

The Chase in Lean

Crafting a Formal Library for Existential Rule Research

Lukas Gerlach

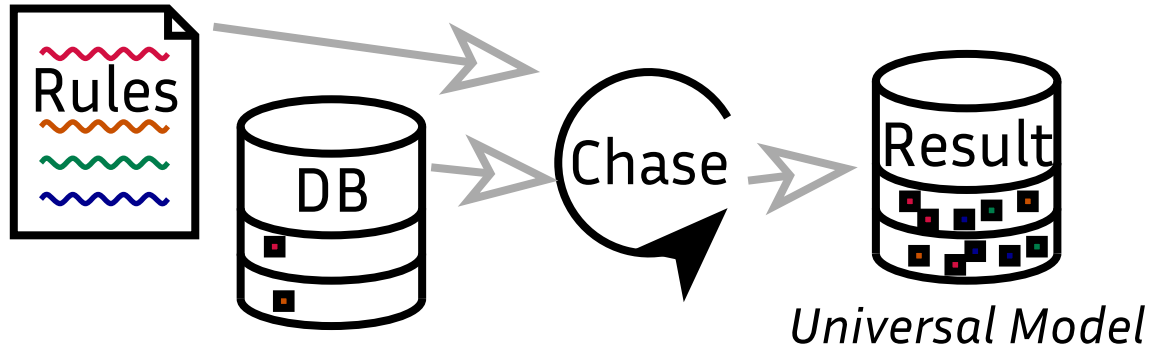
Knowledge-Based Systems Group, TU Dresden, Germany

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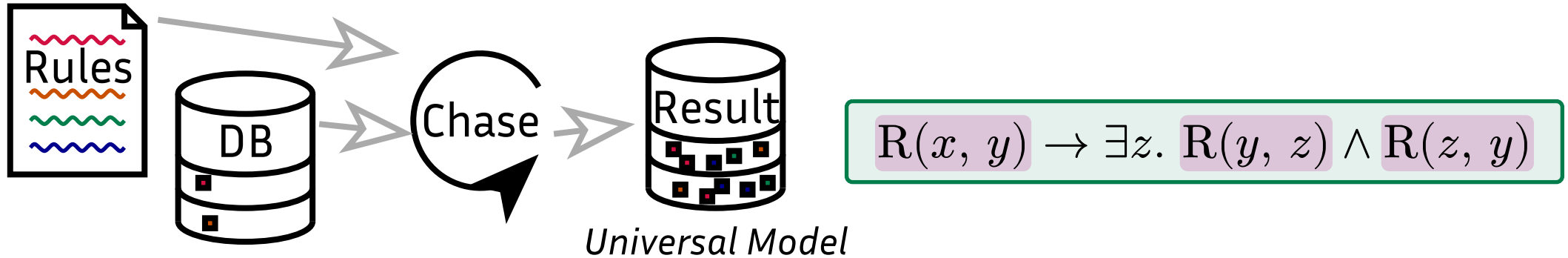


International Center
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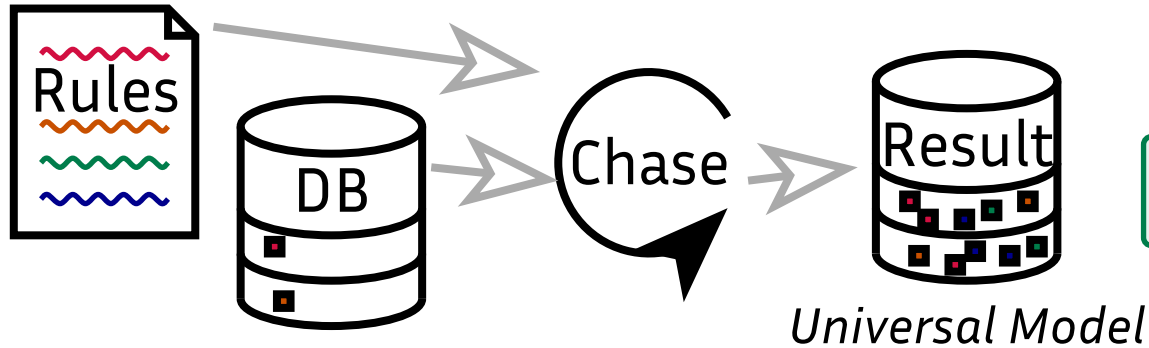
Chase Crash Course



