# An Efficient Encoding of the at-most-one Constraint 

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# An Efficient Encoding of the at-most-one Constraint 

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#### Abstract

One of the most widely used constraint during the process of translating a practical problem into an equivalent SAT instance is the at-most-one ( $A M O$ ) constraint. Besides a brief survey of well-known $A M O$ encodings, we will point out the relationship among several $A M O$ encodings - the relaxed ladder, sequential, regular and ladder encodings. Therefore, it could help SAT community, especially researchers working in SAT encoding to avoid confusing among these encodings. The major goal of this paper is to propose a new encoding for the $A M O$ constraint, named the bimander encoding which can be easily extended to cardinality constraints. Experimental results reveal that the proposed method is a significantly competitive one among other recently efficient methods. We will prove that the bimander encoding allows the unit propagation to achieve arc consistency. Furthermore, we will show that one of special case of bimander encoding outperforms the binary encoding, a well-known AMO encoding, in all experiments.


## 1 Introduction

Boolean Satisfiability problem (SAT) has been significantly investigated for the last two decades. SAT solving comprises two essential phases: encoding a certain problem into an equivalent SAT instance, and then solving the resulting instance by advanced SAT solvers. Compared with considerable improvements in the design and implementation of SAT solvers, in the last decade the progress on SAT encoding has been very limited. Moreover, different encodings when translating a Constraint Satisfaction Problem (CSP) into a SAT instance can get different sizes and difficulties of the resulting CNF formula.

Generally, it is well-known that no particular encoding performs better than others, whereas the following aspects of an encoding are always considered:

- the number of clauses required;
- the number of auxiliary variables required; and
- the strength of the encoding in terms of performance of unit propagation in SAT solvers.

The most natural and common way to translate a CSP is the direct encoding (see [1]). The direct encoding requires the at-least-one ( $A L O$ ) and at-most-one
( $A M O$ ) constraints to let one CSP variable to assign exactly one value. While the $A L O$ constraint is trivial to translate to a single clause, the $A M O$ constraint is more complicated and it has been intensively studied ([2/3|4|5|6]). The AMO constraint, as its name, requires that at most one of $n$ propositional variables is allowed to be $T R U E$, shortly denoted by $\leq_{1}\left(X_{1}, \ldots, X_{n}\right)$. Interest of the AMO constraint has increased to meet requirements of different applications, such as computer motographs [7], partial Max-SAT [8, and cardinality constraints [3].

Inspired by many interesting and recent results 2|34], especially when Prestwich used the binary $A M O(X)$ encoding 910 to solve successfully many large instances with a standard SAT local search method [5]6, after surveying several of well-known methods of the $A M O$ constraint, we will introduce a new way of encoding this constraint.

In the brief survey, we will point out the identity of three $A M O$ encodings -the relaxed ladder, the sequential and the regular encodings. These encodings are exact the ladder encoding after removing redundant clauses. Therefore, it could help SAT community, especially researchers working in SAT encoding to avoid confusing among these encodings.

The new encoding, named the bimander encoding, requires $\frac{n^{2}}{2 m}+n \log _{2} m-\frac{n}{2}$ binary clauses, and $\log _{2} m(1 \leq m \leq n)$ additional variables, where $m$ is the number of disjointed subsets by dividing from the original set of $n$ Boolean variables $\left\{X_{1}, \ldots, X_{n}\right\}$. Additionally, the bimander encoding can be easily extended to cardinality constraints, $\leq k\left(X_{1}, \ldots, X_{n}\right)$, which expresses that there are no more than $k$ of the $n$ Boolean variables $X_{i}, 1 \leq i \leq n$, assigned simultaneously to TRUE values. To the best of our knowledge, our encoding is the one that requires least number of additional variables among known encoding methods, except for the pairwise encoding which needs no additional variables. With respect to scalability, the bimander encoding can be adjusted by changing the number of subsets $m$ to get a suitable encoding. For example, by setting the parameter $m$ to specific values, the binary and pairwise encodings can be expressed as special cases of the bimander encoding. Interestingly, a special case of the bimander encoding, setting $m=\left\lceil\frac{n}{2}\right\rceil$, outperforms the binary encoding, a well-known encoding, in all our experiments. It is important to note that our encoding allows unit propagation $(U P)$ to preserve arc consistency.

The structure of the paper is as follows. In Section 2, we briefly represent efficient and recent approaches to encode the $A M O$ constraint. In Section 3 we describe the new encoding for the $A M O$ constraint, the so-called bimander encoding. In section 4, we compare the bimander encoding with others through experiments. Finally, we give conclusions and future research works in Section 5.

## 2 Existing Encodings

Before giving a brief survey of almost all of well-known existing $A M O$ encodings of SAT encoding, we first define notions and notations, mainly following [3].

Let $X_{i}, 1 \leq i \leq n$, be Boolean variables; let $A$ be a possibly empty set of auxiliary Boolean variables supporting the encoding; and let $\phi(X, A)$ be an encoding of $\leq_{1}\left(X_{1}, \ldots, X_{n}\right)$. The encoding $\phi(X, A)$ is correct if and only if:

- any assignment $\alpha$ that satisfies $\leq_{1}\left(X_{1}, \ldots, X_{n}\right)$ can be extended to a complete assignment that satisfies $\phi(X, A)$, and
- for any (partial) assignment $\hat{x}$ to $X=\left(X_{1}, \ldots, X_{n}\right)$ in which if $\hat{x}$ has more than one literals assigned TRUE values, unit propagation $U P$ detects a conflict (generating an empty clause).

On the SAT side, $U P$ plays a crucial role in SAT solver by being a major deduction in DPLL [11|12], whereas on the CSP side, arc consistency is the most important technique since it is the best trade-off between the amount and the cost of pruning. Therefore, when translating a CSP instance into an equivalent SAT instance, in order to know how powerful the performance of $U P$ of that encoding is, one should pay much attention to determine whether $U P$ of the equivalent SAT instance enforces arc consistency property.

