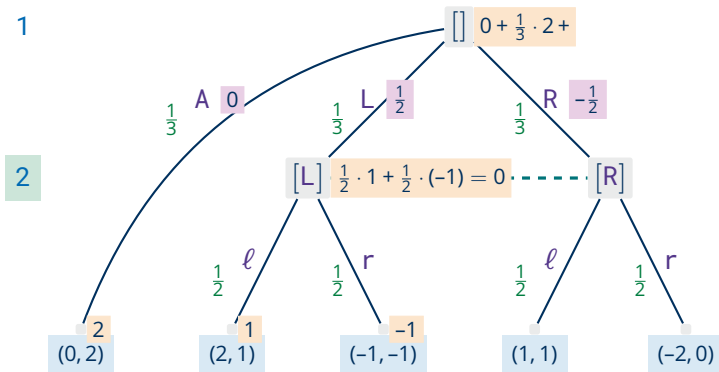
Recall the following extensive-form game G_4 :



(2) Traverse game tree for $T = 1, i = 1$

CFR: Example

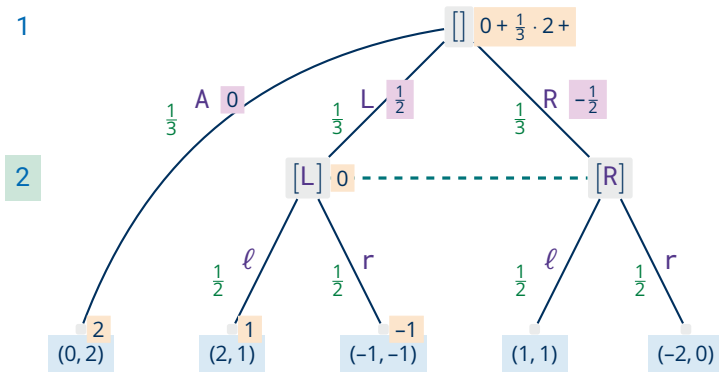
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

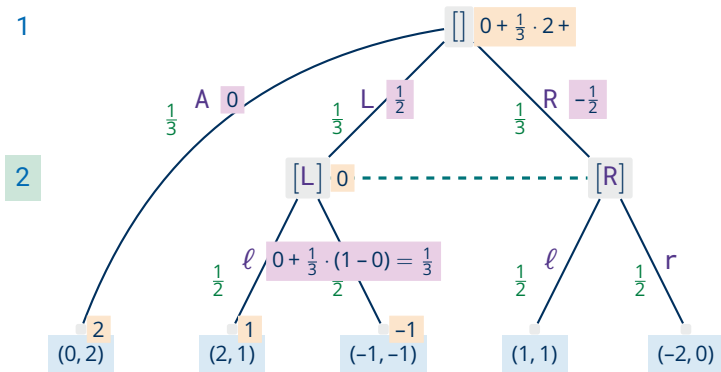
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

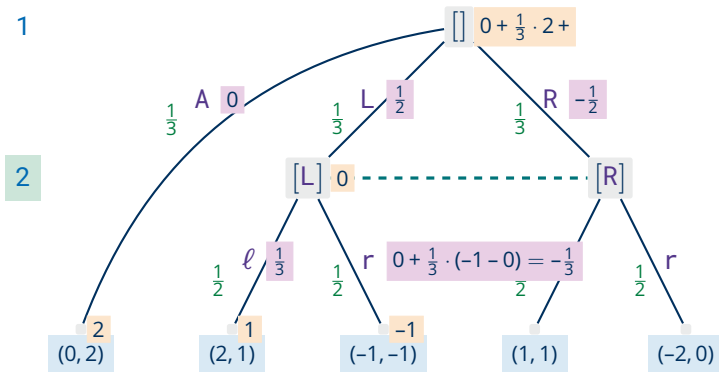
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

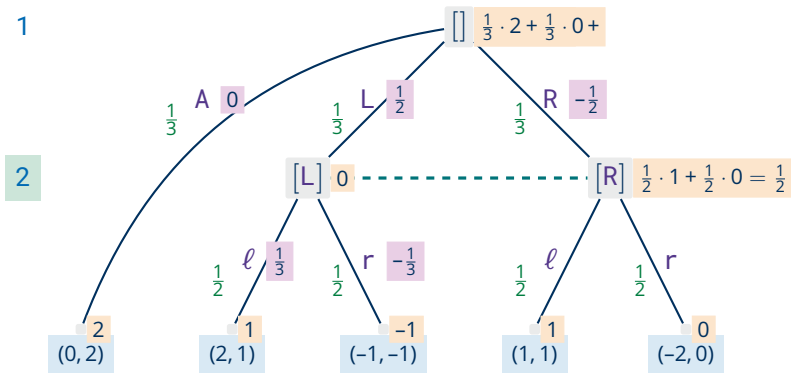
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

