



TECHNISCHE  
UNIVERSITÄT  
DRESDEN

# DEDUCTION SYSTEMS

## Optimizations for Tableau Procedures

Sebastian Rudolph

# Agenda

- Recap Tableau Calculus
- Optimizations
  - Unfolding
  - Absorption
  - Dependency-Directed Backtracking
  - Further Optimizations
- Classification
- Summary

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- tableau construction successful, if no further rules are applicable and there is no contradiction
- $C$  is satisfiable iff there is a successful tableau construction

## Treatment of Knowledge Bases

we condense the TBox into one concept:

for  $\mathcal{T} = \{C_i \sqsubseteq D_i \mid 1 \leq i \leq n\}$ ,  $C_{\mathcal{T}} = \text{NNF}(\bigwedge_{1 \leq i \leq n} \neg C_i \sqcup D_i)$

we extend the rules of the  $\mathcal{ALC}$  tableau algorithm:

$\mathcal{T}$ -rule: for an arbitrary  $v \in V$  with  $C_{\mathcal{T}} \notin L(v)$ ,  
let  $L(v) := L(v) \cup \{C_{\mathcal{T}}\}$ .

in order to take an ABox  $\mathcal{A}$  into account, initialize  $G$  such that

- $V$  contains a node  $v_a$  for every individual  $a$  in  $\mathcal{A}$
- $L(v_a) = \{C \mid C(a) \in \mathcal{A}\}$
- $\langle v_a, v_b \rangle \in E$  iff  $r(a, b) \in \mathcal{A}$

## Extensions of the Logic

- plus inverses ( $\mathcal{ALCI}$ ): inverse roles in edge labels, definition and use of  $r$ -neighbors instead of  $r$ -successors in tableau rules
- plus functional roles ( $\mathcal{ALCIF}$ ): merging of nodes to account for functionality

blocking guarantees termination:

- $\mathcal{ALC}$  subset-blocking
- plus inverses ( $\mathcal{ALCI}$ ): equality blocking
- plus functional roles ( $\mathcal{ALCIF}$ ): pairwise blocking

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- Naïve implementation not performant enough
  - $\mathcal{T}$ -regel adds one disjunction per axiom to the corresponding node
  - ontologies may contain  $> 1.000$  axioms and tableaux may contain thousands of nodes

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- realistic implementations use many optimizations
  - (Lazy) unfolding
  - Absorbtion
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# Unfolding

- $\mathcal{T}$ -rule is not necessary if  $\mathcal{T}$  is **unfoldable**, i.e., every axiom is:
  - **definitorial**: form  $A \sqsubseteq C$  or  $A \equiv C$  for  $A$  a concept name  
( $A \equiv C$  corresponds to  $A \sqsubseteq C$  and  $C \sqsubseteq A$ )
  - **acyclic**:  $C$  uses  $A$  neither directly nor indirectly
  - **unique**: only one such axiom exists for every concept name  $A$

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  - **acyclic**:  $C$  uses  $A$  neither directly nor indirectly
  - **unique**: only one such axiom exists for every concept name  $A$
- If  $\mathcal{T}$  is unfoldable, the TBox can be (**unfolded**) into a concept

# Unfolding Example

- We check satisfiability of  $A$  w.r.t. the TBox  $\mathcal{T}$

$\mathcal{T}$ :

$$A \sqsubseteq B \sqcap \exists r.C$$

$$B \equiv C \sqcup D$$

$$C \sqsubseteq \exists r.D$$

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$$\begin{aligned} & A \\ \rightsquigarrow & A \sqcap B \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap (C \sqcup D) \sqcap \exists r.C \end{aligned}$$

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$\mathcal{T}$ :

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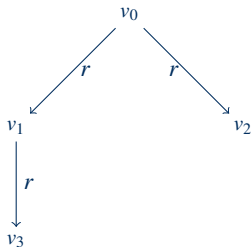
- $A$  is satisfiable w.r.t.  $\mathcal{T}$  iff

$$A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$$

is satisfiable w.r.t. the empty TBox

## Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of  $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$ :



$$L(v_0) = \{U, A, (C \sqcap \exists r.D) \sqcup D, \\ \exists r.(C \sqcap \exists r.D), C \sqcap \exists r.D, \\ C, \exists r.D\}$$

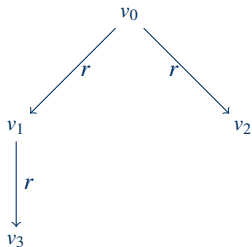
$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

$$L(v_2) = \{D\}$$

$$L(v_3) = \{D\}$$

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We obtain the following contradiction-free tableau for the satisfiability of  $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$ :



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$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

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Only one disjunctive decision left!

