

Elisa Böhl, Sarah A. Gaggl, Stefan Ellmauthaler  
Logic Programming and Argumentation Group, TU Dresden, Germany

# Winning Snake: Design Choices in Multi-Shot ASP

Dallas, USA, October 16th 2024

# Overview

Motivation

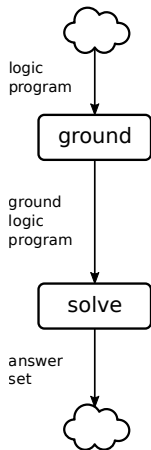
Snakes

Multi-shot approaches

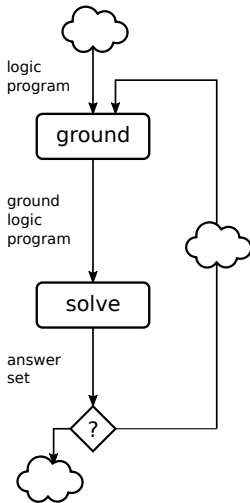
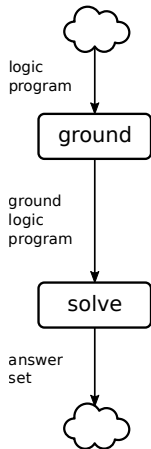
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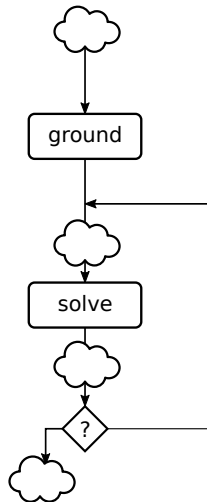
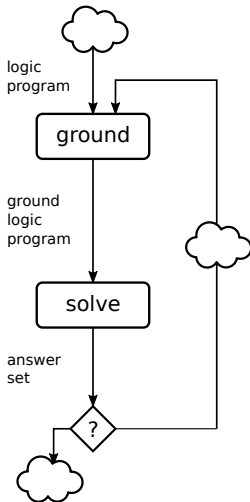
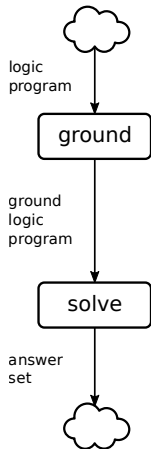
# Motivation



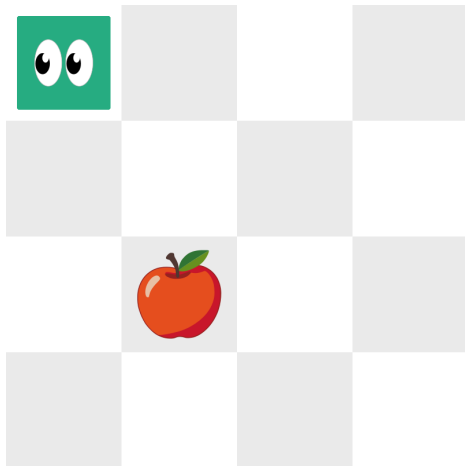
# Motivation



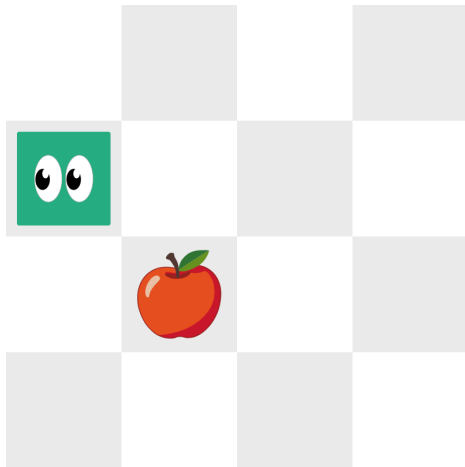
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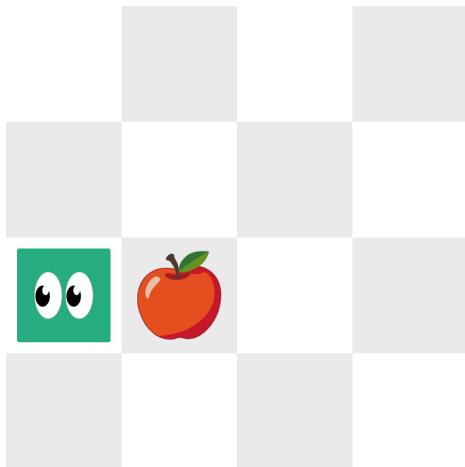
# About Snakes



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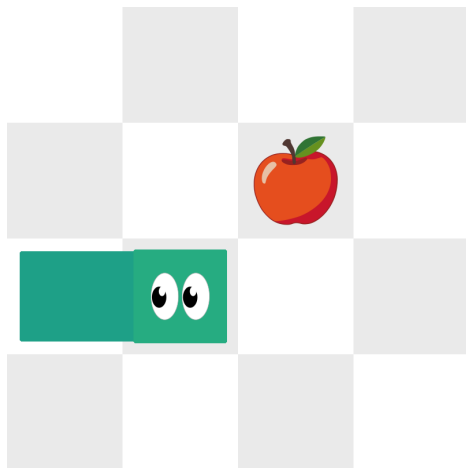


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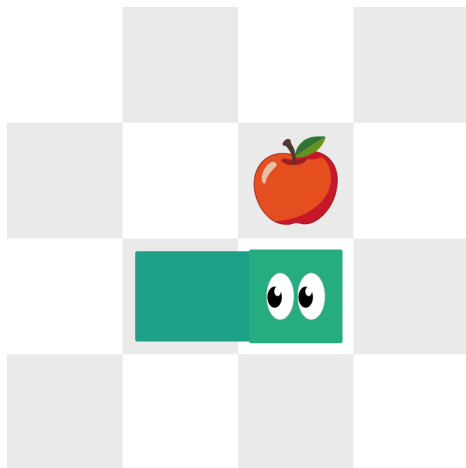