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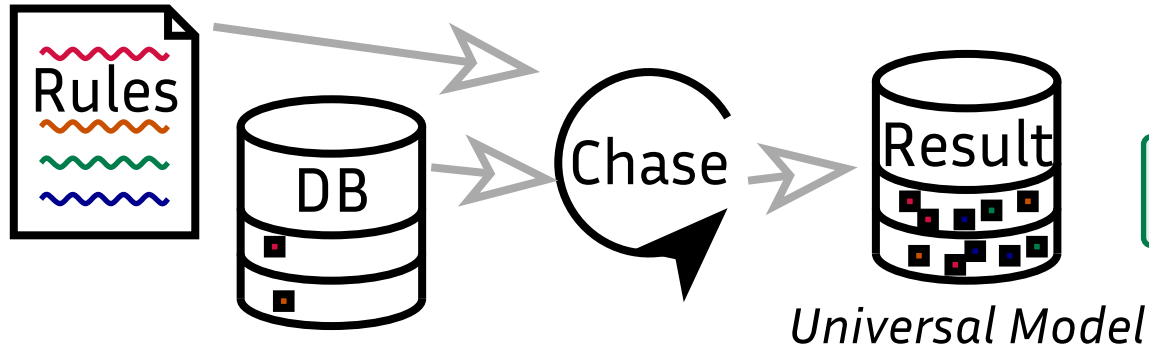
Chase Crash Course



$$R(x, y) \rightarrow \exists z. R(y, z) \wedge R(z, y)$$

DB: $R(c, d)$

Chase Crash Course

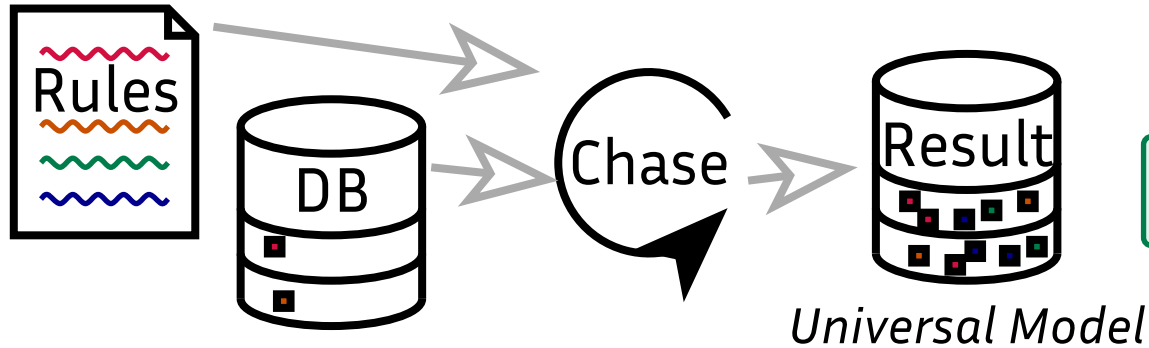


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Chase Crash Course



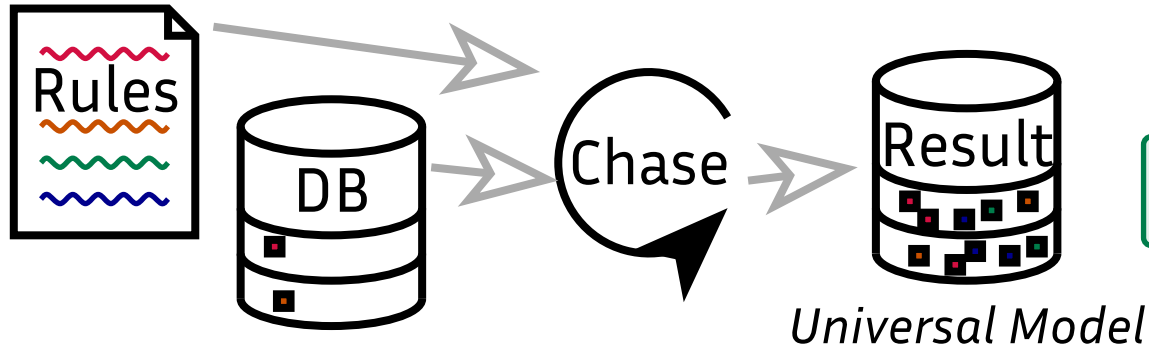
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Chase Crash Course