UP of a SAT encoding of $\leq_{1}\left(X_{1}, \ldots, X_{n}\right)$ constraints achieves the same pruning as arc consistency on the original CSP if:

- whenever any variable $X_{i}, 1 \leq i \leq n$, is assigned to $T R U E$, all the other variables must be forced to the values $F A L S E$ under UP.

In following sections, generally $A M O(X), A L O(X)$ and $E O(X)$ denote the at-most-one, at-least-one and Exactly-One constraint, respectively for the set of positional variables $X$. Furthermore, for the sake of convenience, we will illustrate those encoding on a running example through the set consisting 8 Boolean variable, $X=X_{1}, \ldots, X_{8}$.

We briefly represent several well-known and efficient encodings of the $\leq_{1}$ $\left(X_{1}, \ldots, X_{n}\right)$ constraint. Some notations used was taken from 3 and we give comments for each encoding if they are necessary.

### 2.1 The Pairwise Encoding

There are several different names of this encoding: the naive encoding [13|2], the pairwise encoding 14]6, and the binomial encoding [3]. In this paper, we refer to it as the pairwise encoding. The idea of this encoding is to express that no possible combinations of two variables are simultaneously $T R U E$, therefore as soon as one literal is $T R U E$, the all others must be $F A L S E$ :

$$
\bigwedge_{i=1}^{n-1} \bigwedge_{j=i+1}^{n}\left(\bar{X}_{i} \vee \bar{X}_{j}\right)
$$

In the running example, the pairwise encoding produces the following clauses:

$$
\begin{array}{r}
\bar{X}_{1} \vee \bar{X}_{2}, \bar{X}_{1} \vee \bar{X}_{3}, \bar{X}_{1} \vee \bar{X}_{4}, \ldots, \bar{X}_{1} \vee \bar{X}_{8} \\
\bar{X}_{2} \vee \bar{X}_{3}, \bar{X}_{2} \vee \bar{X}_{4}, \ldots, \\
\bar{X}_{3} \vee \bar{X}_{4} \vee \bar{X}_{8}, \ldots, \bar{X}_{3} \vee \bar{X}_{8} \\
\vdots \\
\bar{X}_{7} \vee \bar{X}_{8}
\end{array}
$$

The pairwise encoding is the most widely known one for encoding the $A M O$ constraint. Although this method does not need any auxiliary variables, it requires a quadratic number of clauses (see Table 11. Generally, this encoding performs acceptably well, particularly for small cases, but usually produces impractical large formulas which can be inferior to other methods, especially for encoding the At-Most-k constraint. Nevertheless, the pairwise encoding is not only commonly used in practical, but also easily combined with other encoding methods [24].

### 2.2 The Binary Encoding

Frisch et al. 9|0 firstly proposed the binary encoding (Prestwich independently named the bitwise encoding [6|15]), and Prestwich used this encoding to solve successfully a number of large instances with a standard SAT local search method [5]6.

New Boolean variables $\left.B_{1}, \ldots, B_{\left\lceil\log _{2} n\right\rceil}\right\rceil^{1}$ are introduced. The expected clauses are following: where $B_{j}$ ( or $\bar{B}_{j}$ ) is the bit $j$ of $i-1$ represented by a binary string is 1 (or 0 ).

$$
\bigwedge_{i=1}^{n} \bigwedge_{j=1}^{\left\lceil\log _{2} n\right\rceil}\left\langle\bar{X}_{i} \vee \phi(i, j)\right\rangle
$$

where $\phi(i, j)$ denotes $B_{j}$ (or $\bar{B}_{j}$ ) if the bit $j$ of $i-1$ represented by a binary string is 1 (or 0 ).

The running example is represented by the binary encoding as follows:

$$
\begin{array}{cccc}
\bar{X}_{1} \vee \bar{B}_{1} & \bar{X}_{2} \vee B_{1} & \bar{X}_{3} \vee \bar{B}_{1} \ldots & \bar{X}_{8} \vee B_{1} \\
\bar{X}_{1} \vee \bar{B}_{2} & \bar{X}_{2} \vee \bar{B}_{2} & \bar{X}_{3} \vee B_{2} \ldots & \bar{X}_{8} \vee B_{2} \\
\bar{X}_{1} \vee \bar{B}_{3} & \bar{X}_{2} \vee \bar{B}_{3} & \bar{X}_{3} \vee \bar{B}_{3} \ldots & \bar{X}_{8} \vee B_{3}
\end{array}
$$

The hidden idea is to create the different sequences of $\left\lceil\log _{2} n\right\rceil$-tuples $B_{j}, 1 \leq$ $j \leq\left\lceil\log _{2} n\right\rceil$, such that whenever any $X_{i}$ is assigned to $T R U E, 1 \leq i \leq n$, then we immediately infer that the other variables $X_{i^{\prime}}$ must be $F A L S E$, for any $i^{\prime} \neq i$. With this encoding $U P$ maintains arc consistency property.

