



# FOUNDATIONS OF DATABASES AND QUERY LANGUAGES

## **Lecture 13: Graph Databases and Path Queries**

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# Overview

1. Introduction | Relational data model
2. First-order queries
3. Complexity of query answering
4. Complexity of FO query answering
5. Conjunctive queries
6. Tree-like conjunctive queries
7. Query optimisation
8. Conjunctive Query Optimisation / First-Order Expressiveness
9. First-Order Expressiveness / Introduction to Datalog
10. Expressive Power and Complexity of Datalog
11. Optimisation and Evaluation of Datalog
12. Evaluation of Datalog (2)
13. Graph Databases and Path Queries
14. Outlook: database theory in practice

See course homepage [[⇒ link](#)] for more information and materials

# Review: Datalog

Datalog is a powerful recursive query language

Advantages:

- Natural extension of (U)CQs with recursion
- Can be extended with (EDB) negation
- Polynomial data complexity of query answering

Disadvantages:

- High query and combined complexity ( $\text{EXPTIME}$ )
- Perfect optimisation is undecidable
- Somewhat complicated to write queries

# Graph Databases

Our original motivation for going from FO queries to Datalog:  
Reachability of nodes in a (directed) graph  $\leadsto$  let's focus on graphs

Graph database: a DBMS that supports “graphs” as its datamodel

There are many kinds of graphs:

- Directed or undirected?
- Labelled or unlabelled edges/nodes?
- What kinds of labels? Datatypes?
- Parallel edges (multi-graphs)? With same label?
- One graph or several graphs per database?

Two types of graph database models dominate the market today:  
Resource Description Framework (RDF) and Property Graph

# Resource Description Framework (RDF)

RDF is a W3C standard for representing linked data on the Web

- Directed labelled graph; nodes are identified by their labels
- Labels are URIs or datatype literals
- Multiple parallel edges only when using different edge labels
- Supports multiple graphs in one database
- W3C standard; implementations for many programming languages
- Datatype support based on W3C XML Schema datatypes
- Graphs can be exchanged in many standard syntax formats

# Property Graph

Property Graph is a popular data model of many graph databases

- Directed labelled multi-graph; labels do not identify nodes
- “Labels” can be lists of attribute-value pairs
- Multiple parallel edges with the exact same labels are possible
- No native multi-graph support (could be simulated with additional attributes)
- No standard definition of technical details; most common implementation: Tinkerpop/Blueprints API (Java)
- Datatype support varies by implementation
- No standard syntax for exchanging data

# Representing Graphs

Graphs (of any type) are usually viewed as sets of edges

- RDF: triples of form subject-predicate-object
  - When managing multiple graphs, each triple is extended with a fourth component (graph ID)  $\rightsquigarrow$  quads
  - RDF databases are sometimes still called “triple stores”, although most modern systems effectively store quads
- Property Graph: edge objects with attribute lists
  - represented by Java objects in Blueprints

Graphs can be stored in relational databases

- RDF: table Triple[Subject,Predicate,Object]
- Property Graph: tables Edge[SourceId,EdgeId,TargetId] and Attributes[Id,Attribute,Value]

# Representing Data in Graphs

Property Graphs can represent RDF:

- use attributes to store RDF node and edge labels (URIs)
- use key constraints to ensure that no two distinct nodes can have same label



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## RDF can represent Property Graphs:

- use additional nodes to represent Property Graph edges
- use RDF triples with special predicates to represent attributes

Either model can also represent hypergraphs/RDBs (exercise)

↪ all models can represent all data in principle

↪ supported query features and performance will vary

# Querying Graphs

Preferred query language depends on graph model

- RDF: W3C SPARQL query language
- Property Graph: no uniform approach to data access
  - many tools prefer API access over a query language
  - proprietary query languages, e.g., “Cypher” for Neo4j

However, there are some common basics in almost all cases:

- Conjunctive queries
- Regular path queries

# Conjunctive Queries over Graphs

Basic descriptions of local patterns in a graph

Formally, it suffices to say:

CQs over RDF correspond to CQs over relational databases with a single table Triple[Subject,Predicate,Object]

(analogously for Property Graphs)

- All complexity results for query answering and optimisation carry over from RDBs (in particular, restricting to graphs does not make anything simpler)
- Details of representation of data in tables do not matter
- CQs are restricted to local patterns (no reachability . . .)