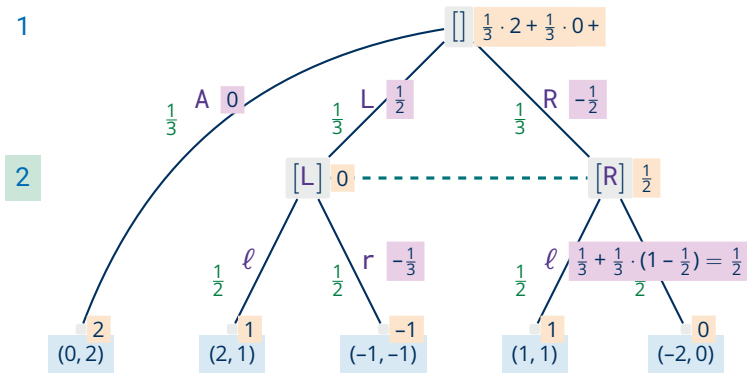
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

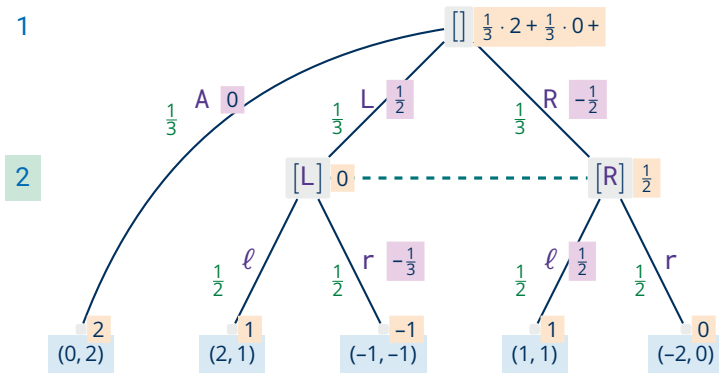
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

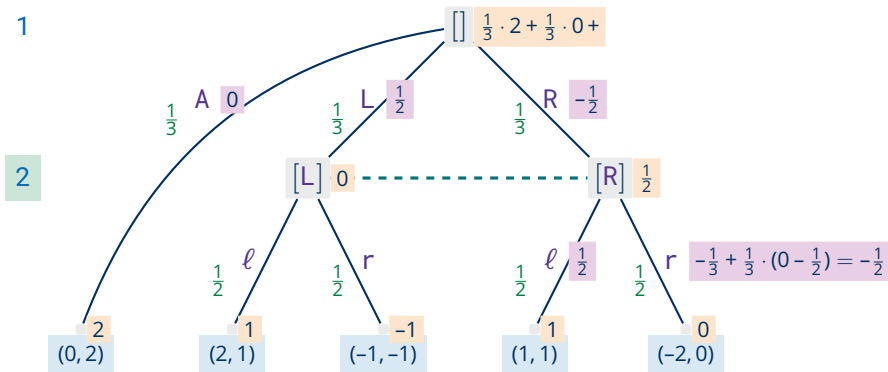
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

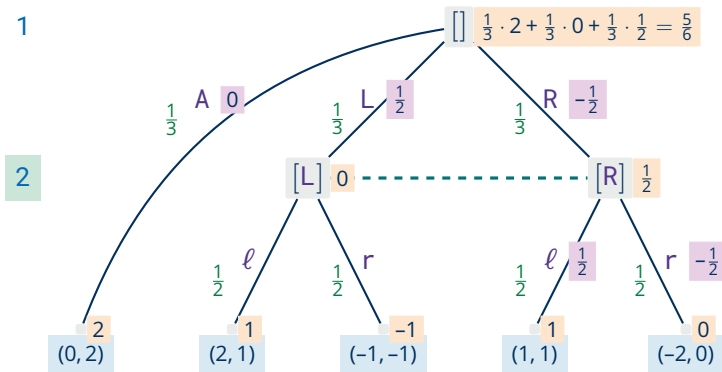
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