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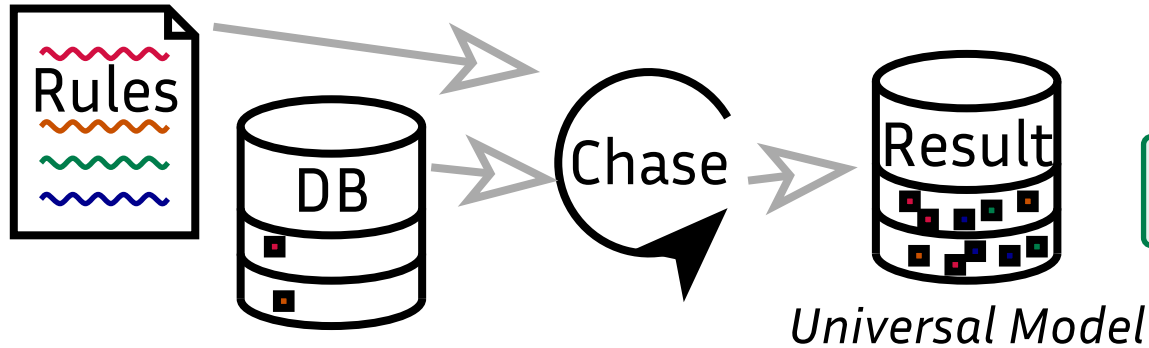
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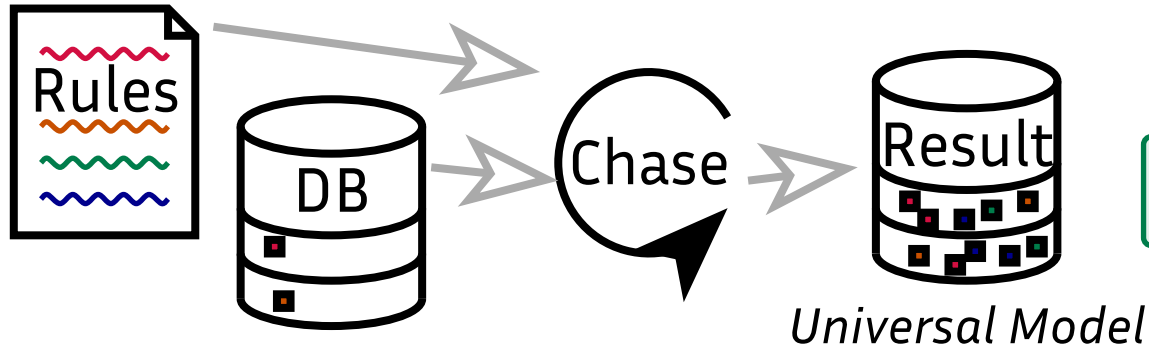
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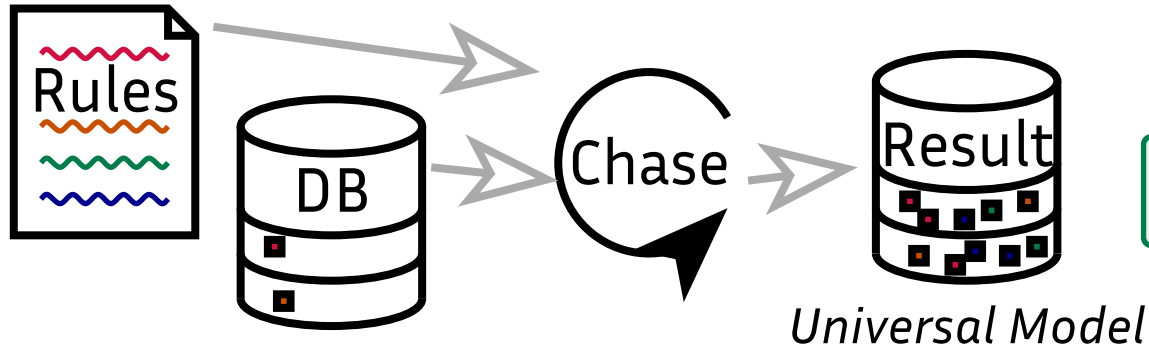
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$$R(x, y) \rightarrow \exists z. R(y, z) \wedge R(z, y)$$