[^0]
### 2.3 The Commander Encoding

Klieber and Kwon [2] described the commander encoding by dividing the set of Boolean variables $\left\{X_{1}, \ldots, X_{n}\right\}$ into $m$ disjointed subsets $G_{1}, \ldots, G_{m}$, and introducing a commander variable $c_{i}$ considered as a candidate of each group $G_{i}$, $1 \leq i \leq m$. The commander encoding requires the following clauses:

1. Exactly-One variable in each group, consisting $G_{i}$ and corresponding $\bar{c}_{i}$, is assiged to the TRUE value. Whereas the ALO constraint is trivial to translate to a single clause, $A M O$ can be encoded by any known methods :

$$
\bigwedge_{i=1}^{m}\left\langle E O\left(\bar{c}_{i} \cup G_{i}\right)\right\rangle=\bigwedge_{i=1}^{m}\left\langle A M O\left(\bar{c}_{i} \cup G_{i}\right)\right\rangle \wedge \bigwedge_{i=1}^{m}\left\langle A L O\left(\bar{c}_{i} \cup G_{i}\right)\right\rangle
$$

For the running example, we divide the set $X=\left\{X_{1}, \ldots, X_{8}\right\}$ into $m=4$ disjointed subsets: $G_{1}=\left\{X_{1}, X_{2}\right\}, G_{2}=\left\{X_{3}, X_{4}\right\}, G_{3}=\left\{X_{5}, X_{6}\right\}$ and $G_{4}=\left\{X_{7}, X_{8}\right\}$. Then, four Boolean variables $c_{1}, c_{2}, c_{3}$ and $c_{4}$ are introduced as a candidate of $G_{1}, G_{2}, G_{3}$ and $G_{4}$ respectively. Consequently, the commander produces the following clauses:

$$
A M O\left(\bar{c}_{1}, X_{1}, X_{2}\right) \wedge\left(\bar{c}_{1} \vee X_{1} \vee X_{2}\right) \wedge \cdots \wedge A M O\left(\bar{c}_{4}, X_{7}, X_{8}\right) \wedge\left(\bar{c}_{4} \vee X_{7} \vee X_{8}\right)
$$

2. At most one commander variable is assigned TRUE. This constraint can be encoded either by the pairwise encoding or by the commander method:

$$
\bigwedge_{i=1}^{m}\left\langle A M O\left(c_{i}\right)\right.
$$

The following clauses are generated in the running example:

$$
\left.A M O\left(c_{1}, c_{2}, c_{3}, c_{4}\right)\right\rangle
$$

Compared with the pairwise encoding, the commander encoding requires less the number of clauses, and introduces an acceptable number of new variables (see Table 11. The commander encoding also allows $U P$ to preserve arc consistency property.

### 2.4 The Product Encoding

Chen [4] proposed an encoding for AMO constraint, named the product encoding. Insteading of encoding the constraint consisting of $n$ propositional variables $\leq_{1}$ $\left(X_{1}, \ldots, X_{n}\right)$, he encoded the constraint consisting of corresponding $n$ point $\leq_{1}$ $\left\{\left(u_{i}, v_{j}\right), 1 \leq i \leq u, 1 \leq j \leq v, p \times q \geq n\right\}$. The hidden idea can be explained as follows:

1. Firstly mapping each variable $X_{k}, 1 \leq k \leq n$ onto one corresponding point $\left(u_{i}, v_{j}\right)$ where $u_{i} \in U=\left\{u_{1}, \ldots, u_{p}\right\}, v_{i} \in V=\left\{v_{1}, \ldots, v_{q}\right\}$.
2. Then the product encoding is represented:

$$
A M O(X)=A M O(U) \wedge A M O(V) \bigwedge_{1 \leq i \leq p, 1 \leq j \leq q}^{1 \leq k \leq n, k=(i-1) q+j}\left\langle\left(\bar{X}_{k} \vee u_{i}\right) \wedge\left(\bar{X}_{k} \vee v_{j}\right)\right\rangle
$$

whereas $A M O(U)$ and $A M O(V)$ can be encoded by either a recursive or another way.

Regard to the running example, we choose $p=3$ and $q=3$, and we use the paiwise encoding for $A M O(U)$ and $A M O(V)$. The derived clauses are as follows:

$$
\begin{aligned}
A M O(U): & \left(\bar{u}_{1} \vee \bar{u}_{2}\right) \wedge\left(\bar{u}_{1} \vee \bar{u}_{3}\right) \wedge\left(\bar{u}_{2} \vee \bar{u}_{3}\right) \\
A M O(V): & \left(\bar{v}_{1} \vee \bar{v}_{2}\right) \wedge\left(\bar{v}_{1} \vee \bar{v}_{3}\right) \wedge\left(\bar{v}_{2} \vee \bar{v}_{3}\right) \\
A M O(X)= & A M O(U) \wedge A M O(V) \wedge \\
& \left(\bar{X}_{1} \vee u_{1}\right) \wedge\left(\bar{X}_{1} \vee v_{1}\right) \wedge\left(\bar{X}_{2} \vee u_{2}\right) \wedge\left(\bar{X}_{2} \vee v_{1}\right) \wedge \\
& \left(\bar{X}_{3} \vee u_{3}\right) \wedge\left(\bar{X}_{3} \vee v_{1}\right) \wedge\left(\bar{X}_{4} \vee u_{1}\right) \wedge\left(\bar{X}_{4} \vee v_{2}\right) \wedge \\
& \left(\bar{X}_{5} \vee u_{2}\right) \wedge\left(\bar{X}_{5} \vee v_{2}\right) \wedge\left(\bar{X}_{6} \vee u_{3}\right) \wedge\left(\bar{X}_{6} \vee v_{2}\right) \wedge \\
& \left(\bar{X}_{7} \vee u_{1}\right) \wedge\left(\bar{X}_{7} \vee v_{3}\right) \wedge\left(\bar{X}_{8} \vee u_{2}\right) \wedge\left(\bar{X}_{8} \vee v_{3}\right)
\end{aligned}
$$

### 2.5 The Sequential Encoding

By building a count-and-compare hardware circuit and translating this circuit to an equivalent CNF formula, Sinz [13] introduced an encoding of $\leq_{k}\left(X_{1}, \ldots, X_{n}\right)$, namely the sequential encoding.

