# Efficient Model Construction for Horn Logic with VLog: System Description

Jacopo Urbani<sup>1</sup>, Markus Krözsch<sup>2</sup>, Ceriel Jacobs<sup>1</sup>, Irina Dragoste<sup>2</sup>, <u>David Carral<sup>2</sup></u>

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## Definition

**a** . . .

Existential rules are expressions of the form

$$\forall \vec{x} (B_1 \land \ldots \land B_k \to \exists \vec{v}. H_1 \land \ldots \land H_l)$$

## Practical relevance

Existential rules are **very useful** in several scenarios:

- Ontological reasoning
- Data integration
- Query answering
- Knowledge base completion

## Scientific Importance

They are **studied** in several communities

- Databases
- Logic programming
- Semantic Web
- . . .

### The computation of existential rules requires the introduction of fresh individuals

#### Example

A common rule that captures part-whole relationship is:

$$Bicycle(x) \rightarrow \exists v.hasPart(x,v) \land Wheel(v)$$

When we instantiate the head, x is known but v is not. We must introduce new values for it.

The **chase** is a class of reasoning algorithms for existential rules where rules are applied bottom-up until saturation thus resulting in the computation of a **universal model**. Such a model can then be used to directly solve **query answering**.

Warning: The chase may not always terminate.

- Unfortunately, **detecting termination is undecidable**.
- Detecting termination of a set of rules with respect to **any set of facts is not even semi-decidable**.
- Fortunately, **decidable criteria** that are sufficient for termination characterise many real-world ontologies.

r - a rule  $eta o \exists ec v. \eta$ D - a database  $\sigma$  - a substitution mapping variables in  $\beta$ to constants  $\langle r, \sigma \rangle$  - applicable to D if  $\beta \sigma \subseteq D$ 

#### Chase step: apply rule $\mathbf{r}$ to a database D

In each chase step, a single rule is being applied, with all possible substitutions.

#### The Chase

a sequence  $D^0, D^1, \ldots$  of databases where  $D^{i+1} = D^i \cup \Delta^{i+1}$  $\Delta^{i+1} =$ all new derivations produced by a certain rule r in step i + 1. The **Skolem chase** and **restricted** chase are two popular chase algorithms.

frontier(r) - all variables in the rule body that also appear in the rule head.

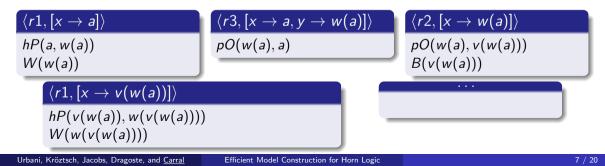
#### Skolem chase

A pair  $\langle r, \sigma \rangle$  is not applied during the computation of the chase if  $\langle r, \sigma' \rangle$  for some  $\sigma' \supseteq \sigma_{frontier(r)}$  has already been applied.

#### Restricted chase

A pair  $\langle r, \sigma \rangle$  is not applied a database D if there is a substitution  $\pi \supseteq \sigma_{frontier(r)}$  that already satisfies the rule with respect to D.

$$\begin{aligned} r1 &= Bicycle(x) \rightarrow \exists w.hasPart(x,w) \land Wheel(w) \longmapsto B(x) \rightarrow hP(x,w(x)) \land W(w(x)) \\ r2 &= Wheel(x) \rightarrow \exists v.partOf(x,v) \land Bicycle(v) \longmapsto W(x) \rightarrow pO(x,v(x)) \land B(v(x)) \\ r3 &= hasPart(x,y) \rightarrow partOf(y,x) \\ D &= \{Bicycle(a)\} \end{aligned}$$



- $r1 = Bicycle(x) \rightarrow \exists w.hasPart(x, w) \land Wheel(w) \longmapsto B(x) \rightarrow hP(x, w(x)) \land W(w(x))$   $r2 = Wheel(x) \rightarrow \exists v.partOf(x, v) \land Bicycle(v) \longmapsto W(x) \rightarrow pO(x, v(x)) \land B(v(x))$  $r3 = hasPart(x, y) \rightarrow partOf(y, x)$
- $D = \{Bicycle(a)\}$

$\langle r1, [x \to a] \rangle$ $\exists w.hP(a, w) \land W(w)?$	$egin{aligned} &\langle r3, [x  ightarrow a, y  ightarrow w(a)]  angle \ & ho O(w(a), a) \end{aligned}$	$\langle r2, [x \to w(a)] \rangle$ $\exists v.  ho O(w(a), v) \land B(v)?$
hP(a, w(a)) W(w(a))		$\Delta^3 = \emptyset$ $D^3 = D^\infty$

- State-of-the-art performance, with excellent memory footprint and scalability
- Implements the restricted and Skolem chase with a distinctive "set-at-a-time" processing
- Freely available and easy to use

# Outline First, we will first take a look at the performance Then, we will discuss how we achieved it Finally, we will illustrate how the system can be used

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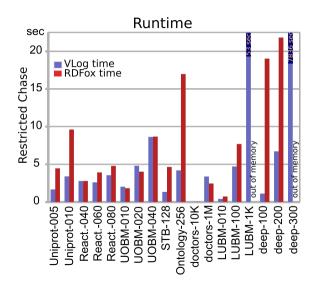
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# VLog: Performance

Considered datasets from a recent **chase benchmark** (PODS'17) and popular real-world OWL ontologies.