Skolem Chase

DB: $R(c, d)$

Step 1: $R(d, f_z(d)), R(f_z(d), d)$

Step 2: $R(f_z(d), f_z(f_z(d))), \dots$

Step N: ...

Restricted Chase

DB: $R(c, d)$

Step 1: $R(d, f_z(d)), R(f_z(d), d)$

We still use Skolem functions instead of nulls (as a naming convention).

Formal Verification – Why Bother? 🧑

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Theory 🧐 – *Proving things is hard and intuitions might be deceiving.*

▪

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- Universal Chase Termination has been believed to be a semi-decidable problem. This is not true! [Deutsch et al. \(2008\)](#), [Grahne and Onet \(2018\)](#), [Carral et al. \(2025\)](#)
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- ... and many works around practically motivated formalizations of Datalog already exist. [Whitehead \(2007\)](#), [Dumbrava \(2016\)](#), [Schlichtkrull et al. \(2024\)](#), [Tantow et al. \(2025\)](#)

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Lean 🎉 – *Let's treat theorems and proofs like (open source) software.*

- A formal library can function as ground truth for both theory and practice.
- Mathlib and CSLib receive a lot of attention. [Baanen et al. \(2026\)](#), [Barrett et al. \(2026\)](#)

Lean Crash Course

```
-- Let's (re)define the naturals ...  
inductive Nat' where  
| zero : Nat'  
| succ : Nat' -> Nat'
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-- Let's (re)define the naturals ...
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def Nat'.add (n : Nat') : Nat' -> Nat'
| .zero => n
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-- ... and prove that add is associative.
```

```
theorem Nat'.add_assoc (n m k : Nat') : n.add (m.add k) = (n.add m).add k := by
```

We show the proof state here.

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n m k : Nat
⊢ n.add (m.add k) = (n.add m).add k
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theorem Nat'.add_assoc (n m k : Nat') : n.add (m.add k) = (n.add m).add k := by
  induction k with
  | zero => rfl -- both sides are definitionally equal
```

```
n m : Nat
⊢ n.add (m.add 0) = (n.add m).add 0
```

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  | succ k ih => -- after unfolding the definition, applying the ih closes the goal
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    simp only [Nat'.add]
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```
  induction k <;> grind [add] -- or simply use grind in all cases
```

Goals accomplished 

Cut to the Chase!

DB: $R(c, d)$ (Skolem)

Step 1: $R(d, f_z(d)), R(f_z(d), d)$

Step 2: $R(f_z(d), f_z(f_z(d))), \dots$

Step N: ...

$R(x, y) \rightarrow \exists z. R(y, z) \wedge R(z, y)$

DB: $R(c, d)$ (Restricted)

Step 1: $R(d, f_z(d)), R(f_z(d), d)$

How do we capture the differences (Skolem/Restricted and Finite/Infinite)?

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-- Skolem/Restricted behavior can be generalized to checking "obs"
structure Chase (obs : ObsolescenceCondition) (rs : RuleSet) where

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```
-- Skolem/Restricted behavior can be generalized to checking "obs"  
structure Chase (obs : ObsolescenceCondition) (rs : RuleSet) where  
  seq : List (ChaseNode obs rs) -- does not work...  
  <conditions>
```

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```
-- Skolem/Restricted behavior can be generalized to checking "obs"  
structure Chase (obs : ObsolescenceCondition) (rs : RuleSet) where  
  seq : Nat -> (ChaseNode obs rs) -- still does not work...  
  <conditions>
```

Cut to the Chase!