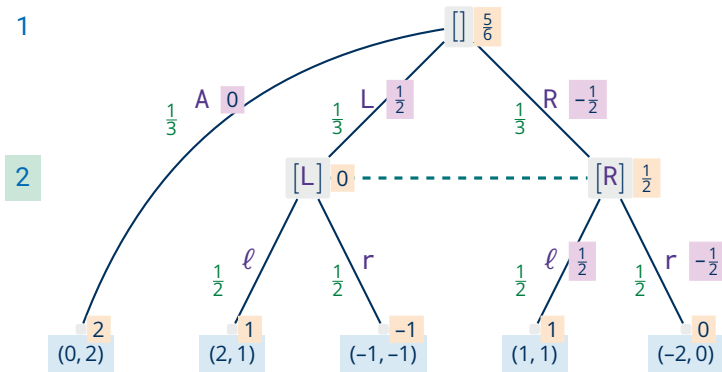
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

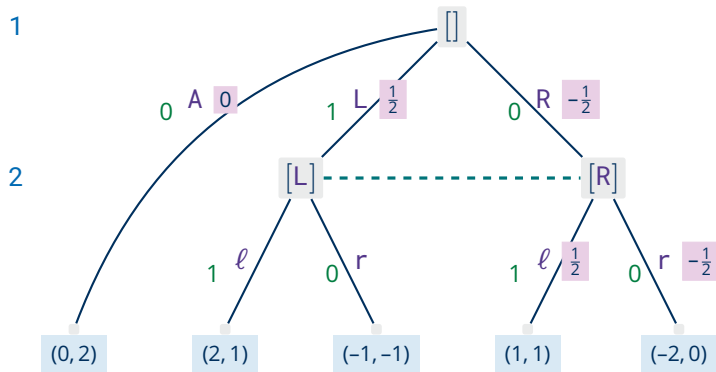
Recall the following extensive-form game G_4 :



(3) Traverse game tree for $T = 1, i = 2$

CFR: Example

Recall the following extensive-form game G_4 :



(4) Update move probabilities according to regret matching

CFR: Convergence and Correctness

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

For any extensive-form game with perfect recall, if player i selects actions according to regret matching at information sets, then

$$r_i^T(\mathcal{J}_j) \leq \omega \cdot \sqrt{|M'_i|} \cdot \sqrt{T} \quad \text{whence} \quad R_i^T \leq \omega \cdot |\{\mathcal{J}_j \in \mathcal{J} \mid p(\mathcal{J}_j) = i\}| \cdot \sqrt{|M'_i|} \cdot \sqrt{T}$$

where $\omega \in \mathbb{R}$ only depends on \mathbf{u} , and $|M'_i| := \max_{\mathcal{J}_j \in \mathcal{J}_{p(\mathcal{J}_j)=i}} |M_i(\mathcal{J}_j)|$.

CFR: Convergence and Correctness

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

For any extensive-form game with perfect recall, if player i selects actions according to regret matching at information sets, then

$$r_i^T(\mathcal{J}_j) \leq \omega \cdot \sqrt{|M'_i|} \cdot \sqrt{T} \quad \text{whence} \quad R_i^T \leq \omega \cdot |\{\mathcal{J}_j \in \mathcal{J} \mid p(\mathcal{J}_j) = i\}| \cdot \sqrt{|M'_i|} \cdot \sqrt{T}$$

where $\omega \in \mathbb{R}$ only depends on \mathbf{u} , and $|M'_i| := \max_{\mathcal{J}_j \in \mathcal{J}_{p(\mathcal{J}_j)=i}} |M_i(\mathcal{J}_j)|$.

- The bound on overall regret is **linear** in the number of information sets.

CFR: Convergence and Correctness

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

For any extensive-form game with perfect recall, if player i selects actions according to regret matching at information sets, then

$$r_i^T(\mathcal{J}_j) \leq \omega \cdot \sqrt{|M'_i|} \cdot \sqrt{T} \quad \text{whence} \quad R_i^T \leq \omega \cdot |\{\mathcal{J}_j \in \mathcal{J} \mid p(\mathcal{J}_j) = i\}| \cdot \sqrt{|M'_i|} \cdot \sqrt{T}$$

where $\omega \in \mathbb{R}$ only depends on \mathbf{u} , and $|M'_i| := \max_{\mathcal{J}_j \in \mathcal{J}_{p(\mathcal{J}_j)=i}} |M_i(\mathcal{J}_j)|$.

- The bound on overall regret is **linear** in the number of information sets.
- The overall regret grows **sublinearly** in T , so the **average overall regret** $\bar{R}_i^T := \frac{1}{T} \cdot R_i$ tends to zero as $T \rightarrow \infty$.