For the case $k=1$, the set of $A M O(X)$ clauses is followed:

$$
\begin{equation*}
\left(\bar{X}_{1} \vee s_{1}\right) \wedge\left(\bar{X}_{n} \vee \bar{s}_{n-1}\right) \bigwedge_{1<i<n}\left\langle\left(\bar{X}_{i} \vee s_{i}\right) \wedge\left(\bar{s}_{i-1} \vee s_{i}\right) \wedge\left(\bar{X}_{i} \vee \bar{s}_{i-1}\right)\right\rangle \tag{1}
\end{equation*}
$$

where $s_{i}, 1 \leq i \leq n-1$, are additional variables.
The running example is represented as follows:

$$
\begin{array}{ccc}
\bar{X}_{1} \vee s_{1} & & \\
\bar{X}_{2} \vee s_{2} & \bar{s}_{1} \vee s_{2} & \bar{X}_{2} \vee \bar{s}_{1} \\
\bar{X}_{3} \vee s_{3} & \bar{s}_{2} \vee s_{3} & \bar{X}_{3} \vee \bar{s}_{2} \\
\bar{X}_{4} \vee s_{3} & \bar{s}_{3} \vee s_{4} & \bar{X}_{4} \vee \bar{s}_{3} \\
\bar{X}_{5} \vee s_{4} & \bar{s}_{4} \vee s_{5} & \bar{X}_{5} \vee \bar{s}_{4} \\
\bar{X}_{6} \vee s_{5} & \bar{s}_{5} \vee s_{6} & \bar{X}_{6} \vee \bar{s}_{5} \\
\bar{X}_{7} \vee s_{6} & \bar{s}_{6} \vee s_{7} & \bar{X}_{7} \vee \bar{s}_{6} \\
\bar{X}_{8} \vee \bar{s}_{7} & &
\end{array}
$$

As Marques-Silva and Lynce [14] pointed out that the sequence $s_{1}, \ldots, s_{n-1}$ is of the form " $0 \ldots 01 \ldots 1$ " and whenever any Boolean variable $X_{i}$ is assigned to $T R U E$ (or 1 ), $1 \leq i \leq n$, consequently, under unit propagation all the other variables $X_{j}$ must be forced to $F A L S E$ (or 0 ), $1 \leq j \neq i \leq n$.

### 2.6 The Ladder Encoding

Gent and Nightingale used the ladder structure, originally proposed by Gent et al. [16], to describe a new encoding for the alldifferent constraint into SAT [17]. It was named the ladder encoding related to its ladder structure.

Without loosing the correctness property, we reverse the condition of $n-1$ additional Boolean variables, $s_{1}, \ldots, s_{n-1}$ in [1314 (in [17], $y_{1}, \ldots, y_{n-1}$ ) which satisfy the following ladder clauses:

$$
\begin{equation*}
\bigwedge_{i=1}^{n-2}\left(s_{i+1} \vee \bar{s}_{i}\right) \tag{2}
\end{equation*}
$$

and adds the channeling clauses:

$$
\begin{equation*}
\bigwedge_{i=1}^{n}\left\langle\left(s_{i} \wedge \bar{s}_{i-1}\right) \Longleftrightarrow X_{i}\right\rangle \tag{3}
\end{equation*}
$$

where

$$
\begin{equation*}
s_{0}=0 \wedge s_{n}=1 \tag{4}
\end{equation*}
$$

are set.
The idea hidden is simple. While the sequence $s_{1}, \ldots, s_{n-1}$ is a sequence of 0 's or more 1 's values, and the rest of variables assigned 1 values; i.e., the sequence $s_{1}, \ldots, s_{n-1}$ is of the form " $0 \ldots 01 \ldots 1$ " ( in 17, " $1 \ldots 10 \ldots 0$ "). Thus, there is at most one adjacent pair of variables $s_{i-1}$ and $s_{i}$ where $s_{i-1}=0 \wedge s_{i}=1,1 \leq i \leq n$. As soon as a variable $X_{i}$ is assigned to $T R U E, 1 \leq i \leq n$, and consequently, all the other variables $X_{j}$ are forced to $F A L S E, 1 \leq j \neq i \leq n$, under unit propagation.

By combining (2),(3) and (4) we obtain the following set of clauses:

$$
\begin{equation*}
\bigwedge_{i=1}^{n}\left\langle\left(\bar{s}_{i-1} \vee s_{i}\right) \wedge\left(\bar{s}_{i} \vee s_{i-1} \vee X_{i}\right) \wedge\left(\bar{X}_{i} \vee s_{i}\right) \wedge\left(\bar{X}_{i} \vee \bar{s}_{i-1}\right)\right\rangle \tag{5}
\end{equation*}
$$

We can prove easily that the clause $\left(\bar{s}_{i} \vee s_{i-1} \vee X_{i}\right)$ in (5) is redundant since it does not affect the correctness of the at-most-one constraint. Moreover, both the sequential encoding and the ladder encoding require the same $n-1$ additional Boolean variables. Now we realize that the sequential encoding is exact the ladder encoding without the redundant clauses.

Prestwich [6] supposed the relaxed ladder encoding which is the ladder encoding without these redundant clauses. It is easy to see that the relaxed ladder encoding and the sequential encoding are the same. Argelich et al. [18] also noticed that the sequential encoding is a reformulation of a regular encoding [19]. In fact, it is a simple matter to prove that the regular encoding and the ladder encodings are the same.

In conclusion, we shown that the two $A M O$ encodings -the relaxed ladder encoding and the sequential encoding are the same. These encodings are exact the ladder encoding or the regular encoding after removing redundant clauses. Interestingly, there are various related works. Tamura et al. used this structure for the order encoding in their SAT-based solving system [20]. Bailleux et al. [7] referred to this structure as the unary representation which was used during their translation of cardinality constraints and pseudo-Boolean constraints to SAT formulas ([7|21|22]).

