



TECHNISCHE
UNIVERSITÄT
DRESDEN

DEDUCTION SYSTEMS

Optimizations for Tableau Procedures

Sebastian Rudolph

Agenda

- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Optimizations

- Naïve implementation not performant enough
 - \mathcal{T} -regel adds one disjunction per axiom to the corresponding node
 - ontologies may contain > 1.000 axioms and tableaux may contain thousands of nodes

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 - (Lazy) unfolding
 - Absorbtion
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 - Simplification and Normalization
 - Caching
 - Heuristics
 - ...

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Unfolding

- \mathcal{T} -rule is not necessary if \mathcal{T} is **unfoldable**, i.e., every axiom is:
 - **definitorial**: form $A \sqsubseteq C$ or $A \equiv C$ for A a concept name
($A \equiv C$ corresponds to $A \sqsubseteq C$ and $C \sqsubseteq A$)
 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A

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 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A
- If \mathcal{T} is unfoldable, the TBox can be (**unfolded**) into a concept

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

\mathcal{T} :

$$A \sqsubseteq B \sqcap \exists r.C$$

$$B \equiv C \sqcup D$$

$$C \sqsubseteq \exists r.D$$

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$$\begin{aligned} \mathcal{T}: \\ & A \sqsubseteq B \sqcap \exists r.C \\ & B \equiv C \sqcup D \\ & C \sqsubseteq \exists r.D \end{aligned}$$

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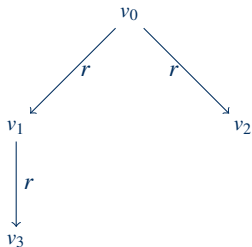
- A is satisfiable w.r.t. \mathcal{T} iff

$$A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$$

is satisfiable w.r.t. the empty TBox

Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$:



$$L(v_0) = \{U, A, (C \sqcap \exists r.D) \sqcup D, \\ \exists r.(C \sqcap \exists r.D), C \sqcap \exists r.D, \\ C, \exists r.D\}$$

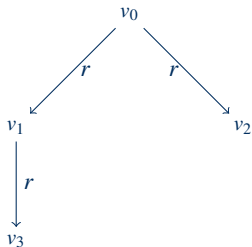
$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

$$L(v_2) = \{D\}$$

$$L(v_3) = \{D\}$$

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Only one disjunctive decision left!

Lazy Unfolding

- computation of NNF together with unfolding may decrease performance, e.g.:
 - satisfiability of $C \sqcap \neg C$ w.r.t. $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
 - unfolding: $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$

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 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$
 - better: apply NNF and unfolding if needed, via corresponding tableau rules:
 - $A \equiv C \rightsquigarrow A \sqsubseteq C$ and $A \supseteq C$
- \sqsubseteq -rule: For $v \in V$ such that $A \sqsubseteq C \in \mathcal{T}$, $A \in L(v)$ and $C \notin L(v)$
let $L(v) := L(v) \cup C$.
- \supseteq -rule: For $v \in V$ such that $A \supseteq C \in \mathcal{T}$, $\neg A \in L(v)$ and $\neg C \notin L(v)$
let $L(v) := L(v) \cup \{\neg C\}$.
- \neg -rule: For $v \in V$ such that $\neg C \in L(v)$ and $\text{NNF}(\neg C) \notin L(v)$,
let $L(v) := L(v) \cup \{\text{NNF}(\neg C)\}$.