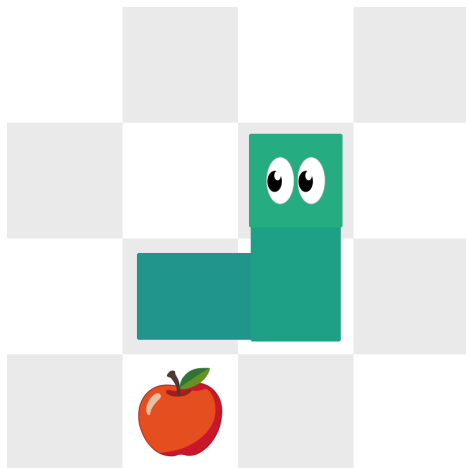
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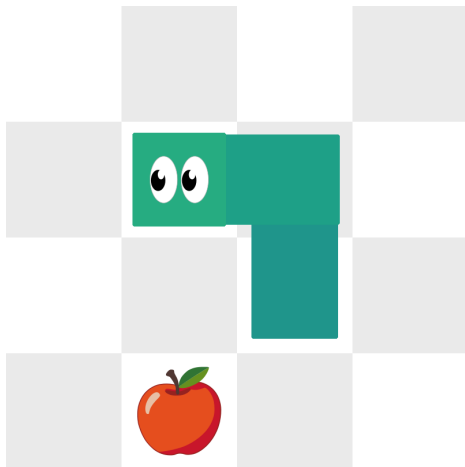
# About Snakes



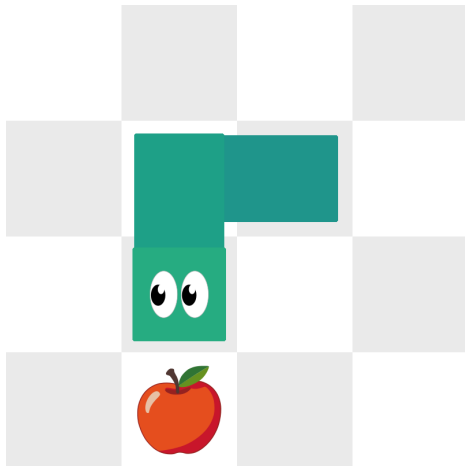
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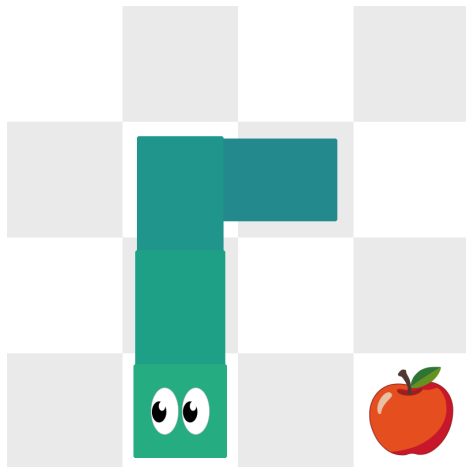
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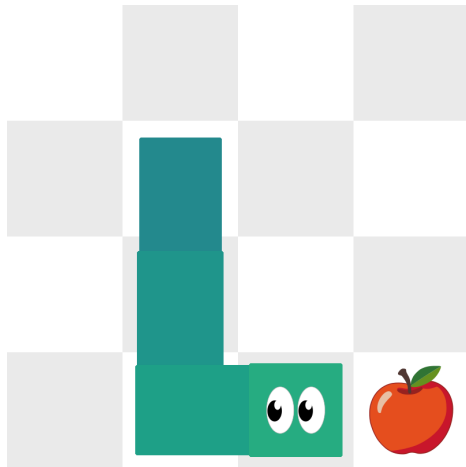
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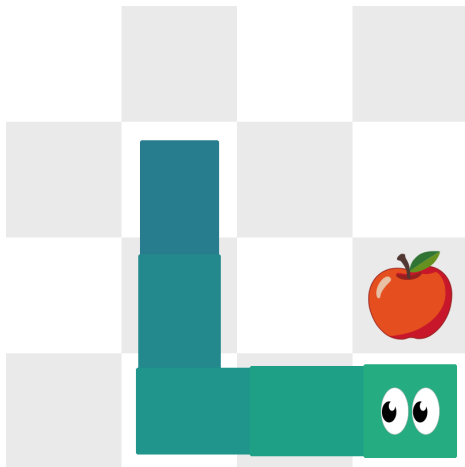
# About Snakes



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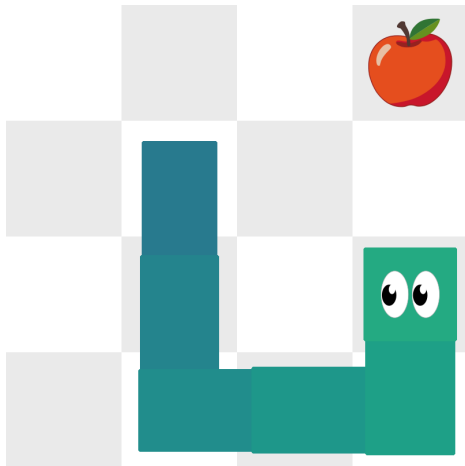