CFR: Convergence and Correctness

Theorem [Zinkevich, Johanson, Bowling, and Piccione, 2007]

For any extensive-form game with perfect recall, if player i selects actions according to regret matching at information sets, then

$$r_i^T(\mathcal{J}_j) \leq \omega \cdot \sqrt{|M'_i|} \cdot \sqrt{T} \quad \text{whence} \quad R_i^T \leq \omega \cdot |\{\mathcal{J}_j \in \mathcal{J} \mid p(\mathcal{J}_j) = i\}| \cdot \sqrt{|M'_i|} \cdot \sqrt{T}$$

where $\omega \in \mathbb{R}$ only depends on \mathbf{u} , and $|M'_i| := \max_{\mathcal{J}_j \in \mathcal{J}_{p(\mathcal{J}_j)=i}} |M_i(\mathcal{J}_j)|$.

- The bound on overall regret is **linear** in the number of information sets.
- The overall regret grows **sublinearly** in T , so the **average overall regret** $\bar{R}_i^T := \frac{1}{T} \cdot R_i$ tends to zero as $T \rightarrow \infty$.

Theorem

In any two-player, zero-sum extensive-form game with perfect recall, if both players select actions according to regret matching at information sets, then the average strategy profiles tend to the set of Nash equilibria as $T \rightarrow \infty$.

CFR Algorithm: Remarks

- Histories/information sets of *Nature* can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.

CFR Algorithm: Remarks

- Histories/information sets of *Nature* can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.

CFR Algorithm: Remarks

- Histories/information sets of *Nature* can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.
- After **solve**(T), the final values of $strategy[j][m]$ can be normalised to obtain the behaviour strategies tending towards Nash equilibria.

CFR Algorithm: Remarks

- Histories/information sets of *Nature* can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.
- After **solve**(T), the final values of $strategy[j][m]$ can be normalised to obtain the behaviour strategies tending towards Nash equilibria.
- Additional techniques, e.g. game abstraction, are used in practice to reduce the number of information sets (per player) to a manageable size.

CFR Algorithm: Remarks

- Histories/information sets of *Nature* can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.
- After **solve**(T), the final values of $strategy[j][m]$ can be normalised to obtain the behaviour strategies tending towards Nash equilibria.
- Additional techniques, e.g. game abstraction, are used in practice to reduce the number of information sets (per player) to a manageable size.
- By using regret matching⁺ in place of regret matching, we obtain CFR⁺.

CFR Algorithm: Remarks

- Histories/information sets of **Nature** can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.
- After **solve**(T), the final values of $strategy[j][m]$ can be normalised to obtain the behaviour strategies tending towards Nash equilibria.
- Additional techniques, e.g. game abstraction, are used in practice to reduce the number of information sets (per player) to a manageable size.
- By using regret matching⁺ in place of regret matching, we obtain CFR⁺.
- CFR⁺ also uses linear weighting to compute average strategies:

$$\bar{\pi}_i^{T,+}(s_j) := \frac{2}{T^2+T} \cdot \sum_{t=1}^T (t \cdot \pi^t(s_j))$$

CFR Algorithm: Remarks

- Histories/information sets of **Nature** can be treated in the algorithm via sampling a move from $M_{\text{Nature}}(J_j)$ with the specified distribution.
- At each time step $t = 1, 2, \dots, T$ (and for each $i \in P$), the call to **cfr**($[], i, t, 1, 1$) leads to a full traversal of the game tree.
- After **solve**(T), the final values of $strategy[j][m]$ can be normalised to obtain the behaviour strategies tending towards Nash equilibria.
- Additional techniques, e.g. game abstraction, are used in practice to reduce the number of information sets (per player) to a manageable size.
- By using regret matching⁺ in place of regret matching, we obtain CFR⁺.
- CFR⁺ also uses linear weighting to compute average strategies:

$$\bar{\pi}_i^{T,+}(s_j) := \frac{2}{T^2+T} \cdot \sum_{t=1}^T (t \cdot \pi^t(s_j))$$

- Bowling et al. [2015] used CFR⁺ (with additional optimisations) to “essentially weakly solve” heads-up limit hold'em poker.

Conclusion

Summary

- The **regret** is the difference between a player's best possible strategy and their actual strategy.
- A **correlated equilibrium** can be seen as providing players with private signals they can use to best-respond to each other's strategies.
- The **regret matching** algorithm uses self-play to steer play towards the set of correlated equilibria.
- In the case of two-player zero-sum games, regret matching tends towards the set of (mixed) Nash equilibria.
- The **counterfactual regret minimisation** algorithm applies regret matching to every information set of an (imperfect-information) extensive-form game (with perfect recall).

Action Point: Implement $\text{CFR}^{(+)}$ and use it to solve Simplified Poker.