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 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \sqsupseteq -rules
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 - \mathcal{T}_g is treated via the \mathcal{T} -rule
- absorption decreases \mathcal{T}_g and increases \mathcal{T}_u
 - 1 take an axiom from \mathcal{T}_g , e.g., $A \sqcap B \sqsubseteq C$
 - 2 transform the axiom: $A \sqsubseteq C \sqcup \neg B$
 - 3 if \mathcal{T}_u contains an axiom of the form $A \equiv D$ ($A \sqsubseteq D$ and $D \supseteq A$), then $A \sqsubseteq C \sqcup \neg B$ cannot be absorbed; $A \sqsubseteq C \sqcup \neg B$ remains in \mathcal{T}_g
 - 4 otherwise, if \mathcal{T}_u contains an axiom of the form $A \sqsubseteq D$, then absorb $A \sqsubseteq C \sqcup \neg B$ resulting in $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u

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 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u
- If $A \equiv D \in \mathcal{T}_u$, try rewriting/absorption with other axioms in \mathcal{T}_u
- nondeterministic: $B \sqsubseteq C \sqcup \neg A$ also possible

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Dependency-Directed Backtracking

- despite those optimizations, search space often to big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

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$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$$

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v	\sqcap -rule	$L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$
r	\sqcup -rule	$L(v) := L(v) \cup \{C_1\}$
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~~$$\begin{array}{l} \sqcup\text{-rule} \\ \exists\text{-rule} \\ \forall\text{-rule} \end{array} \quad \begin{array}{l} L(w) \\ L(w) \\ L(w) \end{array} := \begin{array}{l} L(v) \cup \{C_n\} \\ \{\neg A\} \\ \{\neg A, A\} \text{ clash} \end{array}$$~~

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v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n),$ $\exists r. \neg A, \forall r. A\}$
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$
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- exponentially big search space is traversed

Dependency-Directed Backtracking

- goal: recognize bad branching decisions quickly and do not repeat them

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- backjumping works roughly as follows:
 - concepts in the node label are tagged with a set of integers (dependency set) allowing to identify the concept's "origin"
 - initially, all concepts are tagged with \emptyset
 - tableau rules combine and extend these tags
 - \sqcup -rule adds the tag $\{d\}$ to the existing tag, where d is the \sqcup -depth (number of \sqcup -rules applied by now)
 - when encountering a contradiction, the labels allow to identify the origin of the concepts causing the contradiction
 - jump back to the last **relevant** application of a \sqcup -rule

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 - when encountering a contradiction, the labels allow to identify the origin of the concepts causing the contradiction
 - jump back to the last **relevant** application of a \sqcup -rule
- irrelevant part of the search space is not considered

Dependency-Directed Backtracking Example

$$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v) \quad \text{tagged with } \emptyset$$

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v		\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n),$	all with \emptyset
				$\exists r. \neg A, \forall r. A\}$	
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
		\vdots	\vdots	\vdots	
r					
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
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w		\forall -rule	$L(w) :=$	$\{\neg A, A\}$ clash	$\neg A$ tagged with mit \emptyset

- $\text{tag}(A) \cup \text{tag}(\neg A) = \emptyset$

Dependency-Directed Backtracking Example

		$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$		tagged with \emptyset
v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
	\vdots	\vdots	\vdots	
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- Output **false** (unsatisfiable)

Agenda

- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, z.B., $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$, $\forall r. C \equiv \neg \exists r. \neg C$
 - simplification, e.g., $\sqcap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r. \perp \equiv \perp$, $\forall r. \top \equiv \top$

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Optimizing Classification

One of the most wide-spread tasks for automated reasoning is **classification**

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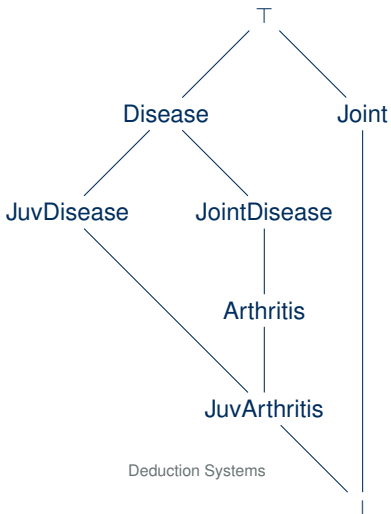
- compute all subclass relationships between atomic concepts in \mathcal{T}
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 - \rightsquigarrow if \mathcal{T} is satisfiable: subsumption does not hold (as we have constructed a counter-model)
 - \rightsquigarrow if \mathcal{T} is unsatisfiable: subsumption holds (no counter-model exists)
- naïve approach needs n^2 subsumption checks for n concept names
- normally cached in the **concept hierarchy** graph