DB: $R(c, d)$ (Skolem)

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How do we capture the differences (Skolem/Restricted and Finite/Infinite)?

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-- Skolem/Restricted behavior can be generalized to checking "obs"
structure Chase (obs : ObsolescenceCondition) (rs : RuleSet) where
  seq : Nat -> Option (ChaseNode obs rs) -- getting somewhere!
  <conditions>
```

Cut to the Chase!

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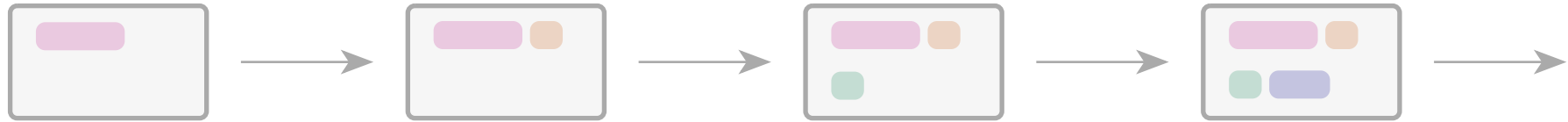
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How do we capture the differences (Skolem/Restricted and Finite/Infinite)?

```
-- Skolem/Restricted behavior can be generalized to checking "obs"  
structure Chase (obs : ObsolescenceCondition) (rs : RuleSet) where  
  seq : PossiblyInfiniteList (ChaseNode obs rs)  
  <conditions>
```

Basic ingredients of our framework 🔍

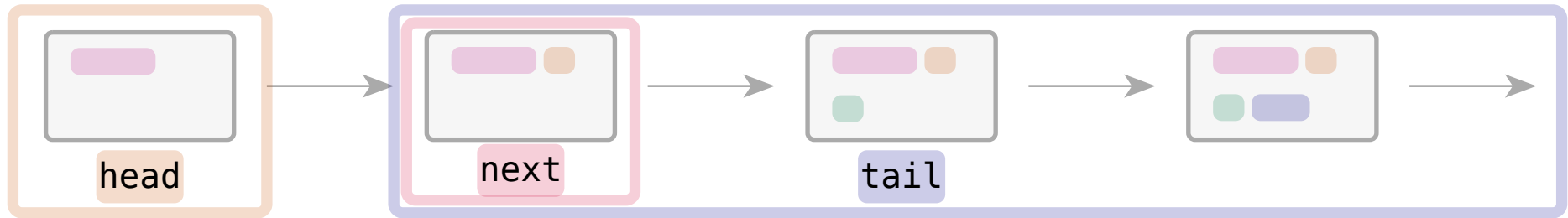
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- 1.
- 2.
- 3.
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Basic ingredients of our framework 🔍

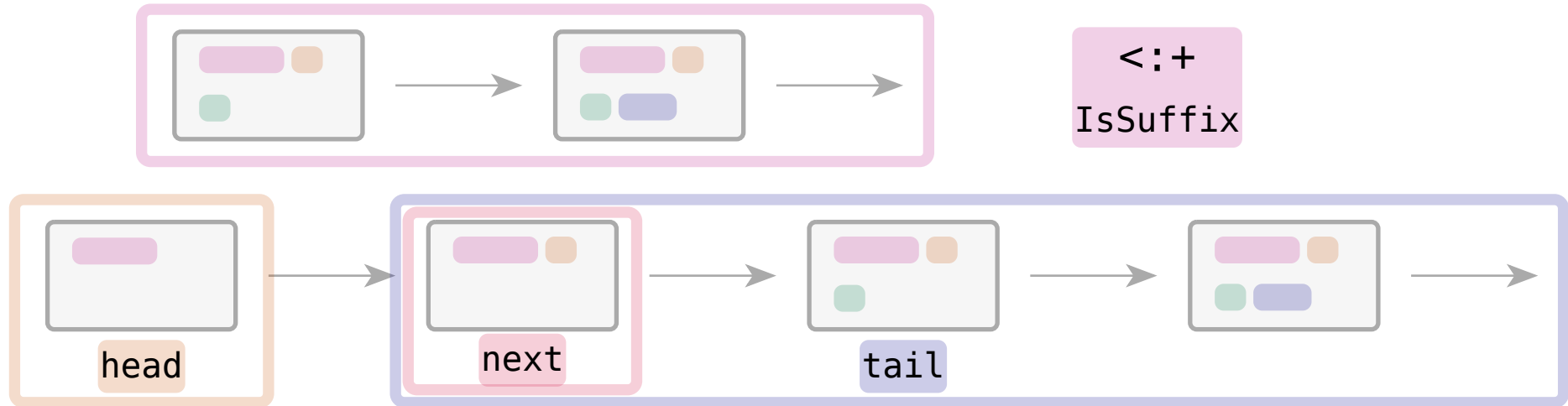
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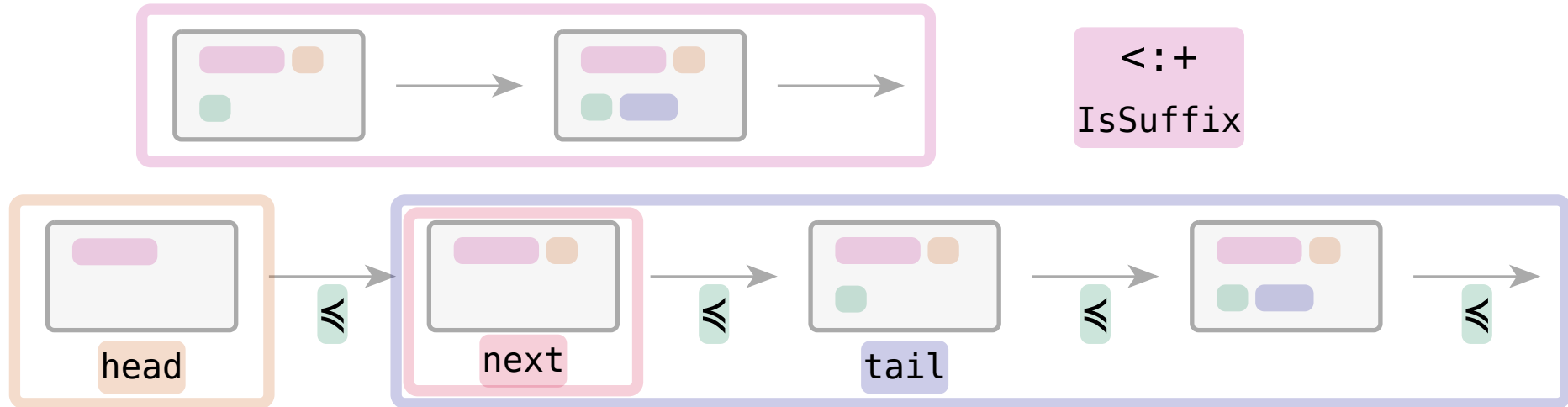
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2. A suffix relation $<:+$ on chase sequences.
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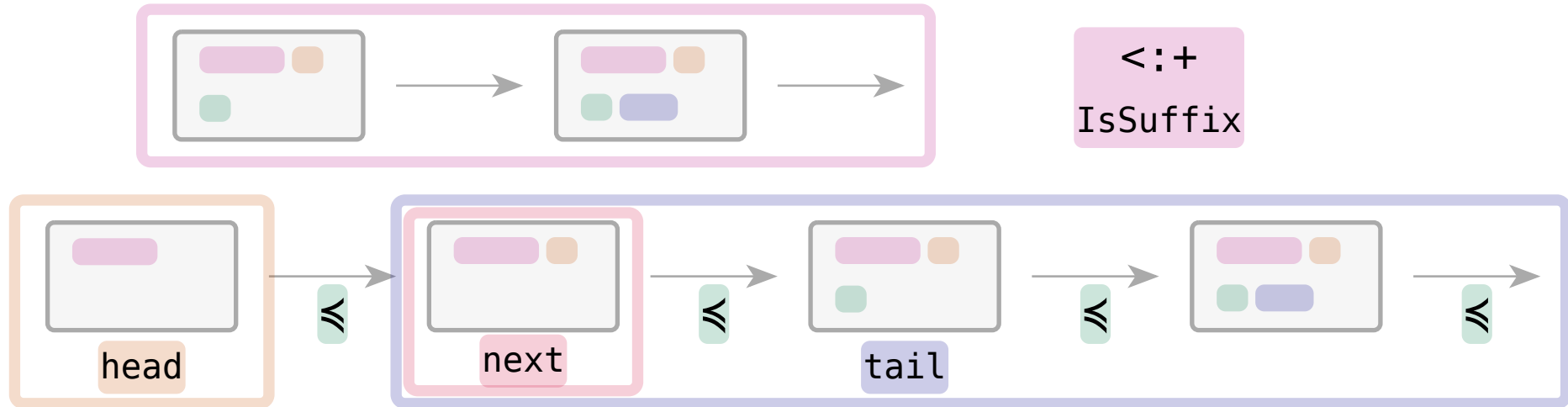
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1. Basic (coinductive) accessors: `head`, `next` and `tail`
2. A suffix relation $<:+$ on chase sequences.
3. A predecessor relation $\preceq$ on nodes in a single chase sequence.
4. An induction principle for nodes in the chase (next slide).

Defining our own induction principle 👁👁

We can define induction principles even on non-inductive types.

Interestingly, the coinductive nature of our chase definition comes in handy.

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  {motive : Node cd -> Prop} -- some possible property of a Node
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  (head : motive (cd.head, cd.head_mem)) -- base case holds
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theorem mem_rec {cd : Chase obs rules}
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  (head : motive (cd.head, cd.head_mem)) -- base case holds
  (step : ∀ (cd2 : Chase obs rules), -- induction step holds
    (suffix : cd2 <:+ cd) ->
    motive (cd2.head, ...) -> -- this is the induction hypothesis
    ∀ next, (next_mem : next ∈ cd2.next) ->
    motive (next, ...))
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    motive (cd2.head, ...) -> -- this is the induction hypothesis
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    motive (next, ...))
  (node : Node cd) : -- base and step hold, so for each node ...
```