Recently, Martins et. al [23] compared both encodings in their paper. Argelich et al. 18] compared two encodings of the alldifferent constraints, one based on the sequential encoding and the other based on the ladder encoding. To the best of our knowledge, we are not aware of any paper mentioning about the relationship among the ladder, sequential, relaxed ladder and regular encodings. We hope that this work could help the SAT community to recognize the similarities of these encodings.

## 3 The Bimander Encoding

The general idea of a new encoding is based on both the ideas of the binary encoding and the commander encoding. We refer to it as the bimander encoding.

Similarly to the commander encoding, with a given positive number $m, 1 \leq$ $m \leq n$, we partition a set of propositional variables $X=\left(X_{1}, \ldots, X_{n}\right)$ into $m$ disjoint subsets $G_{1}, \ldots, G_{m}$ such that each group $G_{i}, 1 \leq i \leq m$, consists $g=\left\lceil\frac{n}{m}\right\rceil$ variables. However, instead of introducing commander variables like in the commander encoding, we introduce a set of auxiliary Boolean variables $B_{1}, \ldots, B_{\left\lceil\log _{2} m\right\rceil}$ like in the binary encoding. The variables $B_{1}, \ldots, B_{\left\lceil\log _{2} m\right\rceil}$ play as the roles of the commander variables in the commander encoding.

The bimander encoding is the conjunction of the clauses obtained as follows:

1. At most one variable in each group can be TRUE. we encode this constraint for each group $G_{i}, 1 \leq i \leq m$, by using the pairwise method.

$$
\bigwedge_{i=1}^{m}\left\langle A M O\left(G_{i}\right)\right\rangle
$$

Regard to the running example, by chooding $m=\sqrt{n}=3$ we have:

$$
A M O\left(X_{1}, X_{2}, X_{3}\right) \wedge A M O\left(X_{4}, X_{5}, X_{6}\right) \wedge A M O\left(X_{7}, X_{8}\right)
$$

2. The following clauses are constraints between each variable in a group and commander variables:

$$
\bigwedge_{i=1}^{m} \bigwedge_{h=1}^{g} \bigwedge_{j=1}^{\left\lceil l o g_{2} m\right\rceil} \bar{X}_{i, h} \vee \phi(i, j)
$$

where $\phi(i, j)$ denotes $B_{j}$ (or $\bar{B}_{j}$ ) if the bit $j$ of $i-1$ represented by a unique binary string is 1 (or 0 ).
The following clauses are generated in the running example:

$$
\begin{array}{ccc}
\bar{X}_{1} \vee \bar{B}_{1} & \bar{X}_{4} \vee B_{1} & \bar{X}_{7} \vee \bar{B}_{1} \\
\bar{X}_{1} \vee \bar{B}_{2} & \bar{X}_{4} \vee \bar{B}_{2} & \bar{X}_{7} \vee B_{2} \\
\bar{X}_{2} \vee \bar{B}_{1} & \bar{X}_{5} \vee B_{1} & \bar{X}_{8} \vee \bar{B}_{1} \\
\bar{X}_{2} \vee \bar{B}_{2} & \bar{X}_{5} \vee \bar{B}_{2} & \bar{X}_{8} \vee B_{2} \\
\bar{X}_{3} \vee \bar{B}_{1} & \bar{X}_{6} \vee B_{1} & \\
\bar{X}_{3} \vee \bar{B}_{2} & \bar{X}_{6} \vee \bar{B}_{2} &
\end{array}
$$

Compared with the commander encoding, in the bimander encoding we do not add any constraints among the binary sequences since any combination of auxiliary Boolean variables $B_{1}, \ldots, B_{\left\lceil\log _{2} m\right\rceil}$ of a corresponding group is different from any combinations of all the other corresponding groups.

Let us first prove some important properties of the bimander encoding.
Correctness.
Now we assume that we have a partial assignment $x=\left(X_{1}, \ldots, X_{l}\right), 1 \leq l \leq n$, with at most one assigned variable to TRUE. For the case of none variables assigned to $T R U E$ value (all variables assigned $F A L S E$ ), then the first condition is trivially satisfied, so is the second condition. In the case of an existing one $X_{i}=T R U E, 1 \leq i \leq n$, there is a corresponding sequence of truth values assigned to $\left\{B_{1}, \ldots B_{\left\lceil l o g_{2} m\right\rceil}\right\}$. The second condition is satisfied as well. Therefore, the partial assignment $x$ can possibly be extended to a complete assignment that satisfies the two above conditions.

Suppose that we have a partial assignment $x=\left(X_{1}, \ldots, X_{l}\right), 1 \leq l \leq n$, with more than one assigned variables to TRUE, assuming that two of them are $X_{i}=T R U E$ and $X_{j}=T R U E, 1 \leq i \neq j \leq l$. Each of these two assignments force a corresponding pattern of truth values to be assigned to the sequence of $\left\{B_{1}, \ldots B_{\left\lceil l o g_{2} m\right\rceil}\right\}$. As a result, the sequence exists one propositional variable $B_{k}, 1 \leq k \leq\left\lceil\log _{2} m\right\rceil$, that is assigned both $T R U E$ and $F A L S E$. It is a contradiction!

Hence, if any partial assignment has more than one literal assigned TRUE values, then $U P$ produces an empty clause. It means that this partial assignment can not be extended to a complete assignment. In conclusion, the bimander encodes correctly the at-most-one constraint.

Propagation strength. Suppose that we have a partial assignment $x=\left(X_{1}, \ldots, X_{l}\right)$, $1 \leq l \leq n$, consisting exactly one variable set to TRUE. Now we will show that $U P$ forces all other variables to $F A L S E$. Indeed, we assume a variable $X_{i, j}=$ $T R U E$ which is the $j^{t h}$ variable in the group $G_{i}, 1 \leq i \leq m$, then this assignment forces a corresponding pattern of $T R U E$ values to $\left\{B_{1}, \ldots B_{\left\lceil l o g_{2} m\right\rceil}\right\}$. By following the first condition, all other variables in group $G_{i}$ are set to $F A L S E$. By following the second condition, all the other variables in group $G_{i^{\prime}}, 1 \leq i^{\prime} \neq i \leq m$ are set to $F A L S E$ since they have different patterns of $T R U E$ values $\left\{B_{1}, \ldots B_{\left\lceil\log _{2} m\right\rceil}\right\}$ of the corresponding $X_{i, j}=T R U E$. In conclusion, the unit propagation (UP) of the bimander encoding forces arc consistency property.