# About Snakes

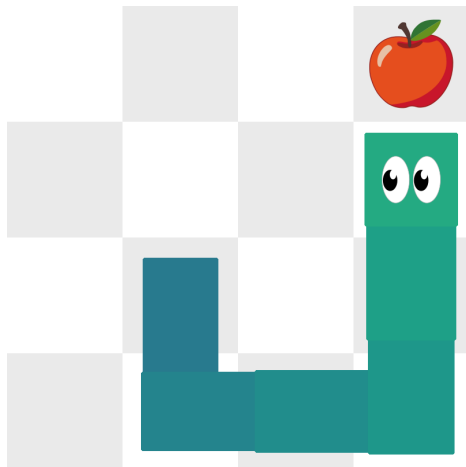




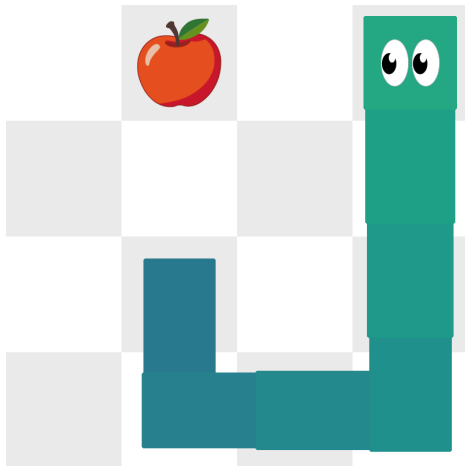
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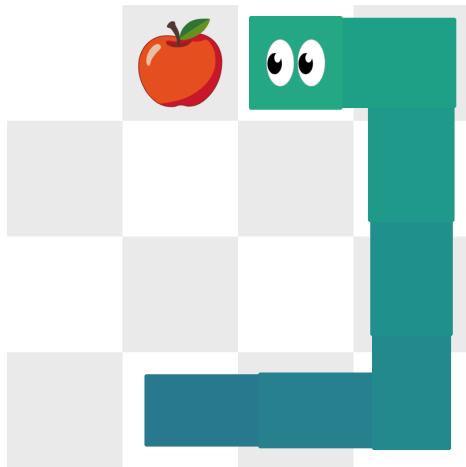
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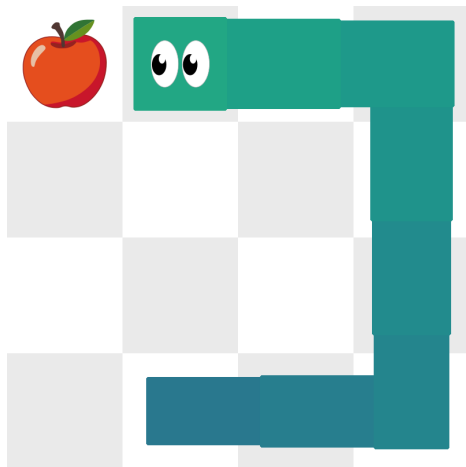
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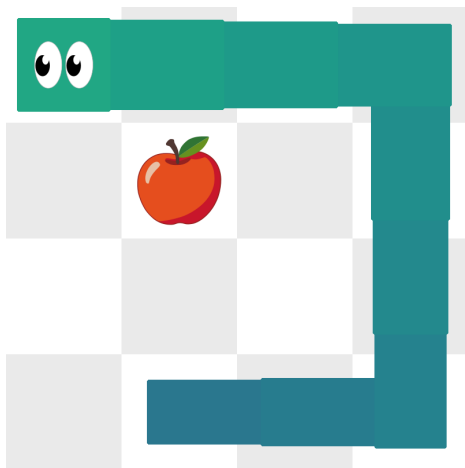
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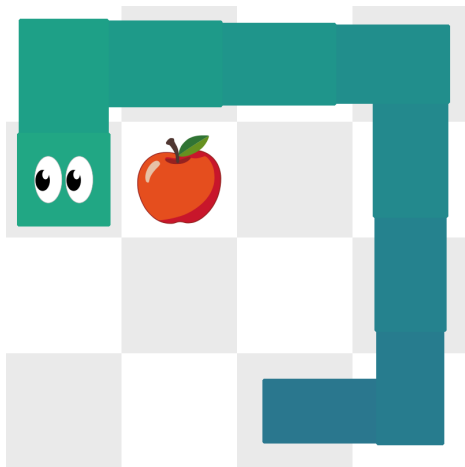
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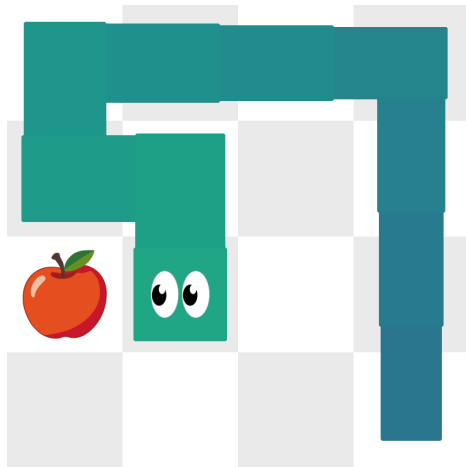
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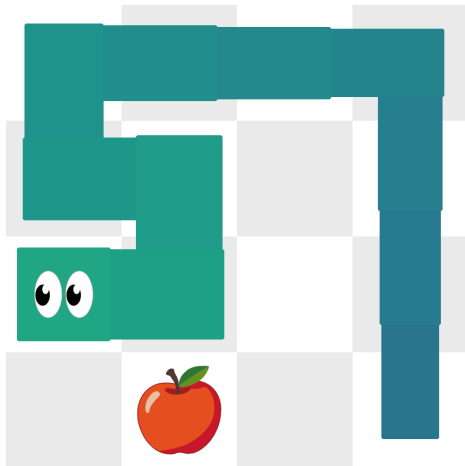