Size of the rulesets: *16-1300 rules* Size of the datasets: *1000-130M facts* 

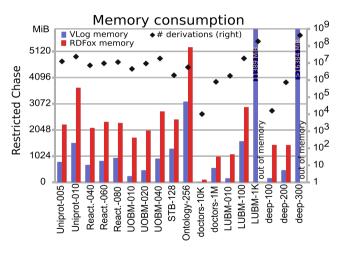
As competitor, we chose *RDFox*: A leading tool that outperforms other state-of-the-art engines such as E, DLV, GRAAL, and LLUNATIC.



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**Algorithm 1:** applyRule (rule r,database  $D^i$ )

1 foreach match  $\sigma$  of the body of r over  $D^i$ , produced since the last application of r do 2 | if the head of r is not satisfied by  $\sigma$  on  $D^i$  then 3 | create fresh nulls for existential variables in r

4 compute  $\Delta^{i+1}$  as the new facts produced by r

5 return  $D^{i+1} = D^i \cup \Delta^{i+1}$ 

#### Challenges:

- Line 1: If the rule body is a conjunction of atoms, then expensive joins might be required
- Line 4: Removing duplicates might be an expensive operation

The key idea of VLog is to store the facts column-by-column rather than row-by-row.

#### Example

Consider the atom hasPart(x, y) in our previous example and assume there are two facts hasPart(a, b) and hasPart(c, d). In VLog, these facts are stored with two columns  $c_1 = \langle a, c \rangle$  and  $c_2 = \langle b, d \rangle$ .

## Why is it a good idea?

- Line 1: Columns are kept **sorted** (whenever possible) to allow merge joins. Some operations on facts can be translated as operations on columns.
- Line 4: In some cases, we can infer whether a set of facts is already derived *without* checking fact-by-fact.
- Moreover, columns can be **compressed** more easily, or can be **reused**.

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# VLog: Usability

## Usability

- $\bullet$  Tool written in C++
  - $\rightarrow$  Used as standalone program
- $\bullet$  It can also be accessed through a web interface  $\rightarrow$  allows an interactive usage and extensive debugging
- We provide comprehensive Java API
  - $\rightarrow$  Easily embedded in other systems
  - $\rightarrow$  Automatically transforms OWL ontologies to rules

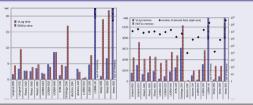
## Other technical features

- Works on all major OS with very few dependencies; Docker image provided
- It can interface concurrently with several data sources: high-performance RDF stores, relational databases, CSV files, RDF files, OWL ontologies, and remote SPARQL endpoints → allows federated reasoning

# Conclusions

VLog: large-scale rule reasoner with excellent performance.

## High-Performance



### Where can I find it?

GitHub: (Core system) https://github.com/karmaresearch/vlog (Java API) https://github.com/knowsys/vlog4j Maven: org.semanticweb.vlog4j Docker: karmaresearch/vlog

#### We are looking for new application areas!

Urbani, Kröztsch, Jacobs, Dragoste, and Carral

Columnar Approach to ReasoningMore possibilities for compression

• Set-at-a-time processing

Quick duplicates deletion

Efficient joins

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# Supported Data Sources

- Relational databases (MySQL, MonetDB and a generic ODBC source). A predicate is mapped to a single relational table.
- **Trident**, which is a **high-performance** in-house **RDF graph** engine. Maps the RDF triples to a ternary predicate.
- (zipped) **CSV files**. Maps to a predicate whose arity corresponds to the number of columns in the CSV table. The table is loaded into main memory and dictionary-encoded.
- (zipped) **RDF files** can be loaded directly into main memory, without being stored in a database. The tripes are mapped to a ternary predicate. Alternatively, they can be automatically translated into unary and binary facts (*vlog4j-owlapi* module).
- **OWL** ontologies (input trough OWL API) are automatically transformed to in-memory **rules** and **facts** using *vlog4j-owlapi* module.
- In-memory Java objects that represent facts.
- **Remote SPARQL endpoints**. A predicate maps to a user-defined SPARQL query. Can be used to access local graph databases, or for federated query answering on the Web.