Complexity. As we mentioned, we need a set of $\left\lceil\log _{2} m\right\rceil$ additional Boolean variables. The first constraint encoding by the pairwise method requires $m$ * $\left[\frac{g(g-1)}{2}\right]=\frac{n\left(\frac{n}{m}-1\right)}{2}$ new clauses. The second constraint requires $m *\left[g * \log _{2} m\right]=$ $n *\left\lceil\log _{2} m\right\rceil$ clauses. Hence, the encoding uses $\frac{n\left(\frac{n}{m}-1\right)}{2}+n\left\lceil\log _{2} m\right\rceil=\frac{n^{2}}{2 m}+$ $n\left\lceil\log _{2} m\right\rceil-\frac{n}{2}$ clauses.

Related to scalability, it is interesting to note that the bimander encoding is a general case of several encodings. For example:

- the pairwise encoding is a special case of the bimander encoding when $m=1$;
- the commander encoding is a special case of the bimander encoding when $m=2$ (when both encodings divide into 2 subsets); and
- the binary encoding is a special case of the bimander encoding when $m=n$.

It is also important to note that the bimander encoding can be easily generalized to encode the At-Most-k constraint, which is described as follows.

1. At most $\boldsymbol{k}$ variables in each group can be true. We encode this constraint for each group $G_{i}, 1 \leq i \leq m$, by using the pairwise (or another) method.
2. The constraints between each variable in a group and commander variables are encoded by the following clauses:

$$
\bigwedge_{i=1}^{m} \bigwedge_{h=1}^{g} \bigvee_{l=1}^{k} \bigwedge_{j=1}^{\left\lceil\log _{2} m\right\rceil} \bar{X}_{i, h} \vee \phi(i, h, l, j)
$$

where $\phi(i, h, l, j)$ denotes $B_{l, j}$ (or $\bar{B}_{l, j}$ ) if the bit $j$ of $i-1$ represented by a binary string is 1 (or 0 ).

## 4 Comparisons and Experimental Evaluations

In this section, we first show almost known methods for the $A M O$ constraint. Then we compare our encoding with several common and efficient methods through experiments.

### 4.1 Comparisons

Table 1 presents a summary of main approaches of the $A M O$ encoding methods. The "Clauses" and "auxiliary Vars" columns show the number of clauses required and auxiliary variables corresponding to the methods. The "Con." column indicates that whether $U P$ of the corresponding encoding achieves the arc consistency property or not. The "Origin" column infers the original publication where the method had been introduced. We use $m$ to denote the disjointed subsets by dividing the set of Boolean variables $\left\{X_{1}, \ldots, X_{n}\right\}$ occurring in the bimander encoding.

Table 1. A summary of almost known methods of the $A M O$ encoding.

| Methods | Clauses | auxiliary Vars | Con. | Origin |
| :---: | :---: | :---: | :---: | :---: |
| pairwise | $\binom{n}{2}$ | 0 | AC | none |
| linear | $8 n$ | $2 n$ | search | $[24$ |
| totalizer | $O\left(n^{2}\right)$ | $O\left(n \log ^{2}(n)\right)$ | AC | $[7$ |
| binary | $n \log _{2} n$ | $\left\lceil\log _{2} n\right\rceil$ | AC | $[10]$ |
| sequential | $3 n-4$ | $n-1$ | AC | $[13$ |
| sorting networks | $O\left(n \log _{2}^{2} n\right)$ | $O\left(n \log _{2}^{2} n\right)$ | AC | $[21]$ |
| commander | $\sim 3 n$ | $\sim \frac{n}{2}$ | AC | $[2]$ |
| product | $2 n+4 \sqrt{n}+O(\sqrt[4]{n})$ | $2 \sqrt{n}+O(\sqrt[4]{n})$ | AC | $[4]$ |
| card. networks | $6 n-9$ | $4 n-6$ | AC | $[25]$ |
| PHFs-based | $n \log _{2} n$ | $\left\lceil\log _{2} n\right\rceil$ | AC | $[26$ |
| bimander | $\frac{n^{2}}{2 m}+n \log _{2} m-\frac{n}{2}$ | $\log _{2} m, 1 \leq m \leq n$ | AC | this paper |
| bimander $\left(m=\frac{n}{2}\right)$ | $n \log _{2} n-\frac{n}{2}$ | $\left\lceil\log _{2} n\right\rceil-1$ | AC | this paper |

With respect to the scalability, the bimander encoding can be adjusted to get a suitable encoding. In fact, the bimander encoding requires the least auxiliary variables, excepting the pairwise encoding, among known encoding methods. The totalizer encoding proposed by Bailleux al et. [7] requires clauses of size at most 3, and the commander encoding proposed by Klieber and Kwon [2] needs $m$ (number of disjointed subsets) clauses of size $\left\lceil\frac{n}{m}+1\right\rceil$, whereas the sequential, binary and bimander encodings require only binary clauses.

### 4.2 Experimental Evaluations

In order to evaluate the different encodings, we choose several difficult and wellknown problems which have been benchmarks not only on the CSP side, but also on the SAT side. These benchmarks have been used in the CSP-solvers and SAT-solvers competitions. Moreover, we take two different parameters $m$ for the bimander encoding, one is $m=\sqrt{n}$ and the other one is $m=\frac{n}{2}$.