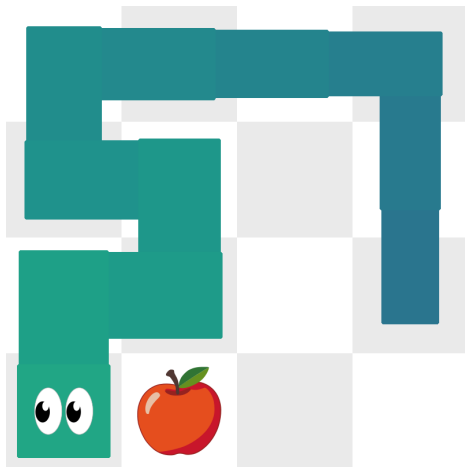
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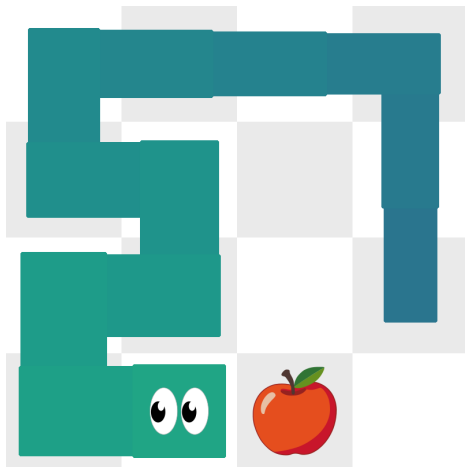
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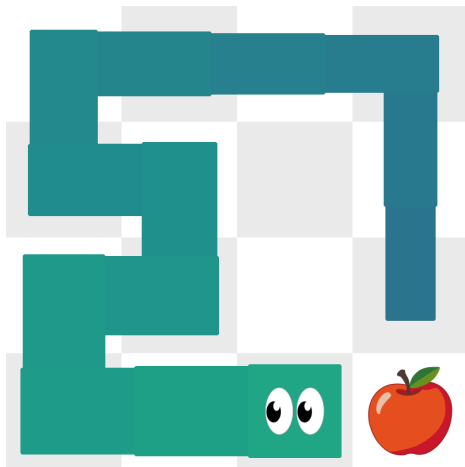
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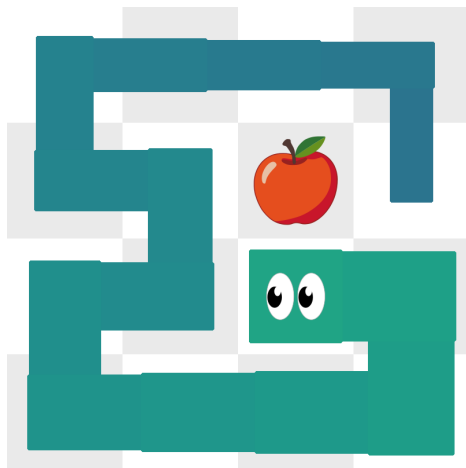
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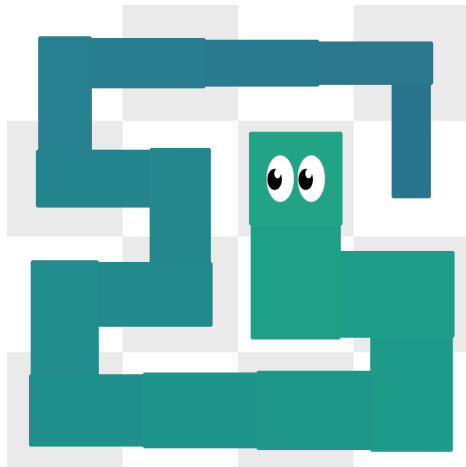


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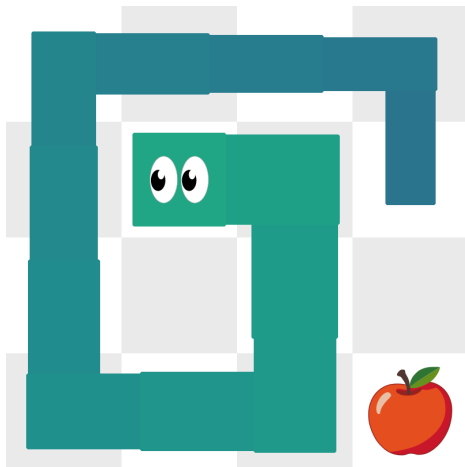




# About Snakes



# About Snakes

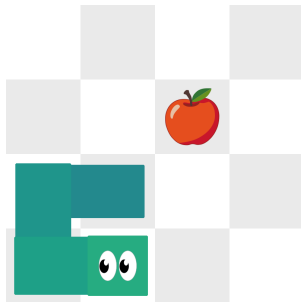


# Snakes - Keypoints

- Iterative setting
- Path from head to apple
- Solving one iteration  $\nrightarrow$  solving next iteration

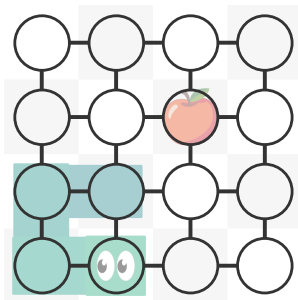


# Strategies



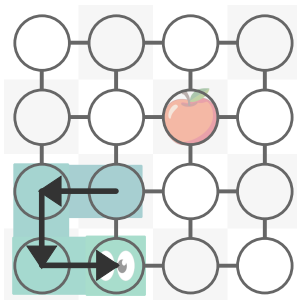
# Strategies

- Interpretation as Grid Graph



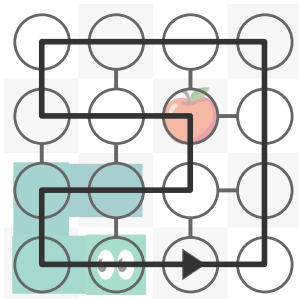
# Strategies

- Interpretation as Grid Graph
- Snake placement



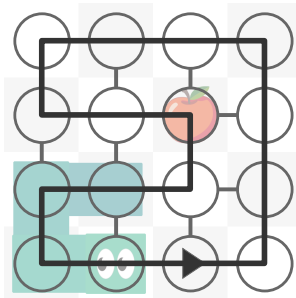
# Strategies

- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle



# Strategies

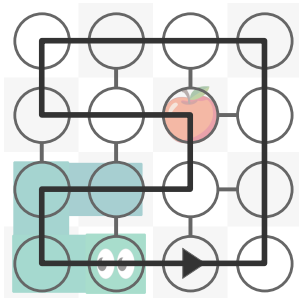
- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle *NP*





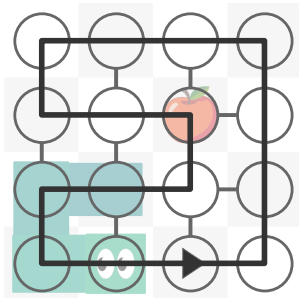
# Strategies

- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle  $NP / P$



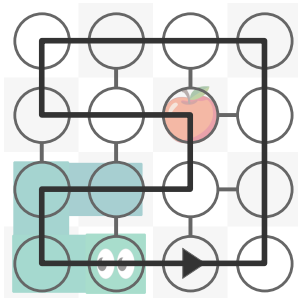
# Strategies

- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle  $NP / P$



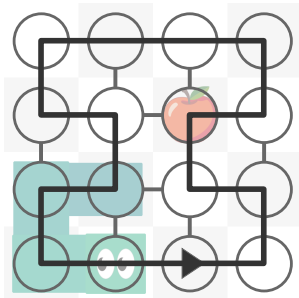
# Strategies

- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle  $NP / P$
- Minimize Step count  $NP^{NP}$   
(conservative Strategy)