## Lazy Unfolding

- computation of NNF together with unfolding may decrease performance, e.g.:
  - satisfiability of  $C \sqcap \neg C$  w.r.t.  $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
  - unfolding:  $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
  - NNF + unfolding:  $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$

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    - NNF + unfolding:  $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$
  - better: apply NNF and unfolding if needed, via corresponding tableau rules:
    - $A \equiv C \rightsquigarrow A \sqsubseteq C$  and  $A \supseteq C$
- $\sqsubseteq$ -rule: For  $v \in V$  such that  $A \sqsubseteq C \in \mathcal{T}$ ,  $A \in L(v)$  and  $C \notin L(v)$   
let  $L(v) := L(v) \cup C$ .
- $\supseteq$ -rule: For  $v \in V$  such that  $A \supseteq C \in \mathcal{T}$ ,  $\neg A \in L(v)$  and  $\neg C \notin L(v)$   
let  $L(v) := L(v) \cup \{\neg C\}$ .
- $\neg$ -rule: For  $v \in V$  such that  $\neg C \in L(v)$  and  $\text{NNF}(\neg C) \notin L(v)$ ,  
let  $L(v) := L(v) \cup \{\text{NNF}(\neg C)\}$ .

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# Absorption

- What if  $\mathcal{T}$  is not unfoldable?
  - Separate  $\mathcal{T}$  into  $\mathcal{T}_u$  (unfoldable part) and  $\mathcal{T}_g$  (GCIs, not unfoldable)
  - $\mathcal{T}_u$  is treated via  $\sqsubseteq$ - and  $\sqsupseteq$ -rules
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- absorption decreases  $\mathcal{T}_g$  and increases  $\mathcal{T}_u$ 
  - 1 take an axiom from  $\mathcal{T}_g$ , e.g.,  $A \sqcap B \sqsubseteq C$
  - 2 transform the axiom:  $A \sqsubseteq C \sqcup \neg B$
  - 3 if  $\mathcal{T}_u$  contains an axiom of the form  $A \equiv D$  ( $A \sqsubseteq D$  and  $D \supseteq A$ ), then  $A \sqsubseteq C \sqcup \neg B$  cannot be absorbed;  $A \sqsubseteq C \sqcup \neg B$  remains in  $\mathcal{T}_g$
  - 4 otherwise, if  $\mathcal{T}_u$  contains an axiom of the form  $A \sqsubseteq D$ , then absorb  $A \sqsubseteq C \sqcup \neg B$  resulting in  $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
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- If  $A \equiv D \in \mathcal{T}_u$ , try rewriting/absorption with other axioms in  $\mathcal{T}_u$
- nondeterministic:  $B \sqsubseteq C \sqcup \neg A$  also possible

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# Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let  $v \in V$  with  $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

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$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. (A \sqcap B)\}$$

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$r$	$\sqcup$ -rule	$L(v)$	:=	$L(v) \cup \{C_1\}$
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$w$	$\sqcup$ -rule	$L(v)$	:=	$L(v) \cup \{C_n\}$
	$\exists$ -rule	$L(w)$	:=	$\{\neg A\}$



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$w$	$\sqcup$ -rule	$L(v) := L(v) \cup \{C_n\}$
	$\exists$ -rule	$L(w) := \{\neg A\}$
	$\forall$ -rule	$L(w) := \{\neg A, A\}$ <i>clash</i>



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$\downarrow$			$\exists r. \neg A, \forall r. (A \sqcap B)\}$	
$r$	$\sqcup$ -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	
$\downarrow$	$\vdots$	$\vdots$	$\vdots$	
$\downarrow$	<del><math>\sqcup</math>-rule</del>	<del><math>L(v) :=</math></del>	<del><math>L(v) \cup \{C_n\}</math></del>	
$w$	<del><math>\exists</math>-rule</del>	<del><math>L(w) :=</math></del>	<del><math>\{\neg A\}</math></del>	
	<del><math>\forall</math>-rule</del>	<del><math>L(w) :=</math></del>	<del><math>\{\neg A, A\}</math></del>	<i>clash</i>
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# Dependency-Directed Backtracking