# Regular Path Queries

Idea: use regular expressions to navigate over paths

Let's consider a simplified graph model, where a graph is given by:

- Set of nodes  $N$  (without additional labels)
- Set of edges  $E$ , labelled by a function  $\lambda : E \rightarrow L$ , where  $L$  is a finite set of labels

## Definition

A **regular expression** over a set of labels  $L$  is an expression of the following form:

$$E ::= L \mid (E \circ E) \mid (E + E) \mid E^*$$

A **regular path query** (RPQ) is an expression of the form  $E(s, t)$ , where  $E$  is a regular expression and  $s$  and  $t$  are terms (constants or variables).

# Semantics of Regular Path Queries

As usual, a regular expression  $E$  **matches** a word  $w = \ell_1 \cdots \ell_n$  if any of the following conditions is satisfied:

- $E \in L$  is a label and  $w = E$ .
- $E = (E_1 \circ E_2)$  and there is  $i \in \{0, \dots, n\}$  such that  $E_1$  matches  $\ell_1 \cdots \ell_i$  and  $E_2$  matches  $\ell_{i+1} \cdots \ell_n$  (the words matched by  $E_1$  and  $E_2$  can be empty if  $i = 0$  or  $i = n$ , respectively).
- $E = (E_1 + E_2)$  and  $w$  is matched by  $E_1$  or by  $E_2$
- $E = E_1^*$  and  $w$  has the form  $w_1 w_2 \cdots w_m$  for  $n \geq 0$ , where each word  $w_i$  is matched by  $E_1$

## Definition

Let  $a$  and  $b$  be constants and  $x$  and  $y$  be variables. An RPQ  $E(a, b)$  is **entailed** by a graph  $G$  if there is a directed path from node  $a$  to node  $b$  that is labelled by a word matched by  $E$ . The **answers to RPQs**  $E(x, y)$ ,  $E(x, b)$ , and  $E(a, y)$  are defined in the obvious way.

# Extending the Expressive Power of RPQs

Regular path queries can be used to express typical reachability queries, but are still quite limited  $\leadsto$  extensions

## 2-Way Regular Path Queries (2RPQs)

- For every label  $\ell \in L$ , also introduce a converse label  $\ell^-$
- Allow converse labels in regular expressions
- Matched paths can follow edges forwards or backwards

## Conjunctive Regular Path Queries (CRPQs)

- Extend conjunctive queries with RPQs
- RPQs can be used like binary query atoms
- Obvious semantics

Conjunctive 2-Way Regular Path Queries (C2RPQs) combine both extensions

# C2RPQs: Examples

All ancestors of Alice:

$$((\text{father} + \text{mother}) \circ (\text{father} + \text{mother})^*)(\text{alice}, y)$$

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Pairs of stops connected by tram lines 3 and 8:

$$(\text{nextStop3} \circ \text{nextStop3}^*)(x, y) \wedge (\text{nextStop8} \circ \text{nextStop8}^*)(x, y)$$

# Complexity of RPQs

A nondeterministic algorithm for Boolean RPQs:

- Transform regular expression into a finite automaton
- Starting from the first node, guess a matching path
- When moving along path, advance state of automaton
- Accept if the second node is reached in an accepting state
- Reject if path is longer than size of graph  $\times$  size of automaton

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Space requirements when assuming query (and automaton) fixed:  
pointer to current node in graph, pointer to current state of automaton, counter for length of path  $\leadsto$  NL algorithm

Conversely, reachability in an unlabelled graph is hard for NL  
 $\leadsto$  RPQ matching is NL-complete (data complexity)

(Combined/query complexity is in P, as we will see below)

# Complexity of C2RPQs

We already know:

- CQ matching is in  $AC^0$  (data complexity) and NP-complete (query and combined complexity)
- RPQ matching is NL-complete (data) and in P (query/combined)
- $AC^0 \subset NL$  and  $NL \subseteq NP$

~> C2RPQs are NP-hard (combined/query) and NL-hard (data)

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→ C2RPQs are NP-hard (combined/query) and NL-hard (data)

It's not hard to show that these bounds are tight:

## Theorem

C2RPQ matching is NP-complete for combined and query complexity, and NL-complete for data complexity.