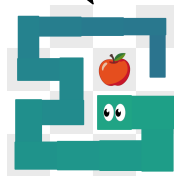
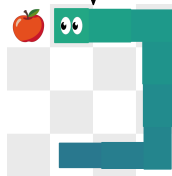
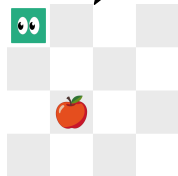
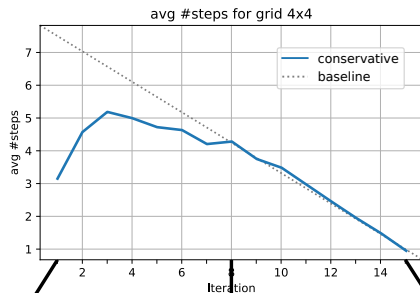
# Strategies

- Interpretation as Grid Graph
- Snake placement
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(conservative Strategy)



# Strategies

- Interpretation as Grid Graph
- Snake placement
- Hamiltonian Cycle  $NP / P$
- Minimize Step count  $NP^{NP}$   
(conservative Strategy)



# Why Snakes?

- Popular, easy to grasp yet hard
- Problem class well suited for ASP
- Iterative setting (multi-shot ASP)
- Minimalistic ASP-Encoding



# Snake logic program class

---

**Input:** grid dimension  $n \times m$ , position of head (head/1) and apple (apple/1)

```
1 field((X,Y)) :- X=1..n, Y=1..m.
2 conn((X,Y1),(X,Y2)) :- |Y1-Y2|=1, field((X,Y1)), field((X,Y2)).
3 conn((X1,Y),(X2,Y)) :- |X1-X2|=1, field((X1,Y)), field((X2,Y)).
4 1 { next(XY,XY') : field(XY), conn(XY,XY') } 1 :- field(XY').
5 1 { next(XY,XY') : field(XY'), conn(XY,XY') } 1 :- field(XY).
6 path(XY) :- field(XY), head(XY).
7 path(Next) :- path(XY), next(XY,Next).
8 :- field(XY), not path(XY).
9 mark(XY) :- field(XY), head(XY).
10 mark(Next) :- mark(XY), next(XY,Next), not apple(XY).
11 #minimize{ 1,XY : mark(XY) }.
```

---



# Answer Set Programming

- Logic programming under stable model semantics
- Established problem solving paradigm
- Advanced programming techniques required
- Specific mechanisms for `clingo`





# Implementation

 oneshot

 ad hoc

 preground


 assume

 nogoods

} multi-shot



# Implementation

 oneshot

 ad hoc

 preground

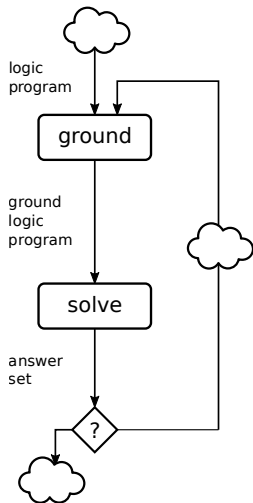
 assume

 nogoods

} multi-shot



# Workflow - Oneshot



---

**Input:** grid dimension  $n \times m$

```
1  $\mathbf{z} \leftarrow [(1,1)]$ 
2 do :
3    $\mathbf{a} \leftarrow \text{generate\_apple}((n,m), \mathbf{z})$ 
4    $\Pi \leftarrow \text{ground}(\text{base\_lp}(n,m) \cup \{\text{apple}(\mathbf{a}). \text{head}(\mathbf{z}_1).\} \cup \bigcup_{i=1..|\mathbf{z}|-1} \{\text{next}(\mathbf{z}_i, \mathbf{z}_{i+1}).\})$ 
5    $\text{model} \leftarrow \text{solve}(\Pi)$ 
6    $\text{path} \leftarrow \text{extract\_path}(\text{model})$ 
7    $\mathbf{z} \leftarrow \text{follow\_path}(\mathbf{z}, \text{path}, \mathbf{a})$ 
8
9
10
11 while  $|\mathbf{z}| < n \cdot m$ 
```

---

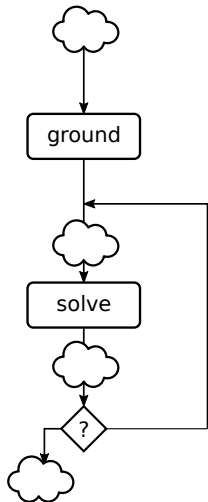


# Workflow - Oneshot

- fast and straight forward implementation
- flexible design, easy debugging
- redundant steps
- suboptimal resource use



# Workflow - Multi-shot

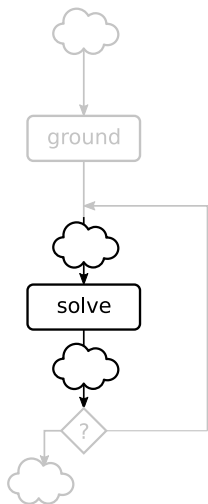


**Input:** grid dimension  $n \times m$

```
1  $\Pi \leftarrow \text{ground}(\{\#external\ apple(X) : \text{field}(X).$   
2  $\quad \#external\ head(X) : \text{field}(X).\}$   
3  $\quad \cup\ base\_lp(n, m))$   
4  $\mathcal{Z} \leftarrow [(1, 1)]$   
5 do:  
6  $\bullet \leftarrow \text{generate\_apple}(n, m, \mathcal{Z})$   
7  $\Pi \leftarrow \text{set\_external}(\Pi, \text{apple}(\bullet), \text{True})$   
8  $\Pi \leftarrow \text{set\_external}(\Pi, \text{head}(\mathcal{Z}_1), \text{True})$   
9  $\Pi, path \leftarrow \text{retrieve}(\Pi, \mathcal{Z})$   
10  $\Pi \leftarrow \text{set\_external}(\Pi, \text{apple}(\bullet), \text{False})$   
11  $\Pi \leftarrow \text{set\_external}(\Pi, \text{head}(\mathcal{Z}_1), \text{False})$   
12  $\mathcal{Z} \leftarrow \text{follow\_path}(\mathcal{Z}, path, \bullet)$   
13 while  $|\mathcal{Z}| < n \cdot m$ 
```