We used Clasp 2 [27] which is one of among state-of-the-art SAT solvers [28]. All experiments were executed on a 2.66 Ghz , Intel Core 2 Quad processor with a memory limit of 3.8 GB running Ubuntu 10.04, and all runtimes are measured in seconds. The dashes mean that running times of instances were over timeout of 3600 seconds. The italic font designates the minimum time for a certain instance. We abbreviate pairwise, sequential, commander, binary, product encoding, and bimander encoding as $p w$, seq, cmd, bi, pro and bim respectively.

The Pigeon-Hole Problem This problem has been a common benchmark on the SAT and CSP sides. The goal of the problem is to prove that $p$ pigeons can not be fit in $h=p-1$ holes. We use this problem to compare the performance of the constraint $\leq_{1}\left(X_{1}, \ldots, X_{n}\right)$ of the various encodings, like Frisch and Giannaros [3], and Klieber and Kwon [2].

Table 2. A comparison of running times of well-known encodings performed by CLASP on unsatisfiable Pigeon-Hole problem. Runtimes reported are in seconds.

| method | pw | seq | cmd | bi | pro | bim |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| size |  |  |  |  |  | $m=\sqrt{n}$ | $m=\frac{n}{2}$ |
| 10 | 2.1 | 0.73 | 0.56 | 0.80 | 0.22 | 0.33 | 0.22 |
| 11 | 22.1 | 5.79 | 4.46 | 6.59 | 6.13 | 5.10 | 2.10 |
| 12 | 244.5 | 117.3 | 43.2 | 29.5 | 43.21 | 38.19 | 26.06 |
| 13 | - | 1604.1 | 352.5 | 142.6 | 736.2 | 546.9 | 64.91 |
| 14 | - | - | - | 1271 | - | - | 560 |

Table 2 shows that the Pigeon-Holes instances seem very hard to deal with. The bimander encoding performs the best for all cases followed by the binary encoding. The pairwise encoding is the worse.

The All-Interval Series Problem We take the All-Interval Series (AIS) problem as a benchmark in which the performance of an encoding is heavily influenced by the performance of encoding the $A M O$ constraint. AIS is one of classical CSPs and usually regarded as a difficult benchmark to find all solutions (see prob007 in [29]).

Table 3. A comparison of running times of well-known encodings performed by CLASP solver on the AIS problem. Runtimes reported are in seconds.

| method | pw | seq | cmd | bi | pro | bim |  | solutions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| size |  |  |  |  | $m=\sqrt{n}$ |  |  | $m=\frac{n}{2}$ |
| 7 | 0.05 | 0.03 | 0.02 | 0.02 | 0.05 | 0.01 | 0.02 | 32 |
| 8 | 0.56 | 1.07 | 0.6 | 0.2 | 0.49 | 0.6 | 0.6 | 40 |
| 9 | 5.33 | 8.9 | 0.37 | 0.27 | 5.61 | 0.3 | 0.24 | 120 |
| 10 | 61.7 | 104 | 1.7 | 1.58 | 60.7 | 1.95 | 1.46 | 296 |
| 11 | 972 | 1387 | 11.9 | 8.9 | 269 | 11.3 | 6.7 | 648 |
| 12 | - | - | 78 | 49 | - | 69 | 43 | 1328 |
| 13 | - | - | 517 | 356 | - | 504 | 276 | 3200 |
| 14 | - | - | 3200 | 2748 | - | 3537 | 2005 | 9912 |

Excepting for two small cases, Table 3 shows that the variant of the bimander encoding with $m=\frac{n}{2}$ significantly surpasses all the others. Moreover, for three last instances this variant performs in a reasonable time, whereas the pairwise and sequential encodings carry out more than 3600 seconds. The binary encoding gives rather good results. Another variant of the bimander encoding with $m=$ $\sqrt{n}$ and the commander encoding perform similarly. The pairwise, sequential and product encodings perform poorly.

The Langford Problem This problem is a classical one of CSPs (see prob024 in [29]) and it is used as a hard benchmark as well. The aim of problem is either to find all the sequences of $2 * n$ numbers $1,1,2,2, \ldots, n, n$, where there exists one number between the two $1 s$, and two numbers between the two $2 s$, and generally $k$ numbers between the two $k s$, or to prove that there are no solutions.

Table 4. A comparison of running times of well-known encodings performed by CLASP solver on the Langford problem. Runtimes reported are in seconds.

| method | pw | seq | cmd | bi | pro | bim |  | solutions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| size |  |  |  | $m=\sqrt{n}$ |  |  |  | $m=\frac{n}{2}$ |
| 8 | 0.03 | 0.04 | 0.03 | 0.05 | 0.04 | 0.04 | 0.04 | 150 |
| 9 | 0.24 | 0.25 | 0.25 | 0.24 | 0.37 | 0.23 | 0.26 | unsat |
| 10 | 1.65 | 1.88 | 1.65 | 1.87 | 2.03 | 1.60 | 2.02 | unsat |
| 11 | 7.2 | 7.6 | 7.5 | 12.5 | 7.2 | 8.93 | 12.2 | 17792 |
| 12 | 59.3 | 62.1 | 56.7 | 86.2 | 53.6 | 79.4 | 58.8 | 108144 |
| 13 | 2275 | 1328 | 1462 | 1955 | 1443 | 1927 | 1925 | unsat |
| 14 | 30842 | 14946 | 16204 | 21308 | - | 20125 | 19734 | unsat |

Table 4 shows that three encodings - binary, and two variants of bimander - show no clear difference. While the pairwise, and product encodings perform worse, the sequential tends to be the fastest one for two large cases in term of running time, and followed by the commander encoding.

The Quasigroup With Holes Problem Achlioptas et al. 30] introduced a method for generating satisfiable Quasigroup With Holes (QWHs) instances which are NP-hard and considered as a structured benchmark domain for the study of CSP and SAT. Moreover, the method can tune the generator to output hard problem instances. We experimented these QWHs instances with different levels of hardness.