Defining our own induction principle 🙄

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Interestingly, the coinductive nature of our chase definition comes in handy.

```
theorem mem_rec {cd : Chase obs rules}
  {motive : Node cd -> Prop} -- some possible property of a Node
  (head : motive (cd.head, cd.head_mem)) -- base case holds
  (step : ∀ (cd2 : Chase obs rules), -- induction step holds
    (suffix : cd2 <:+ cd) ->
    motive (cd2.head, ...) -> -- this is the induction hypothesis
    ∀ next, (next_mem : next ∈ cd2.next) ->
    motive (next, ...))
  (node : Node cd) : -- base and step hold, so for each node ...
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theorem facts_node_subset_every_mem :  
  ∀ node ∈ cd, cd.head.facts ⊆ node.facts := by  
  intro node node_mem  
  let node' : cd.Node := {node, node_mem}  
  show cd.head.facts ⊆ node'.val.facts  
  induction node' using mem_rec with  
  | head => apply Set.subset_refl  
  | step cd2 suffix subset next next_eq =>  
    apply Set.subset_trans subset  
    rw [cd2.facts_next next_eq]  
    apply Set.subset_union_of_subset_left  
    apply Set.subset_refl
```

```
theorem facts_node_subset_of_prec :  
  node1 ≤ node2 ->  
    node1.val.facts ⊆ node2.val.facts := by  
  rintro {cd2, suffix, head_eq, mem}  
  rw [← head_eq]  
  apply facts_node_subset_every_mem  
  exact mem
```

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Consider a chase node n . For each following node m , we have $n \subseteq m$.