# Workflow - Multi-shot




**Input:** grid dimension  $n \times m$

```
1  $\Pi \leftarrow \text{ground}(\{\#external\ apple(X) : \text{field}(X).$   
2  $\quad \#external\ head(X) : \text{field}(X).\}$   
3  $\quad \cup\ base\_lp(n, m))$   
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5 do:  
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8  $\Pi \leftarrow \text{set\_external}(\Pi, \text{head}(\mathcal{Z}_1), \text{True})$   
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10  $\Pi \leftarrow \text{set\_external}(\Pi, \text{apple}(\bullet), \text{False})$   
11  $\Pi \leftarrow \text{set\_external}(\Pi, \text{head}(\mathcal{Z}_1), \text{False})$   
12  $\mathcal{Z} \leftarrow \text{follow\_path}(\mathcal{Z}, path, \bullet)$   
13 while  $|\mathcal{Z}| < n \cdot m$ 
```



# Implementation

 oneshot

 ad hoc

 preground

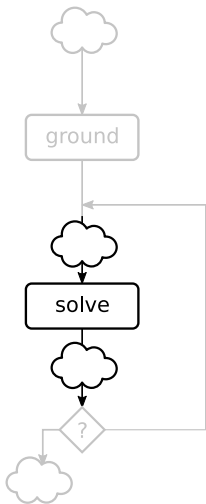
 assume

 nogoods

} multi-shot



# Workflow - Ad hoc $\pm$



---

**Algorithm 1:** *retrieve* for ad hoc; Input:  $\Pi, \mathcal{Z}$ ; Output:  $\Pi, path$

---

- 1  $\Pi \leftarrow \Pi \cup ground(\{\#external\ step(|\mathcal{Z}|). \})$
  - 2 **for**  $i = 1 .. |\mathcal{Z}| - 1$ :
  - 3 |  $\Pi \leftarrow \Pi \cup ground(\{:-\ step(|\mathcal{Z}|),\ not\ next(\mathcal{Z}_i, \mathcal{Z}_{i+1}). \})$
  - 4  $\Pi \leftarrow set\_external(\Pi, step(|\mathcal{Z}|), True)$
  - 5  $model \leftarrow solve(\Pi)$
  - 6  $\Pi \leftarrow release\_external(\Pi, step(|\mathcal{Z}|))$
  - 7  $\Pi \leftarrow cleanup(\Pi)$
  - 8 **return**  $\Pi, extract\_path(model)$
- 






# Workflow - Ad hoc $\pm$

- full flexibility, introduce new atoms
- easy implementation vs. code reusing
- applied standard in current publications

# Implementation

 oneshot

 ad hoc

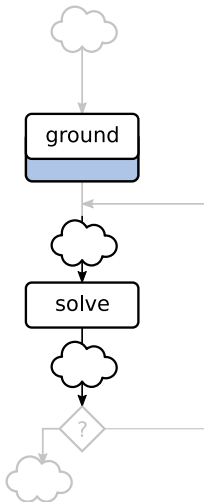
 preground

 assume

 nogoods

} multi-shot

# Workflow - Preground



logic program extension:

```
#external prenext(X,Y) : connected(X,Y).
```

```
:- prenext(X,Y), not next(X,Y), connected(X,Y).
```

---

**Algorithm 2:** *retrieve* for preground; Input:  $\Pi$ ,  $\mathcal{Z}$ ; Output:  $\Pi$ , *path*

---

- 1 for  $i = 1..|\mathcal{Z}| - 1$ :
  - 2 |  $\Pi \leftarrow \text{set\_external}(\Pi, \text{prenext}(\mathcal{Z}_i, \mathcal{Z}_{i+1}), \text{True})$
  - 3  $\text{model} \leftarrow \text{solve}(\Pi)$
  - 4 for  $i = 1..|\mathcal{Z}| - 1$ :
  - 5 |  $\Pi \leftarrow \text{set\_external}(\Pi, \text{prenext}(\mathcal{Z}_i, \mathcal{Z}_{i+1}), \text{False})$
  - 6 return  $\Pi, \text{extract\_path}(\text{model})$
-

# Workflow - Preground

- easy interface
- complex expressions possible
- for a compact extensions
- least flexible

# Implementation

 oneshot

 ad hoc

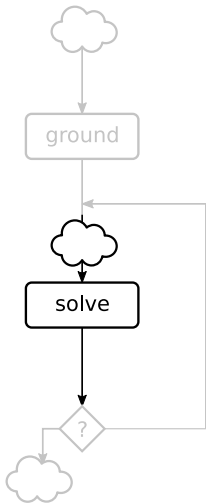
 preground

 assume

 nogoods

} multi-shot

# Workflow - Assume



---

**Algorithm 3:** retrieve for assume; Input:  $\Pi, \mathcal{A}$ ; Output:  $\Pi, path$

---

- 1  $assume \leftarrow []$
  - 2 **for**  $i = 1..|\mathcal{A}| - 1$ :
  - 3      $assume.append((next(\mathcal{A}_i, \mathcal{A}_{i+1}), True))$
  - 4  $model \leftarrow solve(\Pi, assumption = assume)$
  - 5 **return**  $\Pi, extract\_path(model)$
- 



# Workflow - Assume

- manipulate any atom
- no reset required
- logic program stays untouched
- least expressivity
- no interface identifiers