- despite those optimizations, search space often too big
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- exponentially big search space is traversed

# Dependency-Directed Backtracking

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  - initially, all concepts are tagged with  $\emptyset$
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  - jump back to the last **relevant** application of a  $\sqcup$ -rule
- irrelevant part of the search space is not considered

# Dependency-Directed Backtracking Example

$$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v) \quad \text{tagged with } \emptyset$$



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- Output **false** (unsatisfiable)

# Agenda

- Recap Tableau Calculus
- Optimizations
  - Unfolding
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  - Further Optimizations
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# Further Optimizations

- Simplification and Normalization
  - quick recognition of trivial contradictions
  - normalization, z.B.,  $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$ ,  $\forall r. C \equiv \neg \exists r. \neg C$
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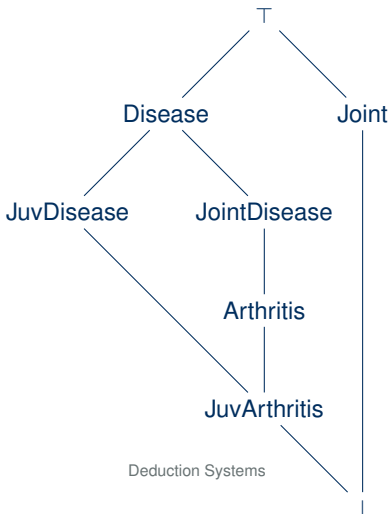
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- naïve approach needs  $n^2$  subsumption checks for  $n$  concept names
- normally cached in the **concept hierarchy** graph

# Concept Hierarchy Graph



# Optimizing Classification

most wide-spread technique is called [enhanced traversal](#)

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most wide-spread technique is called **enhanced traversal**

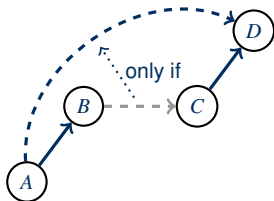
- hierarchy is created incrementally by introducing concept after concept
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# Optimizing Classification

most wide-spread technique is called **enhanced traversal**

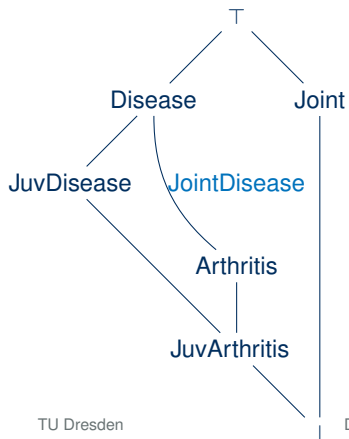
- hierarchy is created incrementally by introducing concept after concept
- top-down phase: recognize direct superconcepts
- bottom-up phase: recognize direct subconcepts
- transitivity of  $\sqsubseteq$  used to save checks



- If  $A \sqsubseteq B$  and  $C \sqsubseteq D$  hold,
- then  $B \sqsubseteq C \rightarrow A \sqsubseteq D$
- and  $A \not\sqsubseteq D \rightarrow B \not\sqsubseteq C$

## Enhanced Traversal Example

already created hierarchy:



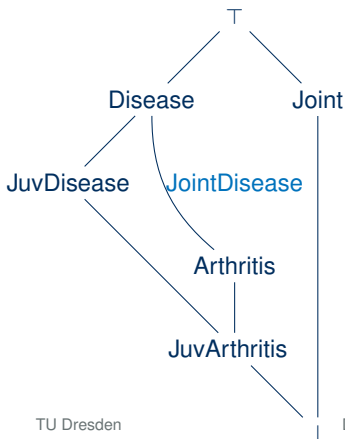
Goal: insertion of JointDisease

Top-Down Phase:

Bottom-Up Phase:

# Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

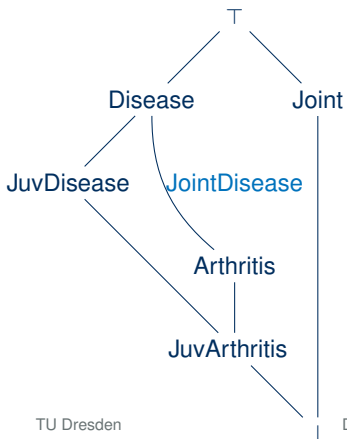
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq ? \text{Disease}$

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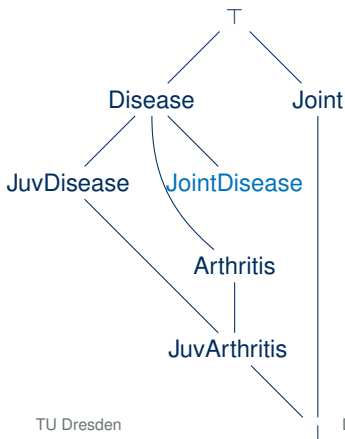
Top-Down Phase:

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Bottom-Up Phase:

## Enhanced Traversal Example

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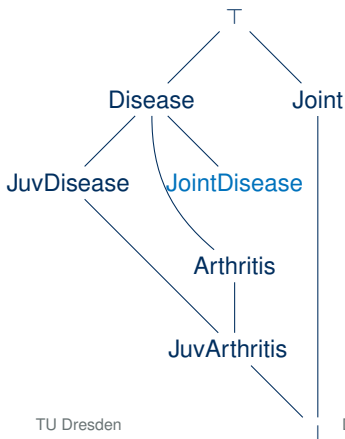
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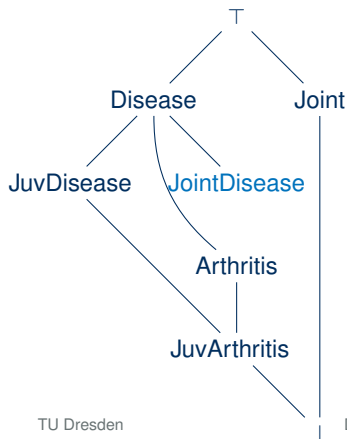
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already created hierarchy:



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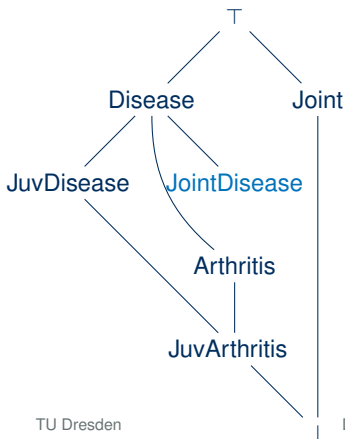
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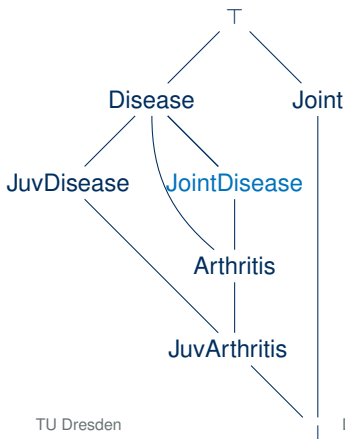
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already created hierarchy:



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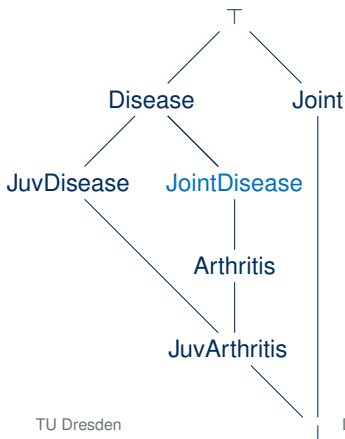
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# Summary

- we have a tableau algorithm for  $\mathcal{ALCIF}$  knowledge bases
  - ABox treated like for  $\mathcal{ALC}$
  - number restrictions are treated similar to functionality and existential quantifiers
- termination via cycle detection
  - becomes harder as the logic becomes more expressive
- naive tableau algorithm not sufficiently performant
- diverse optimizations improve average case
- specific methods for classification
  - enhanced traversal
- tableaux algorithms or variants modifications thereof are the basis of OWL reasoners