Table 5. The running time comparison of several encodings performed by CLASP solver on QWH instances. Runtimes reported are in seconds.

| method | pw | seq | cmd | bi | pro | bim |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| size |  |  |  |  |  | $m=\sqrt{n}$ | $m=\frac{n}{2}$ |
| qwh.order30.holes320 | 0.46 | 0.28 | 0.23 | 0.25 | 0.23 | 0.20 | 0.22 |
| qwh.order35.holes405 | 3.6 | 3.5 | 10.3 | 6.5 | 5.7 | 1.6 | 2.1 |
| qwh.order40.holes528 | 134 | 115 | 124 | 120 | 241 | 58.9 | 159 |
| qwh.order40.holes544 | 39.2 | 14.5 | 47.8 | 123 | 46.7 | 70.8 | 154 |
| qwh.order40.holes560 | 121 | 65.3 | 55.6 | 119 | 33.1 | 21.2 | 53.2 |
| qwh.order33.holes381 | 58.7 | 435 | 174 | 94.2 | 108.0 | 12.7 | 92.3 |
| total | 356.96 | 633.58 | 411.93 | 462.95 | 434.73 | 165.4 | 460.82 |

As shown in Table 5, it is interesting to notice that the variant of the bimander encoding with $m=\sqrt{n}$ is clearly the best overall encoding in term of total runtime. Furthermore, except for the instance qwh.order40.holes544, this encoding is clearly faster than other encodings for all the other instances. Surprisingly, the pairwise encoding performs very well followed by the commander encoding. In general, the variant of the bimander encoding with $m=\frac{n}{2}$, the
binary and the product encoding are slightly similar. Although the sequential encoding carries out the instance qwh.order40.holes544 fastest, its performance is poor in overall.

Throughout above experiments, we shown that two variants of the bimander encoding, with certain parameters $m=\sqrt{n}$ and $m=\frac{n}{2}$, are very competitive. In particular, the variant with $m=\sqrt{n}$ performs significantly the best on QWH instances, and rather well on the other benchmarks, whereas the variant with $m=\frac{n}{2}$ is clear the best on the Pigeon-Hole problem, the AIS problem, and acceptable on the Langford problem.

## 5 Conclusions and Future Works

Inspired by being remarkably successful at solving hard and practical problems of SAT solving, many problems that were solved previously by other methods can now be solved more effectively by translating them to equivalent SAT problems, and using advanced SAT solvers to find solutions. During the encoding phase, one of the most important constraints, occurring naturally in a wide range of real world applications, is the at-most-one (AMO) constraint. Hence solving many problems gets benefits from the efficiency of the encoding of the $A M O$ constraint.

The paper has four contributions. Firstly, we pointed out that the ladder encoding exactly consists of the sequential encoding and a set of redundant clauses. Moreover, the relaxed ladder encoding [6] and the sequential encoding [13] are the same. Two encodings - ladder [17] and regular [19]- are the same as well. Hence, the prior two encodings (relaxed ladder and sequential) are exact the latter two encodings (ladder and regular ) after removing redundant clauses. Interestingly, these ideas were exploited in the unary representation [7] and the order encoding [20]. We hope that our work could help researchers working in SAT encoding to avoid confusing among these encodings.

Secondly, the major goal of the paper is to propose a new method to encode the at-most-one constraint to a SAT formula, called the bimander encoding. Compared to many efficient and well-known $A M O$ methods, the bimander encoding requires the least auxiliary variables, with exception of the pairwise encoding (requires no additional variable). Although the commander and bimander encodings use the same approach by dividing the original set of Boolean variables, the commander requires clauses of size $\left\lceil\frac{n}{m}+1\right\rceil$ (where $m$ is the number of disjointed subsets), whereas the bimander encoding requires only binary clauses. We believe that this helps the bimander encoding performs better than the commander encoding. Moreover, this new encoding has the advantage of high scalability, and it can easily be adjusted in term of the number of additional Boolean variables to get a suitable encoding. For example, the pairwise or binary encodings are special cases of the bimander encoding by setting certain parameters. The important feature of the new encoding is to allow unit propagation to preserve arc consistency property.

Thirdly, this paper also proposes a special case, when dividing the original Boolean variables into $m=\left\lceil\frac{n}{2}\right\rceil$ disjoint subsets. From a theoretical point of
view, this case is better than the binary encoding in term of both the number of auxiliary variables and clauses required. From a practical point of view, we show that the special case of the bimander encoding ( $m=\left\lceil\frac{n}{2}\right\rceil$ ) performs better than the binary encoding in all experiments in term of runtime.

Fourthly, in practice, the bimander encoding is easy to implement to get different encodings. Our experimental results reveal that the variants of the bimander encoding are very competitive with the others. For instance, they are the best in three of four benchmarks.

In general, a smaller encoding with respect to the number of clauses, literals or variables tends to perform better. However, a good encoding for one algorithm might be bad for others. For this reason, the best way to evaluate one encoding is to experiment on particular problems. A side benefit of our encoding is to give more the number of SAT encodings, and then to offer to SAT community more choices to be able to deal with a wide variety of real-world applications. This paper should also be viewed as a preliminary attempt to provides a further choice to encode the very common alldifferent constraint (see [17]).

An interesting our future research is to study how the number of disjointed subsets could affect the bimander encoding through realistic problems. It would be particularly useful to further supplement by implementing and comparing our extended At-Most-k encoding with others. Finally, the ultimate goal should carry out a profound study of not only analytical, but also theoretical knowledge of variants of well-known encodings. We expect that this will help us to spur further what makes an encoding perform better than others (in specific situations).

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[^0]:    ${ }^{1}\lceil x\rceil$ is the smallest integer not less than x.