# Implementation

 oneshot

 ad hoc

 preground

 assume

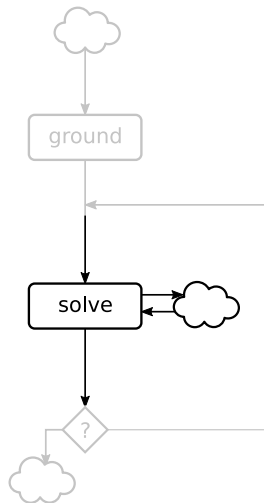
 nogoods

} multi-shot





# Workflow - Nogoods



---

**Algorithm 4:** code snipped to add  $\mathcal{Z}$  as search restriction

---

**Input:** model *model*

```
1 ...
2 if dummy ∈ model:
3   |   for  $i = 1..|\mathcal{Z}| - 1$ :
4   |   |   model.context.add_clause(next( $\mathcal{Z}_i, \mathcal{Z}_{i+1}$ ), True)
5   |   ...
```

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# Workflow - Nogoods

- manipulate any clause
- logic program stays untouched
- no interface identifiers
- complex access
- initial model problem

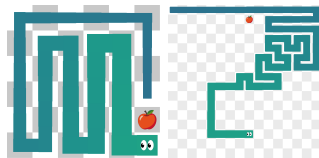
# Attribute summary

- prototyping/debugging: oneshot
- resource optimization: multi-shot

	ad hoc	preground	assume	nogood
flexibility	introduce rules	predefined	predefined	predefined
expressivity	rules	constraints	atoms	clauses
program alternation	every iteration	once	none/once	none
interface	NA	good	depends	depends
accessibility	good	good	good	hidden

# Experiments - Setup

- 6 different square grid sizes ( $n = m, n \in \{6, 8, 10, 12, 14, 16\}$ )
- 100 repetitions per grid size and approach
- 60s timeout for solve per iteration
- average number of steps, average total time
- MacBook Pro (2017, 16 GB RAM, Intel Core i7, 2.8 GHz)
- clingo v. 5.4.0, python v. 3.7.4
- ASP-Chef for prototyping, clingraph for graphics
- [github.com/elbo4u/asp-snake-ms](https://github.com/elbo4u/asp-snake-ms)



# Experiments - Evaluation

average total Time (grounding and solving) in seconds

$n \times m$	$6 \times 6$	$8 \times 8$	$10 \times 10$	$12 \times 12$	$14 \times 14$	$16 \times 16$
one-shot	0.159	<b>2.28</b>	<b>71.83</b>	621	2216	4359
ad hoc	0.066	3.42	90.07	674	1966	3869
time preground	0.060	3.32	94.71	<b>620</b>	1978	3870
assume	<b>0.059</b>	4.78	97.48	628	<b>1944</b>	<b>3853</b>
nogood	0.061	3.16	94.70	702	1951	3877



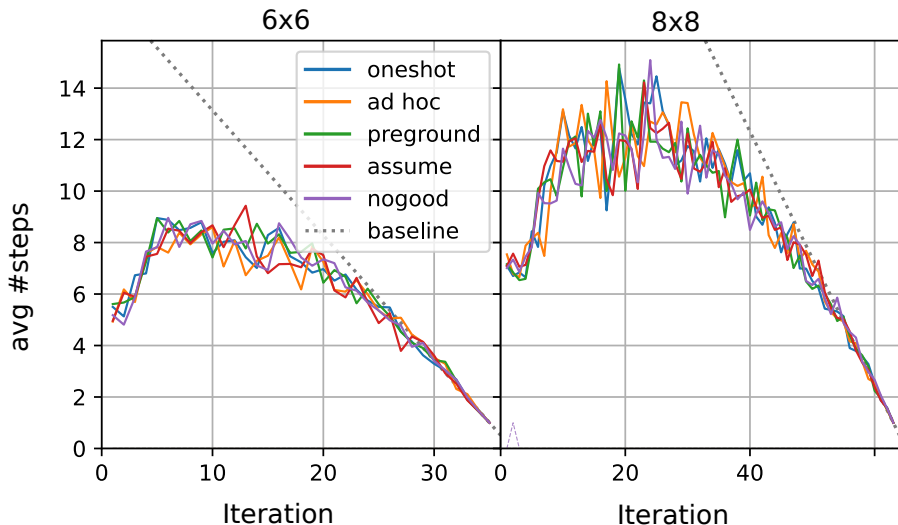
# Experiments - Evaluation

average total Time (grounding and solving) in seconds

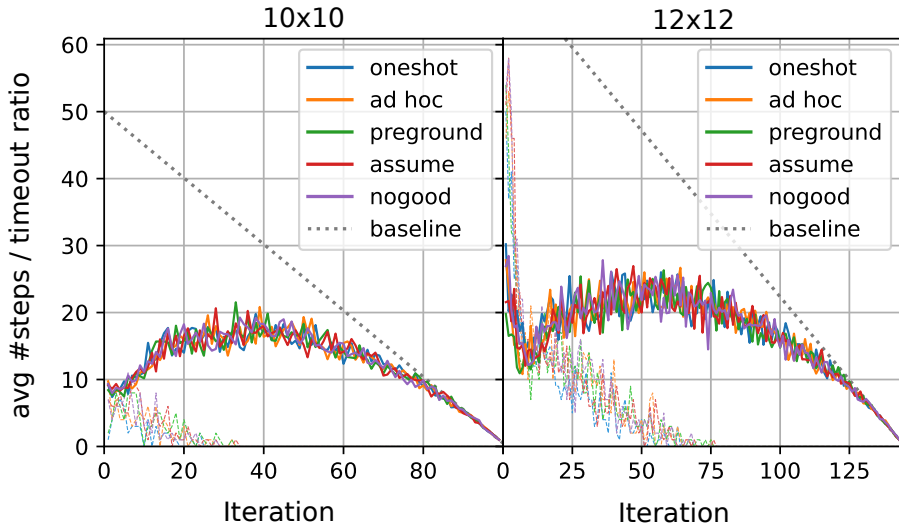
$n \times m$	$6 \times 6$	$8 \times 8$	$10 \times 10$	$12 \times 12$	$14 \times 14$	$16 \times 16$	
time	one-shot	0.159	<b>2.28</b>	<b>71.83</b>	621	2216	4359
	ad hoc	0.066	3.42	90.07	674	1966	3869
	preground	0.060	3.32	94.71	<b>620</b>	1978	3870
	assume	<b>0.059</b>	4.78	97.48	628	<b>1944</b>	<b>3853</b>
	nogood	0.061	3.16	94.70	702	1951	3877
steps	one-shot	213	576	1235	2441	<u>5519</u>	<u>10157</u>
	ad hoc	208	572	1226	2411	4582	7445
	preground	216	563	1236	2374	4540	7482
	assume	210	563	1234	2396	4508	7540
	nogood	212	559	1240	2428	4580	7523