Concept Hierarchy Graph



Optimizing Classification

most wide-spread technique is called [enhanced traversal](#)

Optimizing Classification

most wide-spread technique is called **enhanced traversal**

- hierarchy is created incrementally by introducing concept after concept

Optimizing Classification

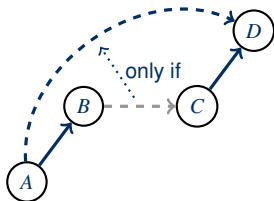
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- bottom-up phase: recognize direct subconcepts

Optimizing Classification

most wide-spread technique is called **enhanced traversal**

- hierarchy is created incrementally by introducing concept after concept
- top-down phase: recognize direct superconcepts
- bottom-up phase: recognize direct subconcepts
- transitivity of \sqsubseteq used to save checks



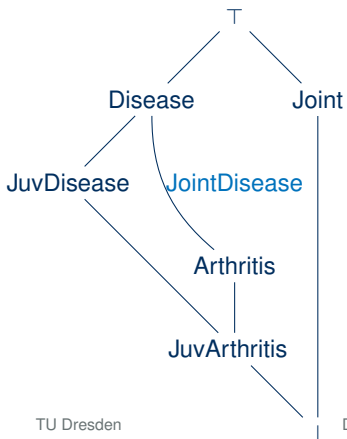
- If $A \sqsubseteq B$ and $C \sqsubseteq D$ hold,
- then $B \sqsubseteq C \rightarrow A \sqsubseteq D$
- and $A \not\sqsubseteq D \rightarrow B \not\sqsubseteq C$

Enhanced Traversal Example

already created hierarchy:

Goal: insertion of JointDisease

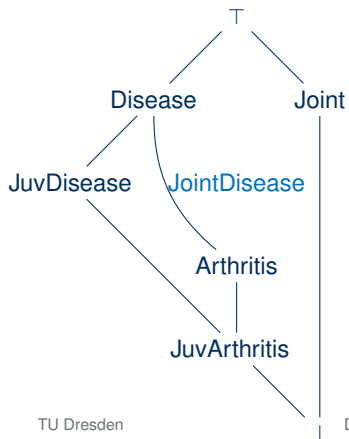
Top-Down Phase:



Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

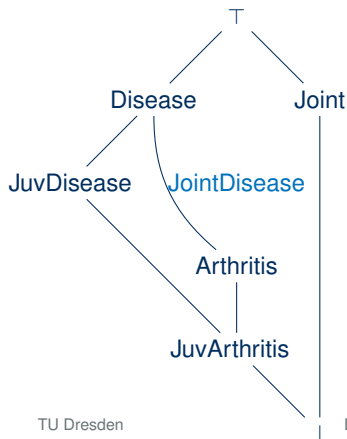
Top-Down Phase:

- JointDisease \sqsubseteq ? Disease

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

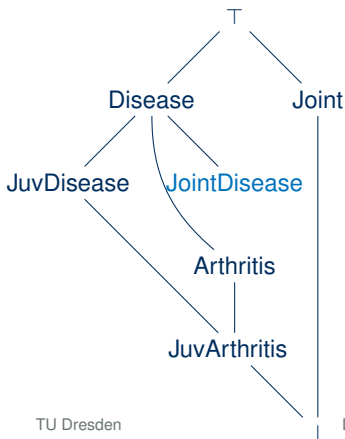
Top-Down Phase:

- JointDisease \sqsubseteq Disease
- JointDisease $\sqsubseteq^?$ JuvDisease

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

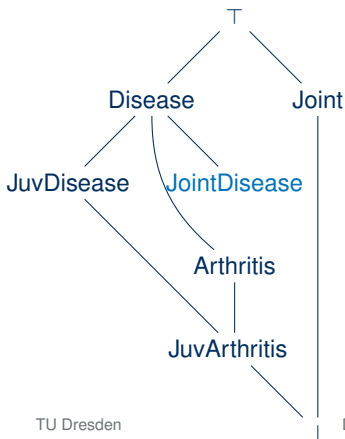
Top-Down Phase:

- JointDisease \sqsubseteq Disease
- JointDisease $\not\sqsubseteq$ JuvDisease
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Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

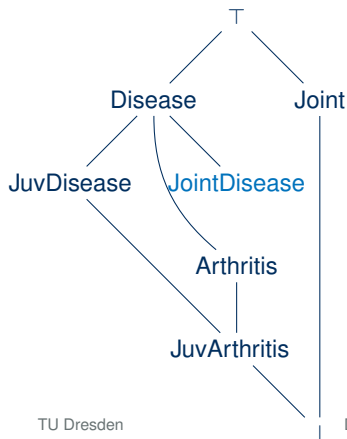
Top-Down Phase:

- JointDisease \sqsubseteq Disease
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- JointDisease $\sqsubseteq^?$ Joint

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

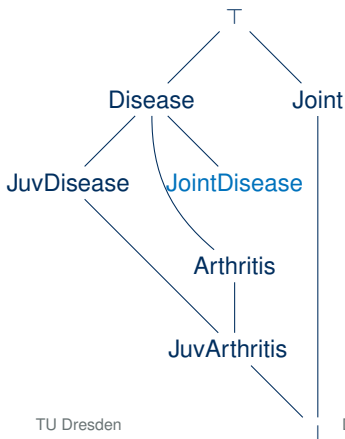
- JointDisease \sqsubseteq Disease
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Bottom-Up Phase:

- JuvArthritis $\sqsubseteq?$ JointDisease

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

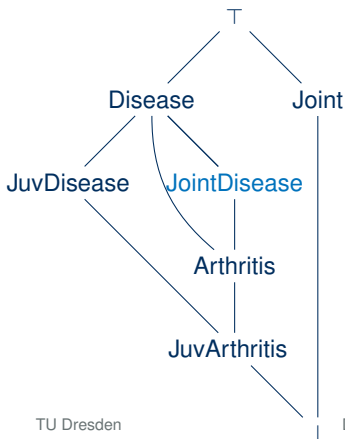
- JointDisease \sqsubseteq Disease
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Bottom-Up Phase:

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- JuvDisease \sqsubseteq ? JointDisease

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

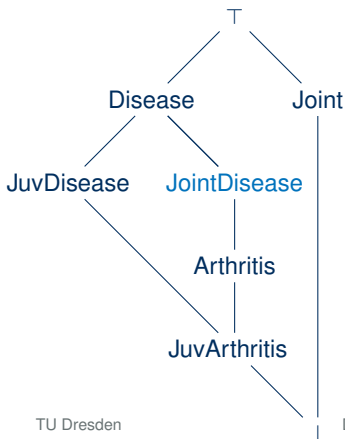
- $\text{JointDisease} \sqsubseteq \text{Disease}$
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- Arthritis \sqsubseteq JointDisease

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Summary

- we have a tableau algorithm for \mathcal{ALCF} knowledge bases
 - ABox treated like for \mathcal{ALC}
 - number restrictions are treated similar to functionality and existential quantifiers
- termination via cycle detection
 - becomes harder as the logic becomes more expressive
- naive tableau algorithm not sufficiently performant
- diverse optimizations improve average case
- specific methods for classification
 - enhanced traversal
- tableaux algorithms or variants modifications thereof are the basis of OWL reasoners