# (C2)RPQs and Datalog

How do path queries relate to Datalog?

We already know:

- Datalog is  $\text{EXPTIME}$ -complete (combined/query) and  $P$ -complete (data)
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$\leadsto$  maybe Datalog is more expressive than C2RPQs ...

Indeed, we can express regular expressions in Datalog

For simplicity, assume that we have a binary EDB predicate  $p_\ell$  for each label  $\ell \in L$  (other encodings would work just as well)

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$$P_E = P_{E_1} \cup P_{E_2} \cup \{Q_E(x, z) \leftarrow Q_{E_1}(x, y) \wedge Q_{E_2}(y, z)\}$$

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If  $E = E_1^*$  then

$$P_E = P_{E_1} \cup \{Q_E(x, x) \leftarrow, Q_E(x, z) \leftarrow Q_E(x, y) \wedge Q_{E_1}(y, z)\}$$

# Reprise: Combined Complexity of 2RPQs

As a side effect, the previous translation shows that 2RPQs can be evaluated in P combined complexity:

- Each (2-way) regular expression  $E$  leads to a Datalog query  $\langle Q_E, P_E \rangle$  of polynomial size
  - Each rule in  $P_E$  has at most three variables  
 $\leadsto$  the grounding of  $P_E$  for a graph with nodes  $N$  is of size  $|P_E| \times |N|^3$
  - propositional logic rules can be evaluated in polynomial time
- $\leadsto$  polynomial time decision procedure

# Expressing C2RPQs in Datalog

It is now easy to express C2RPQs in Datalog:

- Use the encoding of CQs in Datalog as shown in the exercise
- Express 2RPQ atoms in Datalog as just shown

Can every Datalog query over binary “labelled-edge” EDB predicates be expressed with (C2)RPQs?

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Can every Datalog query over binary “labelled-edge” EDB predicates be expressed with (C2)RPQs?

- This would imply  $P = NL$  (but not that  $NP = EXPTIME!$ ): unlikely but not known to be false
- However, there are stronger direct arguments that show the limits of C2RPQs (exercise)



# Linear Datalog and Binary Datalog

Expressing 2RPQs in Datalog requires only restricted forms of Datalog:

## Definition

A Datalog program is **linear** if each of its rules has at most one IDB atom in its body. A Datalog program is **binary** if all of its IDB predicates have arity at most two.

The following complexity results are known:

## Theorem

Query answering in linear Datalog is NL-complete for data complexity, and PSPACE-complete for combined and query complexity.

Combined complexity further drops to NP for binary Datalog.

↪ complexity results that are more similar to (C2)RPQs . . .

## 2RPQs and Linear Datalog

The Datalog translation of 2RPQs does not lead to linear Datalog, but we can fix this.

We transform a regular expression  $E$  to a linear Datalog query  $\langle Q_E, P_E^{\text{lin}} \rangle$ :

- Construct a non-deterministic automaton  $\mathcal{A}_E$  for  $E$
- For every state  $q$  of  $\mathcal{A}_E$ , we use a binary IDB predicate  $S_q$
- For the starting state  $q_0$  of  $\mathcal{A}_E$ , we add a rule  $S_{q_0}(x, x) \leftarrow$
- For every transition  $q \xrightarrow{\ell} q'$  of  $\mathcal{A}_E$ , we add a rule

$$S_{q'}(x, z) \leftarrow S_q(x, y) \wedge p_{\ell}(y, z)$$

- For every final state  $q_f$  of  $\mathcal{A}_E$ , we add a rule

$$Q_E(x, y) \leftarrow S_{q_f}(x, y)$$

Two-way queries can be captured by allowing two-way transitions.