# Experiments - Evaluation - Steps



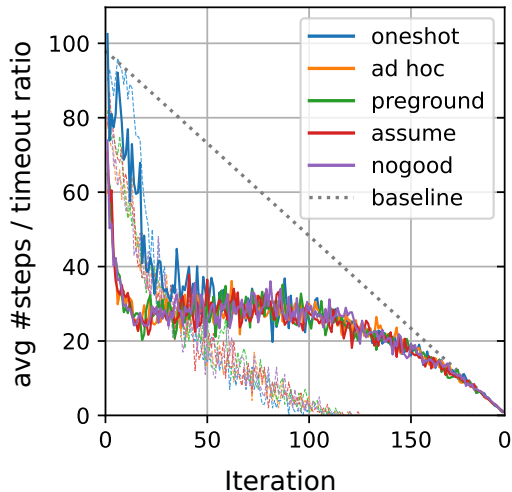
# Experiments - Evaluation - Steps



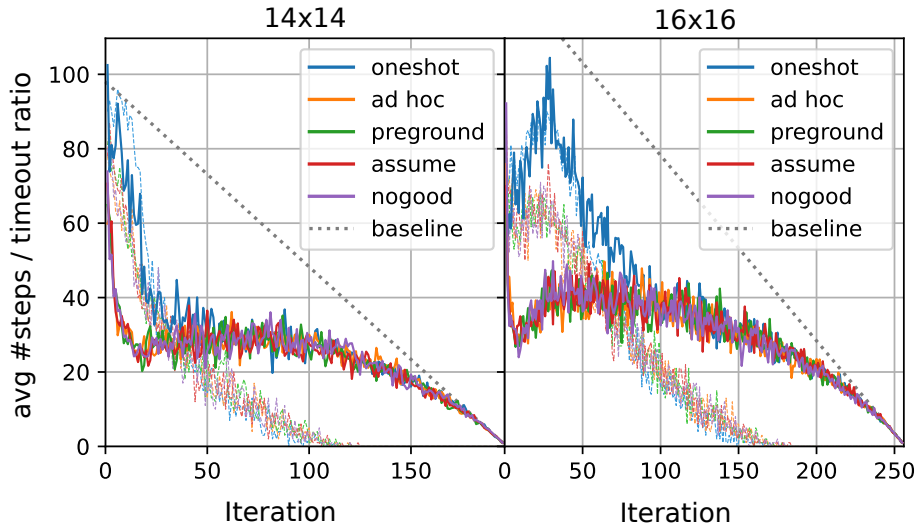


# Experiments - Evaluation - Steps

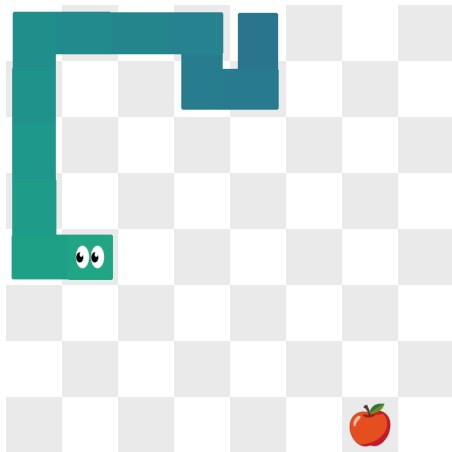
14x14



# Experiments - Evaluation - Steps

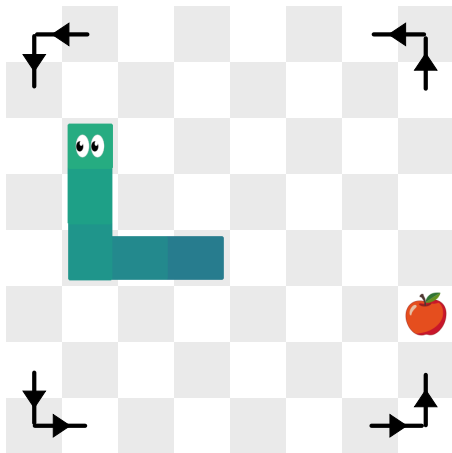


# Experiments - Evaluation - Nogoods

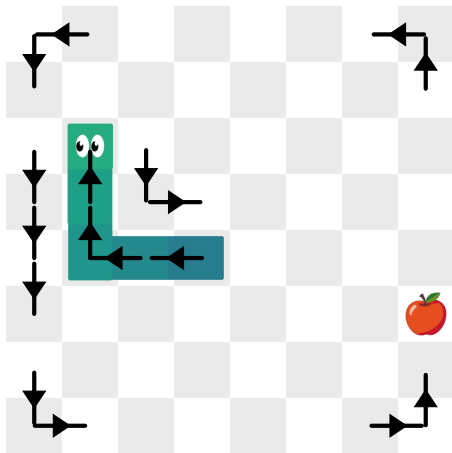




# Experiments - Evaluation - Nogoods



# Experiments - Evaluation - Nogoods



# Conclusion and Future Work

## Conclusion

- Different approaches to implement multi-shot in `clingo`
- Snakes as suited showcase benchmark
- Multi-shot as reasonable technique for limited resources

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- More sophisticated strategies
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