? Does it suffice?

Not if the chase is not finished.

Because then, n is not a node.

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), then yes.

e.

ec :

.facts := by
 mem)

_mem

Results that are already part of the library

1. The chase yields a universal model. (Deutsch et al. 2008)
 - Involves creating an sequence of infinitely many homomorphisms.
 - `cb.result.universallyModelsKb kb`

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 - `¬cb.has_alt_match → cb.result.isStrongCore`
3. Each chase an every rule set that fulfills an **MFA**-like condition terminates; generalizing ([Grau et al. 2013](#), [Carral et al. 2017](#), [Gerlach and Carral 2023a](#))
 - Termination conditions are generic over an `ObsolescenceCondition`.
 - `rs.isMfa rs_finite (BlockingObsolescence obs rs) → rs.terminates obs (RegularChaseNode obs rs)`

Results that are already part of the library

Documentation

ExistentialRules.ChaseSequence.Universality

General documentation

[index](#)

[foundational types](#)

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Library

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- AlternativeMatches
- AtomsAndFacts
- ChaseSequence
 - CoreChase (file)
 - Nontermination
- Termination
 - BacktrackingOfFacts (file)
 - ConstantMappings (file)
 - RenameConstantsApart (file)

ChaseBranch

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- Models
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Lean (file)

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- PossiblyInfiniteList
- InfiniteList
- PossiblyInfiniteList
- PossiblyInfiniteTree

Chase Tree Result is Universal Model Set

return to top

source

Imports

Imported by

chaseTreeResultIsUniversal

This whole file is dedicated to showing that the result of a `ChaseTree` is a universal model set [BMMP16]. More precisely, we want to show the universality part as we have already shown in `ChaseTree.result_modelIs_kb` that each element of the result is a model. So what exactly remains to be shown?

We aim to show that for a given `ChaseTree` for a `KnowledgeBase` and any model M of the `KnowledgeBase`, we can pick a fact set F from the result of the chase tree such that there is a homomorphism from F to M . This result is shown in `chaseTreeResultIsUniversal`.

The proof works by step-wise construction of both a branch in the chase tree as well as a suitable homomorphism. The constructions builds both at the same time. One step of the construction is done by the `hom_step` function below, which calls `hom_step_of_trg_ex` for the heavy lifting. The base of the construction is simply an empty branch and the id mapping. In each step of the construction, we consider an `InductiveHomomorphismResult`, which we define to be a pair of a node in the chase tree and a `GroundTermMapping` such that the mapping is a homomorphism from the node into the model M .

In the proof of `chaseTreeResultIsUniversal`, we leverage the `TreeDerivation.generate_subderivation` function with `hom_step` as the generator function. Besides that, all the homomorphisms from the individual steps need to be combined into a single function. The definition is not too hard and all relevant properties are also not too hard to show once we can establish that the homomorphisms for each step always extend the previous one.

theorem chaseTreeResultIsUniversal

source

```
{sig : Signature} [DecidableEq sig.P] [DecidableEq sig.C] [DecidableEq sig.V]
{obs : ObsolescenceCondition sig} {kb : KnowledgeBase sig}
(ct : RegularChaseTree obs kb) (m : FactSet sig) :
m.modelsKb kb → ∃ (fs : FactSet sig), ∃ (h : GroundTermMapping sig), fs ∈ ct.result
  ∧ h.isHomomorphism fs m
```

As outlined at the very top of this file, we now use `TreeDerivation.generate_subderivation` with the `hom_step` generator to obtain the branch in the tree that yields the result `FactSet` for which the combined `GroundTermMapping`s form a homomorphism into the target model.

Lessons Learned & Outlook

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- Go bottom up and have sensible mini-libraries.
- This should involve (a lot of) obvious theorems (many of them provable via `rf1`).
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What's next? 

- Proving correctness of RPC. ([Gerlach and Carral 2023b](#))
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- An executable (naive) chase procedure.
- *Your contribution?*

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Visit <https://dmfa.dev/lean> 

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