# Linear Datalog vs. 2RPQs

So all 2RPQs can be expressed in linear Datalog  
Is the converse also true?

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Is the converse also true?

No. Counterexample:

$$\text{Query}(x, z) \leftarrow p_a(x, y) \wedge p_b(y, z)$$

$$\text{Query}(x, z) \leftarrow p_a(x, x') \wedge \text{Query}(x', z') \wedge p_b(z', z)$$

The linear Datalog program matches paths with labels from  $a^n b^n$

↪ context-free, non-regular language

↪ not expressible in (C2)RPQs

Intuition: linear Datalog generalises context-free languages

# Query Optimisation for C2RPQs

Recall the basic static optimisation problems of database theory:

- Query containment
- Query equivalence
- Query emptiness

Which of these are decidable for (C2)RPQs?

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Which of these are decidable for (C2)RPQs?

Observation: query emptiness is trivial

# Containment for RPQs

Containment of Regular Path Queries corresponds to containment of regular expressions  $\rightsquigarrow$  known to be decidable in PSPACE

Proof sketch for checking  $E_1 \sqsubseteq E_2$ :

- (1) Construct non-deterministic automata (NFAs),  $A_1$  and  $A_2$  for the regular expressions  $E_1$  and  $E_2$ , respectively
- (2) Construct an automaton  $\bar{A}_2$  that accepts the complement of  $A_2$ .
- (3) Construct the intersection  $A_1 \cap \bar{A}_2$  of  $A_1$  and  $\bar{A}_2$
- (4) Check if  $A_1 \cap \bar{A}_2$  accepts a word (if yes, then there is a counterexample that disproves  $E_1 \sqsubseteq E_2$ ; if no, then the containment holds)

Complexity estimate:

$A_1 \cap \bar{A}_2$  is exponential (blow-up by powerset construction in step (2)) but step (4) is possible by checking reachability on the state graph

$\rightsquigarrow$  NL algorithm on an exponential state graph

$\rightsquigarrow$  NPSPACE algorithm (construct the state graph on the fly)

$\rightsquigarrow$  PSPACE algorithm (Savitch's Theorem)

# Containment for (C)2RPQs

Things are more tricky when adding converses and conjunctions

## Theorem

- Containment of 2RPQs is  $PSPACE$ -complete
- Containment of C2RPQs is  $EXPSpace$ -complete

The proofs are more involved.

Automata-theoretic constructions are used, but with more complicated automata models and for somewhat different languages (there is no good “language of possible C2RPQ matches on a graph”  $\rightsquigarrow$  consider language of possible proofs instead)



# Query Optimisation for Path Queries

Decidable in  $PSPACE$  (2RPQs) and  $EXPSpace$  (C2RPQs)

Should be compared to linear Datalog:

## Theorem

Query containment for linear Datalog queries is undecidable.

Proof: see Lecture 11 (Post Correspondence Problem in Datalog – in fact, in linear Datalog)

Essentially no adoption in practice

↪ maybe the complexities are too high . . .

↪ or maybe path query optimisers are just too primitive

# Path Queries: Final Remarks on Expressivity

We have seen that C2RPQs are NL-complete for data

↪ can all NL-complete queries be captured by a C2RPQ?

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We have seen that C2RPQs are NL-complete for data

~> can all NL-complete queries be captured by a C2RPQ?

No. For many reasons.

- C2RPQs have no disjunction (~> Unions of C2RPQs)
- C2RPQs have no negation

FO-queries with a binary transitive closure operator capture NL

Several (regular) extensions of path queries:

- Nested unary 2RPQs in regular expressions (“test operators”)
- Nested binary C2RPQs in regular expressions
- Other more expressive fragments of “regular Datalog”, e.g.,  
Monadically Defined Queries

# Summary and Outlook

Graph databases as an important class of “noSQL” databases

Two main data models

- Resource Description Framework (RDF)
- Property Graph

Path queries as common foundation of all graph query languages

- higher data complexities than CQs/FO queries
- lower complexities than Datalog queries
- decidable query optimisation

Next topics:

- Applications
- Summary